

Assembly and Operating Manual

JGP-P

2-finger parallel gripper

Translation of Original Operating
Manual

Hand in hand for tomorrow

Imprint

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Technical changes:

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Dear Customer,

Thank you for trusting our products and our family-owned company, the leading technology supplier of robots and production machines.

Our team is always available to answer any questions on this product and other solutions. Ask us questions and challenge us. We will find a solution!

Best regards,

Your SCHUNK team

Customer Management

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Please read the operating manual in full and keep it close to the product.

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1 General

1.1 About this manual

This manual contains important information for a safe and appropriate use of the product.

This manual is an integral part of the product and must be kept accessible for the personnel at all times.

Before starting work, the personnel must have read and understood this operating manual. Prerequisite for safe working is the observance of all safety instructions in this manual.

In addition to these instructions, the documents listed under ▶ 1.1.2 [6] are applicable.

NOTE: The illustrations in this manual are intended to provide a basic understanding and may deviate from the actual version.

1.1.1 Presentation of Warning Labels

To make risks clear, the following signal words and symbols are used for safety notes.



⚠ DANGER

Dangers for persons!

Non-observance will inevitably cause irreversible injury or death.



⚠ WARNING

Dangers for persons!

Non-observance can lead to irreversible injury and even death.



⚠ CAUTION

Dangers for persons!

Non-observance can cause minor injuries.

CAUTION

Material damage!

Information about avoiding material damage.

1.1.2 Applicable documents

- General terms of business *
- Catalog data sheet of the purchased product *
- Assembly and operating manuals of the accessories *

The documents labeled with an asterisk (*) can be downloaded from [schunk.com/downloads](https://www.schunk.com/downloads).

1.1.3 Sizes

This operating manual applies to the following sizes:

- JGP-P 40
- JGP-P 50
- JGP-P 64
- JGP-P 80
- JGP-P 100
- JGP-P 125
- JGP-P 160
- JGP-P 200
- JGP-P 240
- JGP-P 300

1.1.4 Variants

This operating manual applies to the following variations:

- JGP-P stroke 1
- JGP-P stroke 2
- JGP-P with gripping force maintenance "O.D. gripping" (AS)
- JGP-P with gripping force maintenance "I.D. gripping" (IS)

1.2 Warranty

If the product is used as intended, the warranty is valid for 24 months from the ex-works delivery date under the following conditions:

- Observe the ambient conditions and operating conditions, ▶ 2.5 [📄 11]
- Observe the specified maintenance intervals, ▶ 7 [📄 51]

Parts touching the workpiece and wear parts are not included in the warranty.

Size	Warranty duration [months]	or maximum cycles [mil.]*
40	24	20
50	24	15
64	24	15
80	24	15
100	24	15
125	24	15
160	24	15
200	24	10
240	24	10
300	24	5

* A cycle consists of a complete gripping process: "Open gripper" and "Close gripper".

1.3 Scope of delivery

The scope of delivery includes

- 2-finger parallel gripper JGP-P in the version ordered
- Safety information (product-specific instructions available online)
- Accessory pack

Content of the accessory pack:

- 2x centering sleeve for gripper fastening
- 4x centering sleeve for finger fastening
- 2 x O-ring for hose-free direct connection

ID.-No. of the accessory pack

Size	ID number
40	5518410
50	5512043
64	5512044
80	5512045
100	5512046
125	5512047
160	5512048
200	5512049
240	5513858
300	5512050

Tab.: ID.-No. of the accessory pack

1.4 Accessories

A wide range of accessories are available for this product
For information regarding which accessory articles can be used with the corresponding product variants, see catalog data sheet.

1.4.1 Spare parts packages

Spare parts packages allow for the maintenance and repair of individual components. For information on the range of the spare parts packages, see www.schunk.com > Service.

The following spare parts packages are available for this product:

- Spare part package "Sealing kit"

Size	ID number
40	1325991
50	1326003
64	1326011
80	1326019
100	1326027
125	1326031
160	1326040
200	1326045
200-AS	1477531
200-IS	1489746
240	1326048
240-AS	1489780
240-IS	1489781
300	1479146

Tab.: ID. No. spare part kit "Sealing kit"

2 Basic safety notes

2.1 Intended use

The product is designed exclusively for gripping and temporarily holding workpieces or objects.

- The product may only be used within the scope of its technical data, ▶ 3 [18].
- The product is intended for installation in a machine/ automated system. The applicable guidelines for the machine/ automated system must be observed and complied with.
- The product is intended for industrial and industry-oriented use. Its use outside enclosed spaces is only permitted if suitable protective measures are taken against outdoor exposure. The product is not suitable for use in salty air.
- The product can be used within the permissible load limits and technical data for holding workpieces during simple machining operations, but is not a clamping device according to EN 1550:1997+A1:2008.
- Appropriate use of the product includes compliance with all instructions in this manual.
- Any utilization that exceeds or differs from the appropriate use is regarded as misuse.

2.2 Constructional changes

Implementation of structural changes

Modifications, changes or reworking, e.g. additional threads, holes, or safety devices, can damage the product or impair its functionality or safety.

- Structural changes should only be made with the written approval of SCHUNK.

2.3 Spare parts

Use of unauthorized spare parts

Using unauthorized spare parts can endanger personnel and damage the product or cause it to malfunction.

- Use only original spare parts or spares authorized by SCHUNK.

2.4 Gripper fingers

Requirements of gripper fingers

Accumulated energy can make the product unsafe and risk the danger of serious injuries and considerable material damage.

- Execute the gripper fingers in such a way that the product reaches either the "open" or "closed" position in a de-energized state.
- Only change gripper fingers if no residual energy can be released.
- Make sure that the product and the top jaws are a sufficient size for the application.

2.5 Ambient conditions and operating conditions

Required ambient conditions and operating conditions

Incorrect ambient and operating conditions can make the product unsafe, leading to the risk of serious injuries, considerable material damage and/or a significant reduction to the product's life span.

- Make sure that the product is used only in the context of its defined application parameters, ▶ 3 [📄 18].

2.6 Personnel qualification

Inadequate qualifications of the personnel

If the personnel working with the product is not sufficiently qualified, the result may be serious injuries and significant property damage.

- All work may only be performed by qualified personnel.
- Before working with the product, the personnel must have read and understood the complete assembly and operating manual.
- Observe the national safety regulations and rules and general safety instructions.

The following personal qualifications are necessary for the various activities related to the product:

Trained electrician

Due to their technical training, knowledge and experience, trained electricians are able to work on electrical systems, recognize and avoid possible dangers and know the relevant standards and regulations.

Qualified personnel

Due to its technical training, knowledge and experience, qualified personnel is able to perform the delegated tasks, recognize and avoid possible dangers and knows the relevant standards and regulations.

Instructed person

Instructed persons were instructed by the operator about the delegated tasks and possible dangers due to improper behaviour.

Service personnel of the manufacturer Due to its technical training, knowledge and experience, service personnel of the manufacturer is able to perform the delegated tasks and to recognize and avoid possible dangers.

2.7 Personal protective equipment

Use of personal protective equipment

Personal protective equipment serves to protect staff against danger which may interfere with their health or safety at work.

- When working on and with the product, observe the occupational health and safety regulations and wear the required personal protective equipment.
- Observe the valid safety and accident prevention regulations.
- Wear protective gloves to guard against sharp edges and corners or rough surfaces.
- Wear heat-resistant protective gloves when handling hot surfaces.
- Wear protective gloves and safety goggles when handling hazardous substances.
- Wear close-fitting protective clothing and also wear long hair in a hairnet when dealing with moving components.

2.8 Notes on safe operation

Incorrect handling of the personnel

Incorrect handling and assembly may impair the product's safety and cause serious injuries and considerable material damage.

- Avoid any manner of working that may interfere with the function and operational safety of the product.
- Use the product as intended.
- Observe the safety notes and assembly instructions.
- Do not expose the product to any corrosive media. This does not apply to products that are designed for special environments.
- Eliminate any malfunction immediately.
- Observe the care and maintenance instructions.
- Observe the current safety, accident prevention and environmental protection regulations regarding the product's application field.

2.9 Transport

Handling during transport

Incorrect handling during transport may impair the product's safety and cause serious injuries and considerable material damage.

- When handling heavy weights, use lifting equipment to lift the product and transport it by appropriate means.
- Secure the product against falling during transportation and handling.
- Stand clear of suspended loads.

2.10 Malfunctions

Behavior in case of malfunctions

- Immediately remove the product from operation and report the malfunction to the responsible departments/persons.
- Order appropriately trained personnel to rectify the malfunction.
- Do not recommission the product until the malfunction has been rectified.
- Test the product after a malfunction to establish whether it still functions properly and no increased risks have arisen.

2.11 Disposal

Handling of disposal

The incorrect handling of disposal may impair the product's safety and cause serious injuries as well as considerable material and environmental harm.

- Follow local regulations on dispatching product components for recycling or proper disposal.

2.12 Fundamental dangers

General

- Observe safety distances.
- Never deactivate safety devices.
- Before commissioning the product, take appropriate protective measures to secure the danger zone.
- Disconnect power sources before installation, modification, maintenance, or calibration. Ensure that no residual energy remains in the system.
- If the energy supply is connected, do not move any parts by hand.
- Do not reach into the open mechanism or movement area of the product during operation.

2.12.1 Protection during handling and assembly

Incorrect handling and assembly

Incorrect handling and assembly may impair the product's safety and cause serious injuries and considerable material damage.

- Have all work carried out by appropriately qualified personnel.
- For all work, secure the product against accidental operation.
- Observe the relevant accident prevention rules.
- Use suitable assembly and transport equipment and take precautions to prevent jamming and crushing.

Incorrect lifting of loads

Falling loads may cause serious injuries and even death.

- Stand clear of suspended loads and do not step into their swiveling range.
- Never move loads without supervision.
- Do not leave suspended loads unattended.

2.12.2 Protection during commissioning and operation

Falling or violently ejected components

Falling and violently ejected components can cause serious injuries and even death.

- Take appropriate protective measures to secure the danger zone.
- Never step into the danger zone during operation.

2.12.3 Protection against dangerous movements

Unexpected movements

Residual energy in the system may cause serious injuries while working with the product.

- Switch off the energy supply, ensure that no residual energy remains and secure against inadvertent reactivation.
- Never rely solely on the response of the monitoring function to avert danger. Until the installed monitors become effective, it must be assumed that the drive movement is faulty, with its action being dependent on the control unit and the current operating condition of the drive. Perform maintenance work, modifications, and attachments outside the danger zone defined by the movement range.
- To avoid accidents and/or material damage, human access to the movement range of the machine must be restricted. Limit/prevent accidental access for people in this area due through technical safety measures. The protective cover and protective

fence must be rigid enough to withstand the maximum possible movement energy. EMERGENCY STOP switches must be easily and quickly accessible. Before starting up the machine or automated system, check that the EMERGENCY STOP system is working. Prevent operation of the machine if this protective equipment does not function correctly.

2.12.4 Protection against electric shock

Possible electrostatic energy

Components or assembly groups may become electrostatically charged. When the electrostatic charge is touched, the discharge may trigger a shock reaction leading to injuries.

- The operator must ensure that all components and assembly groups are included in the local potential equalisation in accordance with the applicable regulations.
- While paying attention to the actual conditions of the working environment, the potential equalisation must be implemented by a specialist electrician according to the applicable regulations.
- The effectiveness of the potential equalisation must be verified by executing regular safety measurements.

2.13 Notes on particular risks



⚠ DANGER

Risk of fatal injury from suspended loads!

Falling loads can cause serious injuries and even death.

- Stand clear of suspended loads and do not step within their swiveling range.
- Never move loads without supervision.
- Do not leave suspended loads unattended.
- Wear suitable protective equipment.



⚠ WARNING

Risk of injury from objects falling and being ejected!

Falling and ejected objects during operation can lead to serious injury or death.

- Take appropriate protective measures to secure the danger zone.



⚠ WARNING

Risk of injury due to unexpected movements!

If the power supply is switched on or residual energy remains in the system, components can move unexpectedly and cause serious injuries.

- Before starting any work on the product: Switch off the power supply and secure against restarting.
- Make sure, that no residual energy remains in the system.



⚠ WARNING

Risk of injury from crushing and impacts!

Serious injury could occur during movement of the base jaw, due to breakage or loosening of the gripper fingers or if the workpiece is lost.

- Wear suitable protective equipment.
- Do not reach into the open mechanism or the movement area of the product.

**⚠ WARNING****Risk of injury due to electromagnetic interference!**

Electromagnetic interference can cause the product to malfunction and lead to disturbances in medical implants (e.g. pacemakers). Unexpected movements or ejected objects can cause serious injury or death.

- Ensure adequate shielding against magnetic fields in the immediate vicinity of the product, so that exact limits according to relevant standards, e.g. EN IEC 61000, are not exceeded.
 - Take suitable protective measures to secure the danger zone.
-

3 Technical data

Connection data

Pressure medium	Compressed air, compressed air quality according to ISO 8573-1:2010 [7:4:4]
Nominal operating pressure [bar]	6
Minimum pressure [bar] without maintenance of gripping force	2.5
Minimum pressure [bar] with maintenance of gripping force	4
Maximum pressure [bar] without maintenance of gripping force	8
Maximum pressure [bar] with maintenance of gripping force	6.5
Pressure range for air purge [bar]	0.5 – 1

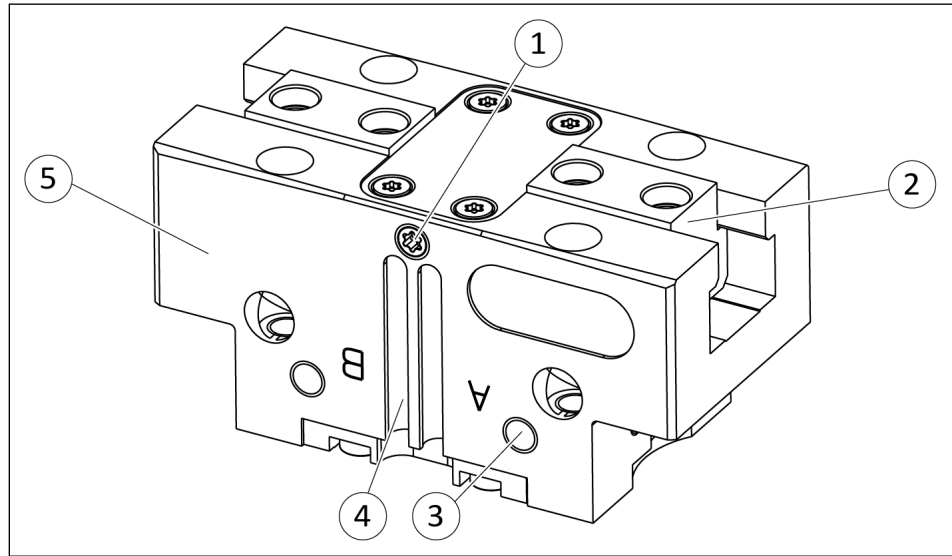
Ambient conditions and operating conditions

Ambient temperature [°C]	
min.	+5
max.	+90
Protection class IP	40
Noise emission [dB(A)]	≤ 70

More technical data is included in the catalog data sheet. Whichever is the latest version.

4 Design and description

4.1 Design



2-finger parallel gripper

- | | |
|---|--------------------------------|
| 1 | Air purge connection |
| 2 | Base jaw |
| 3 | Compressed air main connection |
| 4 | Groove for magnetic switch |
| 5 | Housing |

4.2 Description

Universal 2-finger parallel gripper with a high gripping force and high maximum moments due to the use of a T-slot guidance.

5 Assembly and settings

5.1 Installing and connecting



⚠ WARNING

Risk of injury due to unexpected movements!

If the power supply is switched on or residual energy remains in the system, components can move unexpectedly and cause serious injuries.

- Before starting any work on the product: Switch off the power supply and secure against restarting.
- Make sure, that no residual energy remains in the system.

CAUTION

Damage to the gripper is possible!

If the maximum permissible finger weight or the permissible mass moment of inertia of the fingers is exceeded, the gripper can be damaged.

- A jaw movement always has to be without jerks and bounce.
- You must therefore implement sufficient reduction and/or damping.
- Observe the information in the catalog data sheet.

1. Check the evenness of the mounting surface, ▶ 5.2.1 [📄 21].
2. Connect the product via the hose-free direct connection.
3. OR: Connect compressed air lines to the main air connections "A" and "B".
 - ⇒ Remove the locking screws.
 - ⇒ Screw in air connections (plug connections).
OR: Screw on throttle valve in order to be able to perform sufficient throttling and/or damping.
4. Screw the product to the machine/system, ▶ 5.2.1 [📄 21].
 - ⇒ If necessary, use appropriate connection elements (adapter plates).
 - ⇒ Observe permissible depth of engagement and if required strength class.
5. Connect air purge connection if necessary.
6. Attach additional structure to the product if necessary, ▶ 5.3 [📄 26]
7. Connect the sensor, see assembly and operating manual of the sensor.
8. Mount the sensor, ▶ 5.4 [📄 28].

5.2 Connections

5.2.1 Mechanical connection

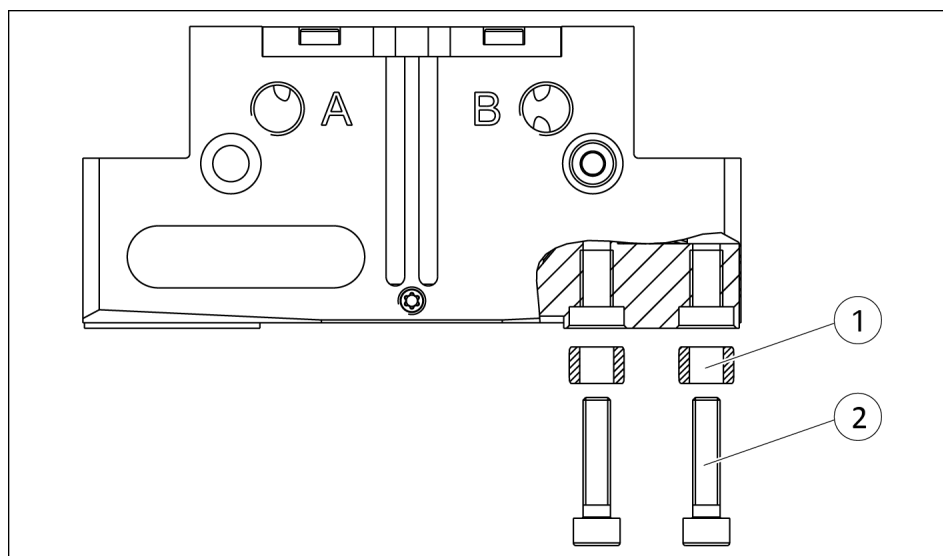
Evenness of the mounting surface

The values apply to the whole mounting surface to which the product is mounted.

Edge length	Permissible unevenness
< 100	< 0.02
> 100	< 0.05

Tab.: Requirements for evenness of the mounting surface (Dimensions in mm)

Connections at the base jaws



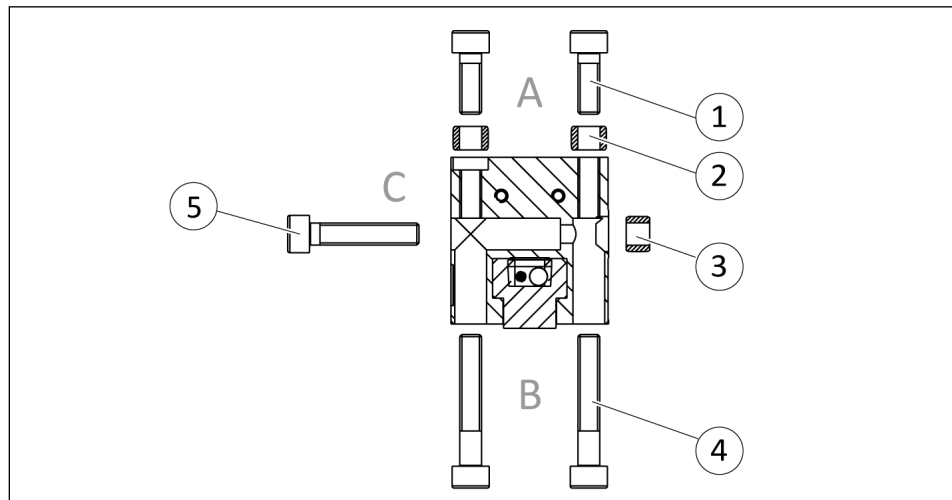
Connections at the base jaws

Size	① Centering sleeve	② Screws *
40	∅ 4	M2.5 / 6.1
50	∅ 5	M3 / 8.5
64	∅ 6	M4 / 10.7
80	∅ 8	M5 / 11.9
100	∅10	M6 / 14.2
125	∅10	M6 / 14.2
160	∅14	M10 / 17
200	∅16	M12 / 19.3
240	∅16	M12 / 21.1
300	∅22	M16 / 27.9

* Thread / max. depth of engagement from locating surface [mm], max. strength class 12.9

Connections at the housing

The product can be mounted from three sides.



Connections at the housing

Side A	Size	① Screws *	② Centering sleeve
	40	M3 / 6	Ø5
	50	M4 / 11	Ø6
	64	M5 / 12	Ø8
	80	M5 / 15	Ø8
	100	M6 / 14	M5
	125	M8 / 20	Ø12
	160	M8 / 20.5	Ø12
	160-AS/IS	M8 / 20	Ø12
	200	M10 / 20	Ø14
	240	M12 / 25.5	Ø16
	240-AS/IS	M12 / 25	Ø16
	300	M16 / 31	Ø22

* Thread / max. depth of engagement from locating surface [mm]

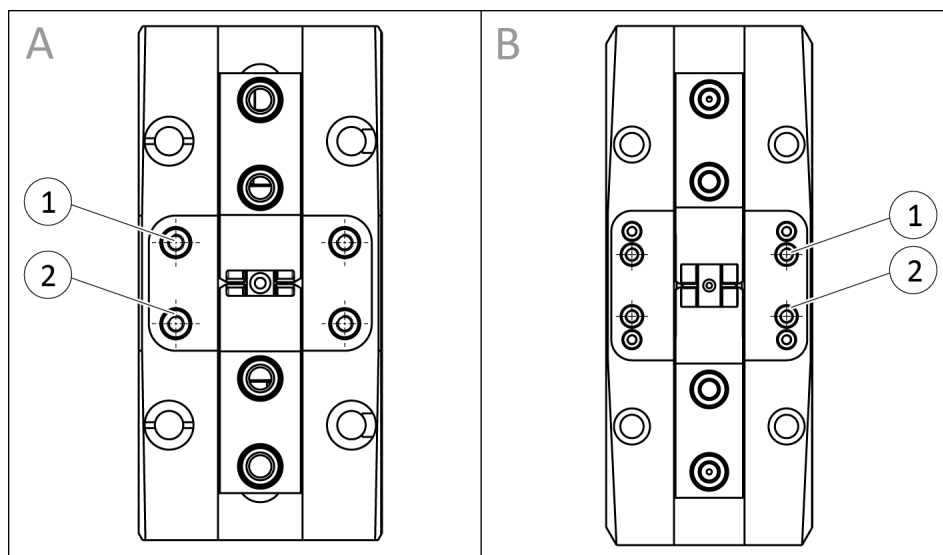
Seite B	Size	④ Screws *	② Centering sleeve
	40	M2.5	Ø5
	50	M3	Ø6
	64	M4	Ø8
	80	M4	Ø8
	100	M5	Ø10
	125	M6	Ø12
	160	M6	Ø12
	200	M8	Ø12
	240	M10	Ø16
	300	M12	Ø22

* DIN EN 4762

Side C	Size	⑤ Screws *	③ Centering sleeve
	40	M2.5	∅5
	50	M3	∅6
	64	M4	∅8
	80	M5	∅8
	100	M6	∅10
	125	M8	∅12
	160	M8	∅12
	200	M10	∅14
	240	M12	∅16
	300	M16	∅22

* DIN EN 4762, max. strength class 8.8

Connections for additional structure



Connections at the housing, Sizes: A - to 100, B - from 125

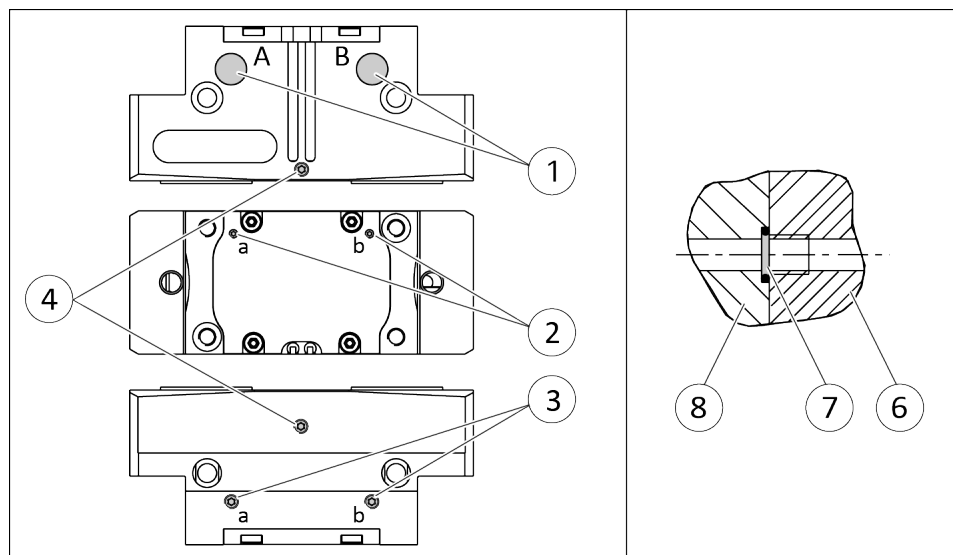
Size	① Thread *	② Centering sleeve
40	M2 / 5	∅3
50	M2.5 / 7.1	∅4
64	M2.5 / 7.1	∅4
80	M2.5 / 7.1	∅4
100	M3 / 8.4	∅5
125	M4 / 10.9	∅6
160	M5 / 13	∅8
200	M6 / 12	∅10
240	M6 / 12	∅10
300	M8 / 12	∅12

* Thread / max. depth of engagement from locating surface [mm]

5.2.2 Pneumatic connection

NOTE

- Observe the requirements for the compressed air supply, ▶ 3 [18].
- In case of compressed air loss (cutting off the energy line), the components lose their dynamic effects and do not remain in a secure position. However, the use of a SDV-P pressure maintenance valve is recommended in this case in order to maintain the dynamic effect for some time. Product variants are also offered with mechanical gripping force via springs, which also ensure a minimum clamping force in the event of a pressure drop.



Air connections

1 Main connections (Hose connection)
(A = open, B = close)

2 Hose-free direct connection at the base
(a = open, b = close)

3 Hose-free direct connection

4 Air purge connection

Hose-free direct connection

6 Product

7 O-ring

8 Attachment

- Open only the air connections that are needed.
- Close unused main air connections using the screw plugs from the enclosed pack.
- For a hose-free direction connection, use the O-rings from the enclosed pack.

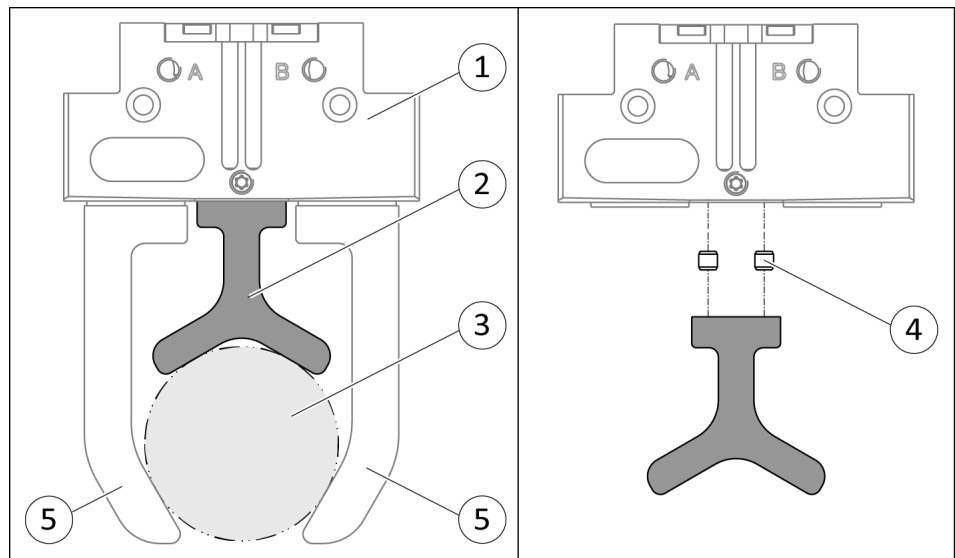
Size	Main air connections *	Air purge connection *
40	M3 / 4	M3 / 3.9
50	M5 / 5	M3 / 5
64	M5 / 6	M5 / 6
80	M5 / 6	M5 / 6
100	G1/8 / 7	M5 / 6
125	G1/8 / 7	M5 / 6
160	G1/8 / 7	M5 / 6
200	G1/8 / 7	M5 / 6
240	G1/8 / 7	M5 / 6
300	G1/4 / 12	M5 / 6

* Thread / max. depth of engagement from locating surface [mm]

Air purge connection

The air purge is used in order to make it more difficult for dirt and dust to penetrate into the product and the guiding areas.

5.3 Attaching additional structure

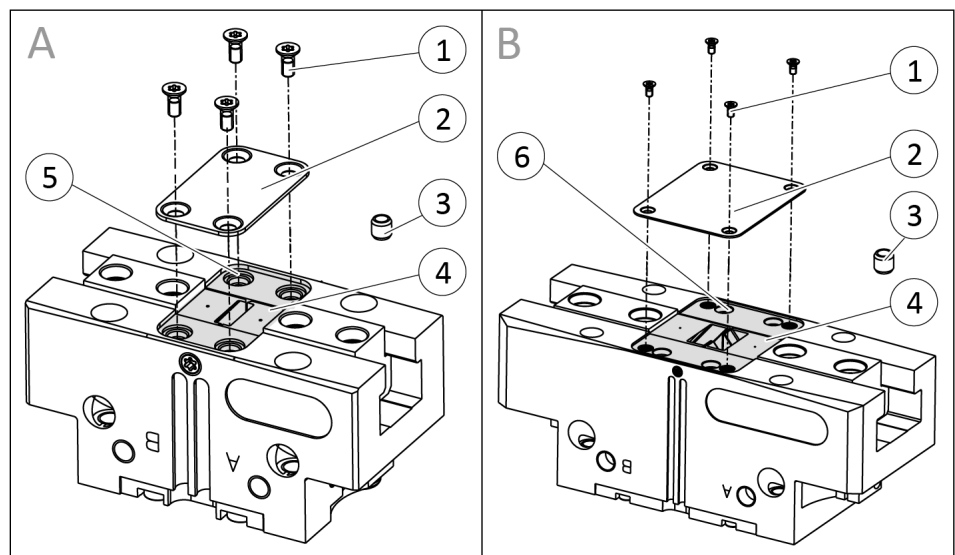


Gripper with additional structure

1	Product	4	Centering sleeve
2	Additional structure	5	Gripper finger
3	Workpiece		

For supporting things like workpieces, an additional structure can be attached to the gripper.

The locating surface of the additional structure may not exceed the recess of the cover. The external dimensions of the additional structure can exceed the external dimensions of the gripper but not interfere with the operating cycle of the gripper fingers.



Mounting surface, sizes: A - to 100, B - from 125

1. **IMPORTANT!** The size of the additional structure may not exceed the recess of the cover.
2. Remove the screws (1) from the cover (2).
3. Remove the cover (2).

4. IMPORTANT! Ensure that no foreign objects can enter the gripper.

Attach additional structure within the recess

(4), ▶ 5.2.1 [📄 21].

- ⇒ Use centering sleeves (3) between gripper and additional structure. Centering sleeves can be ordered from SCHUNK.
- ⇒ With sizes 50 – 100 the threaded holes (5) of the cover (2) are used for securing the additional structure.
- ⇒ From size 125, the additionally attached threaded holes (6) are used for securing the additional structure.

5.4 Mounting the sensor

NOTE

Observe the assembly and operating manual of the sensor for mounting and connecting.

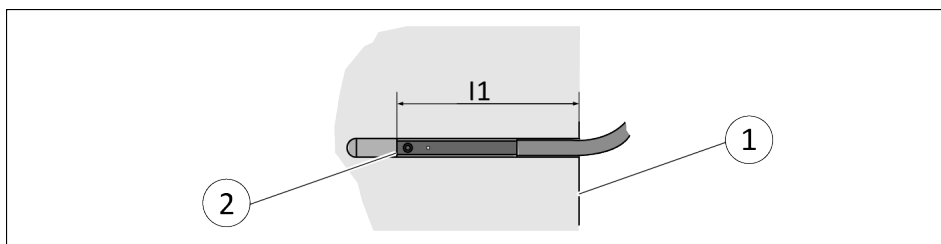
The product is prepared for the use of sensors.

- For the exact type designations of suitable sensors, please see catalog datasheet and ▶ 5.4.1 [📄 28].
- For technical data for the suitable sensors, see assembly and operating manual and catalog datasheet.
 - The assembly and operating manual and catalog datasheet are included in the scope of delivery for the sensors and are available at schunk.com.
- Information on handling sensors is available at schunk.com or from SCHUNK contact persons.

5.4.1 Overview of sensors

Size	IN 80	MMS 22	MMS 22-PI2	MMS-P 22	MMS 22-PI1	MMS 22-10L	MMS 22-A	APS-Z80	FPS	APS-M1
40	⊘	✓	✓	✓	✓	✓	✓	⊘	⊘	⊘
50	⊘	✓	✓	✓	✓	✓	✓	⊘	⊘	⊘
64	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
80	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
100	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
125	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
160	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
200	✓	✓	✓	✓	✓	⊘	✓	✓	✓	✓
240	✓	✓	⊘	⊘	✓	⊘	⊘	✓	✓	✓
300	✓	✓	⊘	⊘	✓	⊘	⊘	✓	⊘	✓

5.4.2 Setting dimensions for magnetic switches



* Setting dimension l_1 , from product bottom edge (1) to front sensor (2)

The setting dimension applies for the following sensors:

- Programmable magnetic switch MMS 22-PI2
- Programmable magnetic switch MMS-P 22
- Programmable magnetic switch MMS 22-PI1
- Analog magnetic switch MMS 22-A

Size	l_1^* [mm]
40	11.9
40 AS	11.9
40 IS	21.9
50	22
50 AS	22
50 IS	38
64	17.8
64 AS	17.8
64 IS	35.8
80	25.8
80 AS	25.8
80 IS	43.8
100	27
100 AS	27
100 IS	53
125	30
125 AS	30
125 IS	60
160	38
160 AS	33.5
160 IS	78.5
200	40.5
200 AS	34
200 IS	92.2

Tab.: Setting dimensions

NOTE

The magnetic switch MMS 22-P11 can be adjusted and taught in two ways.

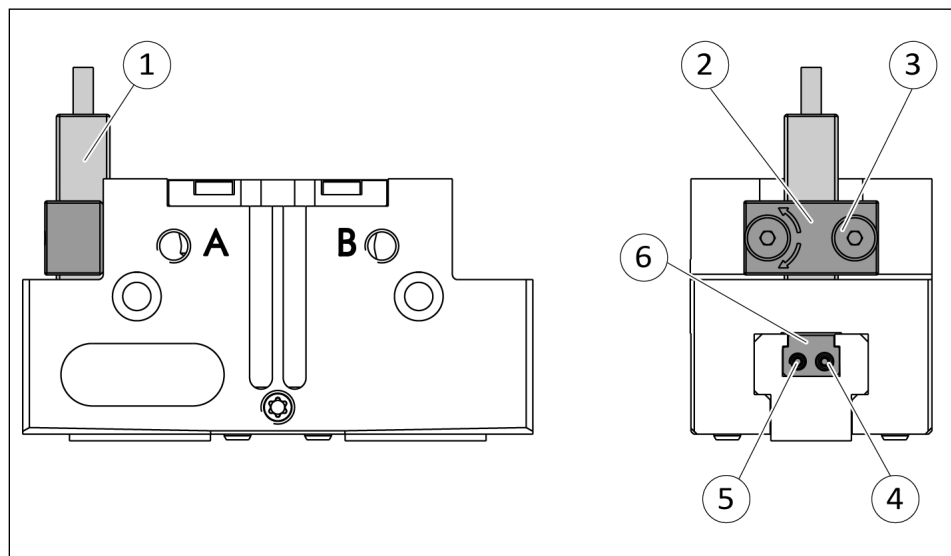
- "Standard mode" allows for quick installation on the T-nut preset by SCHUNK in the groove or the defined setting dimension "l1."
 - In "Optimal Mode", the sensor identifies the optimal position in the groove itself.
SCHUNK recommends "Optimal Mode" for setting the sensors.
-

Further information on the installation of the sensor, ▶ [5.4.7](#) [[📄 36](#)]

5.4.3 Mounting inductive proximity switch IN

NOTE

The sensor cannot be used for sizes smaller than size 64.



Position "Gripper open" or "Gripper closed"

1. Slide the sensor 1 (1) through the bracket (2) and into the housing until it stops.
2. Tighten the screw (3) on the bracket (2).
Tightening torque: 0.2 Nm
3. Bring product into the "open" or "closed" position and test the function.

Position "Part gripped (O.D. gripping)" or "Part gripped (I.D. gripping)"

1. Slide the sensor 1 (1) through the bracket (2) and into the housing until it stops.
2. Tighten the screw (3) on the bracket (2).
Tightening torque: 0.2 Nm
3. Clamp the part to be gripped.
4. Loosen expander bolt (4) by unscrewing it from the control cam (6).
5. Turn adjustable spindle (5) in order to adjust the position of the control cam (6).
 - ⇒ **Part gripped (O.D. gripping):**
Slide control cam (6) outwards until the sensor (1) no longer responds.
 - ⇒ Move the control cam (6) back towards the inside until the sensor (1) begins to switch.

- ⇒ **Part gripped (I.D. gripping):**
Slide control cam (6) inwards until the sensor (1) no longer responds.
 - ⇒ Move the control cam (6) back towards the outside until the sensor (1) begins to switch.
6. Screw the expander bolt (4) back in to fix the switching point.
For tightening torque see following table
 7. Open the product and close it again in order to test its function.

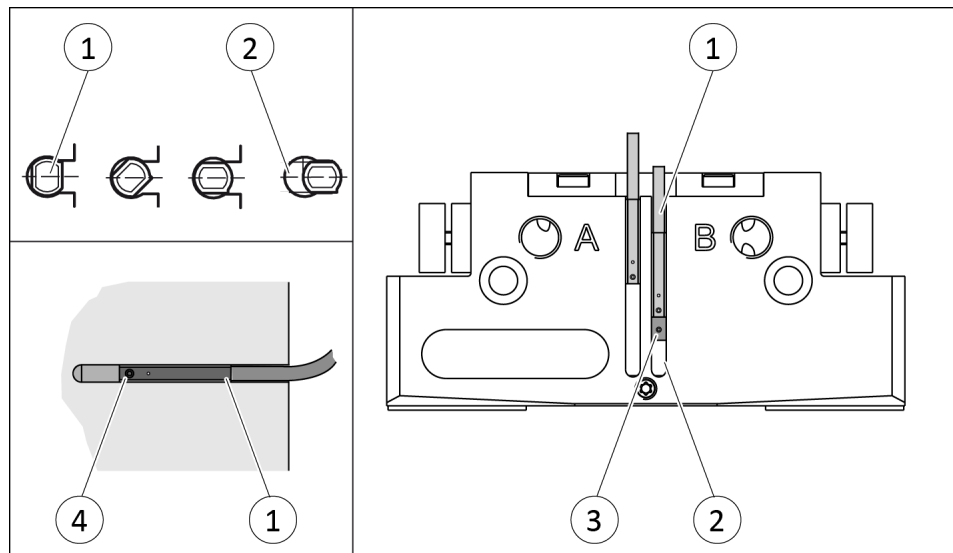
Size	④ Max. tightening torque [Nm]	⑤ Max. Verstellmoment [Nm]
64	0.2	0.2
80	0.2	0.2
100	0.3	0.3
125	0.3	0.3
160	0.4	0.4
200	0.4	0.4
240	0.4	0.4
300	0.4	0.4

5.4.4 Mounting MMS 22 magnetic switch

CAUTION

Risk of damage to the sensor during assembly!

- Observe the maximal tightening torque.



Position "Gripper open" or "Part gripped (I.D. gripping)"

1. Bring product in the position to be set.
2. If necessary remove T-nut (3).
3. Turn the sensor 1 (1) into the groove (2).
OR: Slide the sensor 1 (1) into the groove (2) until the sensor 1 (1) stops at the end of the groove.
4. Pull the sensor 1 (1) back again slowly until it switches.
5. Secure the sensor 1 (1) using the set-screw (4).
Tightening torque: 10 Ncm
6. Bring product into the "Gripper open" or "Part gripped" position and test the function.

Position "Gripper closed" or "Part gripped (O.D. gripping)"

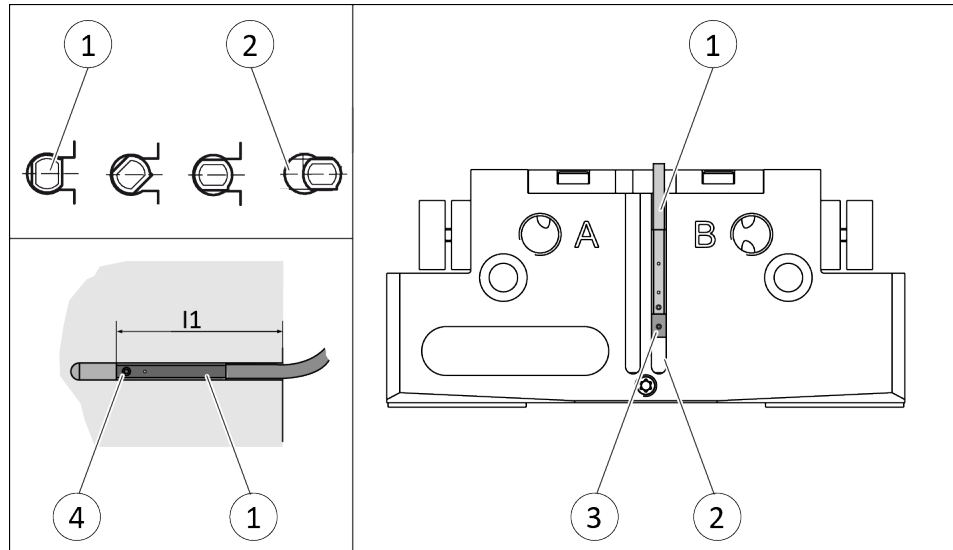
1. Bring product in the position in which it is to be set.
2. If necessary remove T-nut (3).
3. Turn the sensor 2 (1) into the groove (2).
OR: Slide sensor 2 (1) into the groove (2) in the direction of the housing middle (3), until the sensor 2 (1) switches.
4. Secure the sensor 2 (1) using the set-screw (4).
Tightening torque: 10 Ncm
5. Bring product into the "Gripper closed" or "Part gripped" position and test the function.

5.4.5 Mounting programmable MMS 22-PI2 magnetic switch

CAUTION

Risk of damage to the sensor during assembly!

- Observe the maximal tightening torque.



NOTE

If there is no T-nut available, slide the sensor according to dimension l1 into the groove (2), ► 5.4.2 [29].

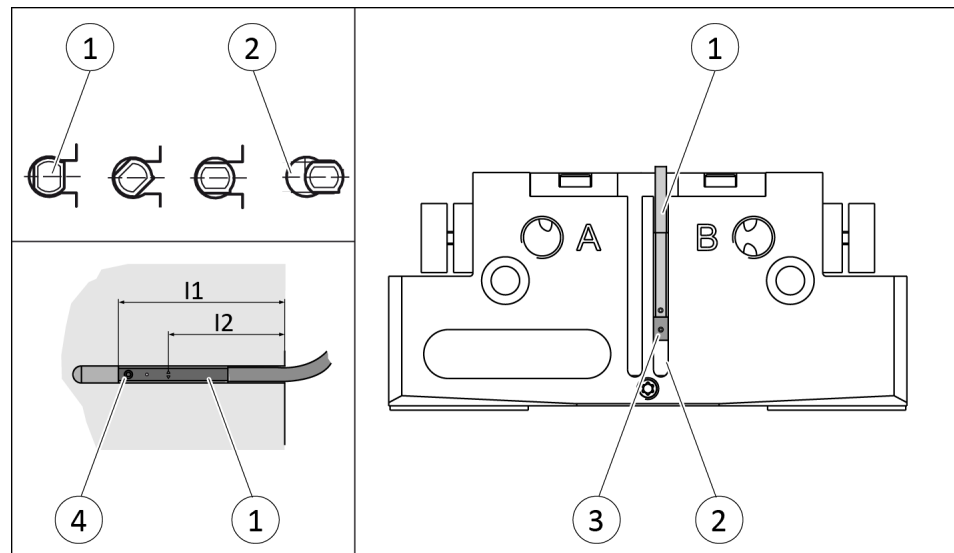
1. Turn the sensor (1) into the groove (2).
OR: Slide the sensor (1) into the groove (2) until the sensor (1) stops at the T-nut (3).
2. Secure the sensor (1) using the set-screw (4).
Tightening torque: 10 Ncm
3. Adjust sensor (1), see sensor assembly and operating manual.

5.4.6 Mounting programmable MMS 22-P 22 magnetic switch

CAUTION

Risk of damage to the sensor during assembly!

- Observe the maximal tightening torque.



NOTE

If there is no T-nut available, slide the sensor according to dimension l1 into the groove (2), ► 5.4.2 [29].

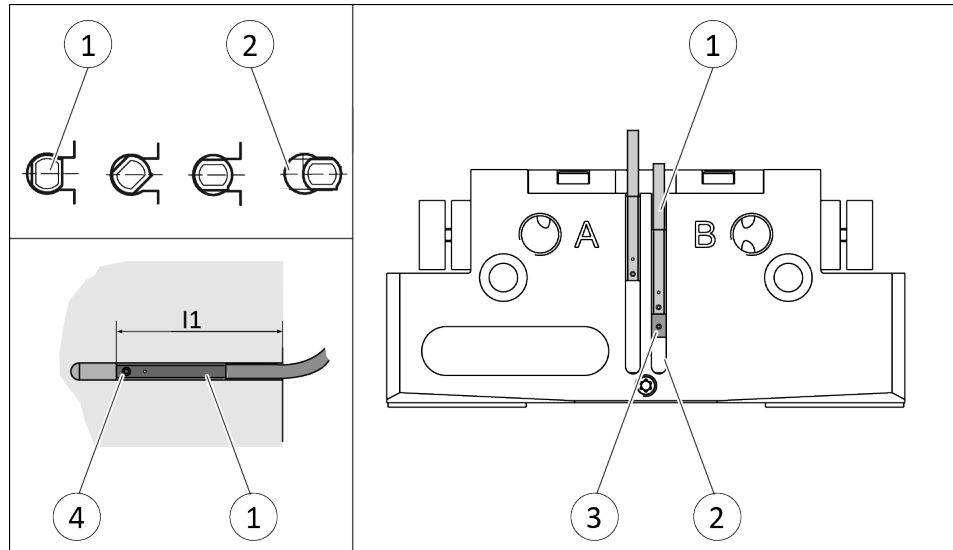
1. Turn the sensor (1) into the groove (2).
OR: Slide the sensor (1) into the groove (2) until the sensor (1) stops at the T-nut (3).
2. Secure the sensor (1) using the set-screw (4).
Tightening torque: 10 Ncm
3. Adjust sensor (1), see sensor assembly and operating manual.

5.4.7 Mounting MMS 22-PI1 programmable magnetic switch

CAUTION

Risk of damage to the sensor during assembly!

- Observe the maximal tightening torque.



NOTE

If there is no T-nut available, slide the sensor according to dimension l_1 into the groove (2), ► 5.4.2 [29].

NOTE

The magnetic switch MMS 22-PI1 can be adjusted and taught in two ways.

- "Standard mode" allows for quick installation on the T-nut preset by SCHUNK in the groove or the defined setting dimension " l_1 ."
- In "Optimal Mode", the sensor identifies the optimal position in the groove itself.
SCHUNK recommends "Optimal Mode" for setting the sensors.

Setting the sensor in "Optimum mode"

1. Put product in the position in which it is to be set.
2. Hold teaching tool to the sensor 1 (1) until the sensor flashes.
3. Slide sensor 1 (1) into the groove (2), until the sensor 1 flashes rapidly.
⇒ The optimum position is displayed.
4. Secure the sensor 1 (1) using the set-screw (3).
Tightening torque: 10 Ncm

5. Hold teaching tool to the sensor 1 (1) to confirm the position.
⇒ The sensor 1 (1) has been taught in.
6. Repeat steps for sensor 2.

Setting the sensor in "Standard mode"

1. Turn the sensor 1 (1) into the groove (2).
OR: Slide the sensor 1 (1) into the groove (2) until the sensor 1 (1) stops at the T-nut (3).
2. Secure the sensor 1 (1) using the set-screw (4).
Tightening torque: 10 Ncm
3. Adjust sensor 1 (1), see sensor assembly and operating manual.
4. Repeat steps for sensor 2.

NOTE

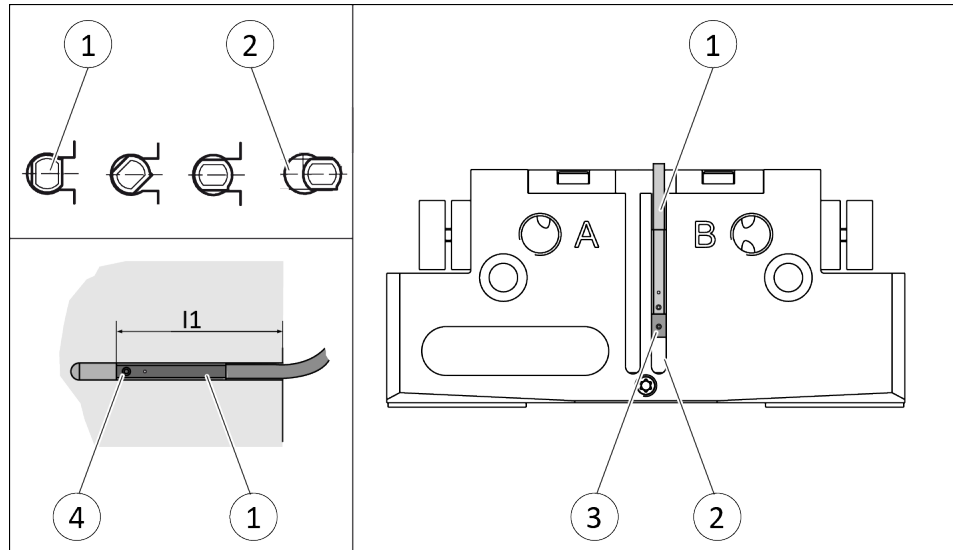
If there is no T-nut available, slide the sensor according to dimension l1 into the groove (2), ► 5.4.2 [□ 29].

5.4.8 Mounting the magnetic switch MMS 22-I0L

CAUTION

Risk of damage to the sensor during assembly!

- Observe the maximal tightening torque.



NOTE

If there is no T-nut available, slide the sensor according to dimension l1 into the groove (2), see following table.

1. Turn the sensor (1) into the groove (2).
OR: Slide the sensor (1) into the groove (2) until the sensor (1) stops at the T-nut (3).
2. Secure the sensor (1) using the set-screw (4).
Tightening torque: 10 Ncm
3. Adjust sensor (1), see sensor assembly and operating manual.

Size	l1* [mm]
40	11.9
40 AS	11.9
40 IS	21.9
50	22
50 AS	22
50 IS	38
64	17.8
64 AS	17.8
64 IS	35.8
80	25.8
80 AS	25.8

Size	l1* [mm]
80 IS	43.8
100	27
100 AS	27
100 IS	53
125	30
125 AS	30
125 IS	60
160	38
160 AS	33.5
160 IS	78.5

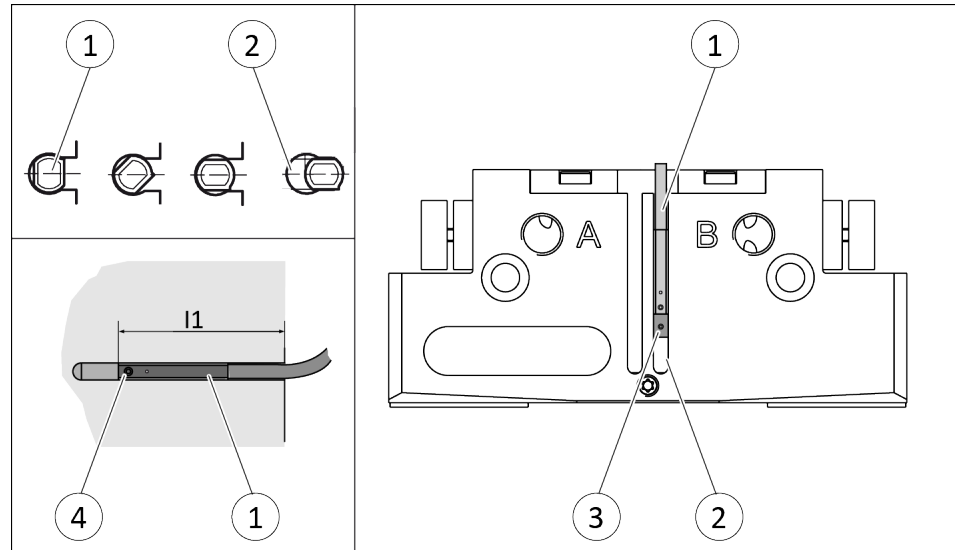
Tab.: Setting dimensions

5.4.9 Mounting analog MMS 22-A magnetic switch

CAUTION

Risk of damage to the sensor during assembly!

- Observe the maximal tightening torque.



NOTE

If there is no T-nut available, slide the sensor according to dimension l_1 into the groove (2), ► 5.4.2 [29].

Sizes 40, 64, 80, 100, 125, 160, 200

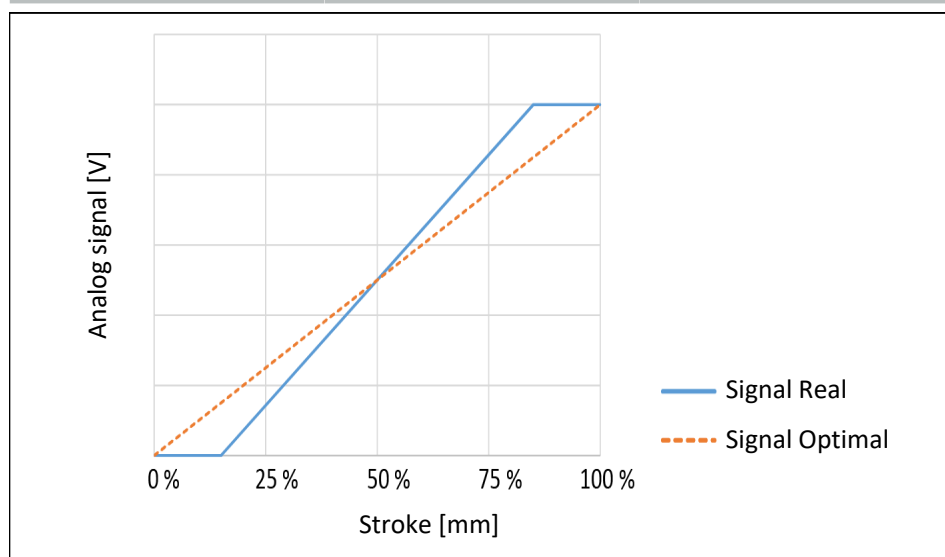
1. Turn the sensor (1) into the groove (2).
OR: Slide the sensor (1) into the groove (2) until the sensor (1) stops at the T-nut (3).
2. Secure the sensor (1) using the set-screw (4).
Tightening torque: 10 Ncm
3. Adjust sensor (1), see sensor assembly and operating manual.

Sizes 50, 200

During the monitoring, the first and last 15% of the nominal stroke will not produce a change in the analog signal. It is therefore not possible to monitor the end positions. If you have questions, please contact SCHUNK.

Size	Hub 1	
	100 %	15 %
50	4 mm	0.6 mm
200	25 mm	3.75 mm

Size	Hub 2	
	100 %	15 %
50	2 mm	0.3 mm
200	14 mm	2.1 mm



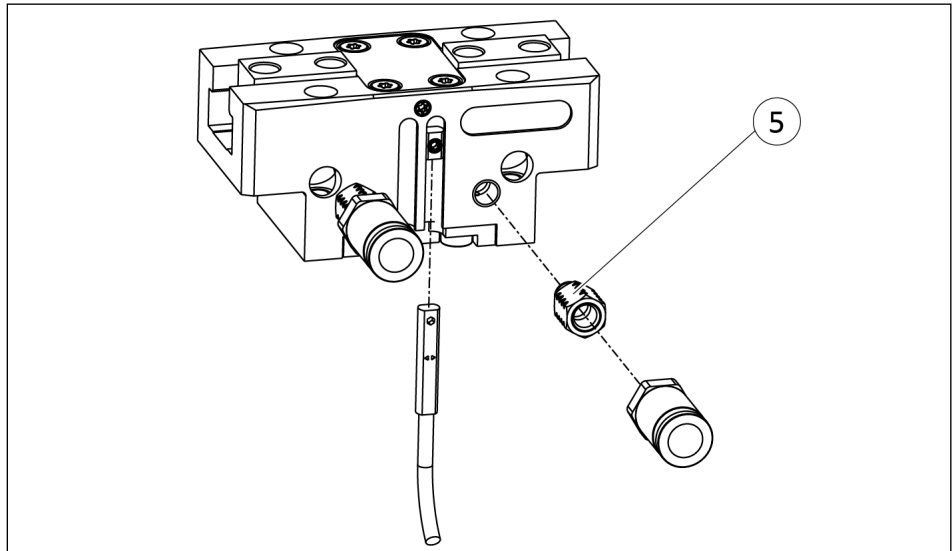
1. Turn the sensor (1) into the groove (2).
OR: Slide the sensor (1) into the groove (2) until the sensor (1) stops at the T-nut (3).
2. Secure the sensor (1) using the set-screw (4).
Tightening torque: 10 Ncm

NOTE

Only valid for size 50!

The gripper is too fast without throttling, which means that teaching the sensor does not work reliably. Fixed throttle valves or other throttle valves with a diameter of 0.8 mm can be used for the teaching process.

ID number throttle reduction M5 - 0.8: 9953035

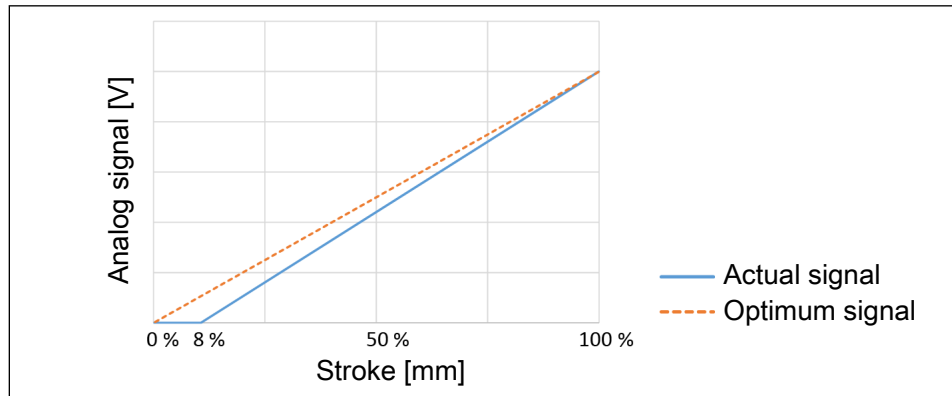


3. Mount a throttle reduction M5 - 0.8 (5) at both main connections "A" and "B".
4. Adjust sensor (1), see the Sensor Assembly and Operating Manual.
5. Remove throttle reduction (5) after finishing the sensor teaching process.

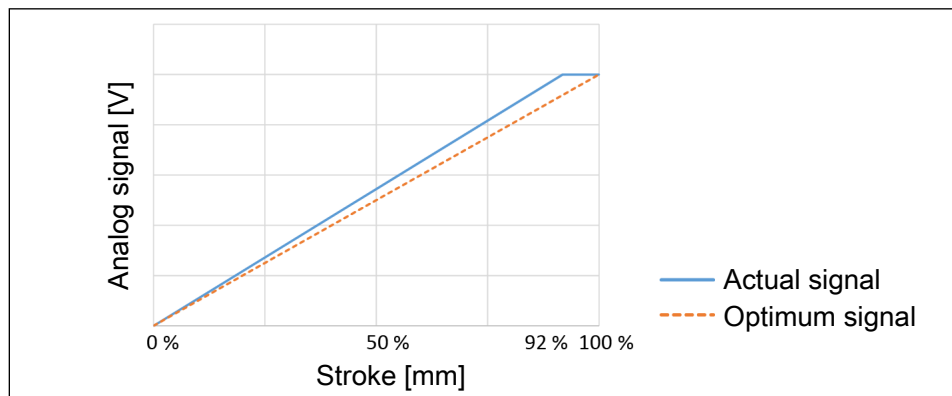
5.4.10 Mounting analog position sensor APS-Z80

To be able to mount the sensor, the gripper has to be retrofitted with a special mounting kit.

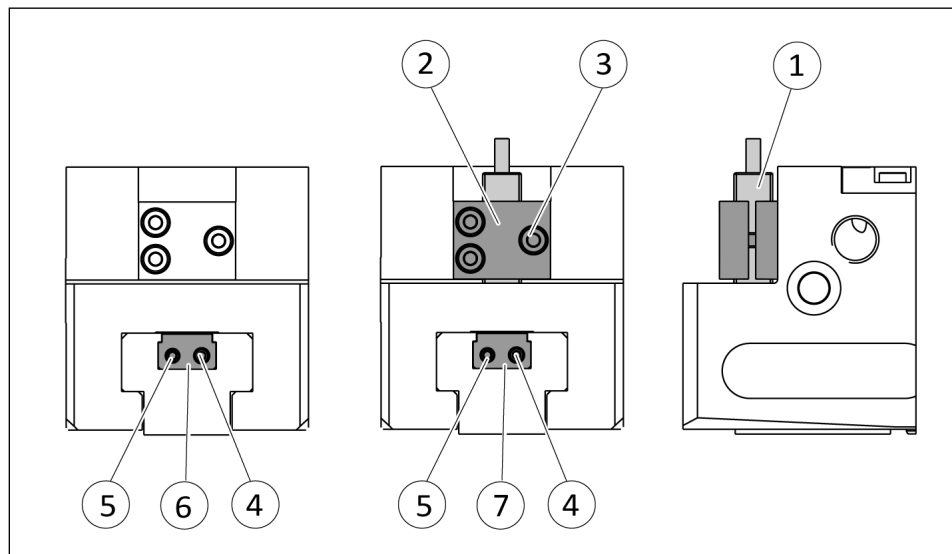
During the monitoring process, the first 8% of the nominal stroke will not produce a change in the analog signal. With O.D. gripping the "Gripper closed" position and with I.D. gripping the "Gripper opened" position cannot be queried. Should you have questions, do not hesitate to contact SCHUNK.



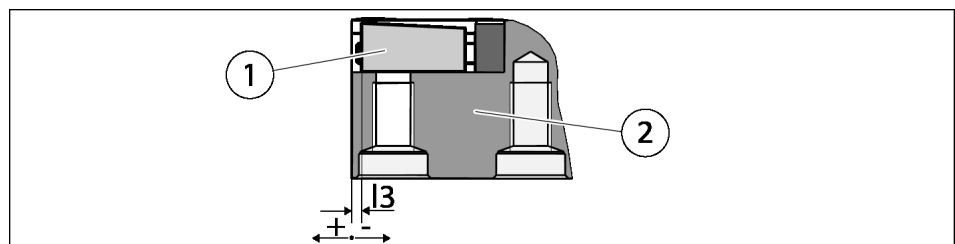
Analog signal on O.D. gripping



Analog signal on I.D. gripping



1. Move product to the "gripper open" position.
2. Loosen clamping spindle (4) and remove the switching cam (6) for inductive sensing from the base jaw by turning the adjusting spindle (5).
3. Slide control cam (7) from the mounting kit into the base jaw.
⇒ Darauf achten, dass die höhere Stirnseite der Schaltnocke (6) nach außen zeigt.
4. Screw the switching cam (7) into the base jaw by turning the adjusting spindle (5) until the adjustment dimension I3 is reached (see table below).
5. Fix the control cam (7) with the clamping spindle (4). It must not be possible to move the control cam after assembly.
6. Slide the sensor (1) to the stop into the bracket (2).
7. Tighten the screw (3) on the bracket (2).
Tightening torque: 0.2 Nm
8. Connect the sensor, see assembly and operating manual of the sensor.



Setting dimension I3 of the base jaw (2) up to the front of the control cam (1)

Size	Setting dimension I3 [mm]
64-1	+0.7
64-2	-3.8
80-1	0
80-2	-3.3
100-1	-1
100-2	-3.8
125-1	+1.7
125-2	-2.3
160-1	0
160-2	-7.1
200-1	0
200-2	-3.6
240-1	+3
240-2	-4.6
300-1	0

Tab.: Setting dimension

5.4.11 Mount the flexible position sensor FPS

The flexible position sensor FPS consists of an evaluation unit and one of the following sensors:

- MMS 22-A-5V
- FPS-S M8

CAUTION

Risk of damage to the sensor during assembly!

- Observe the maximal tightening torque.

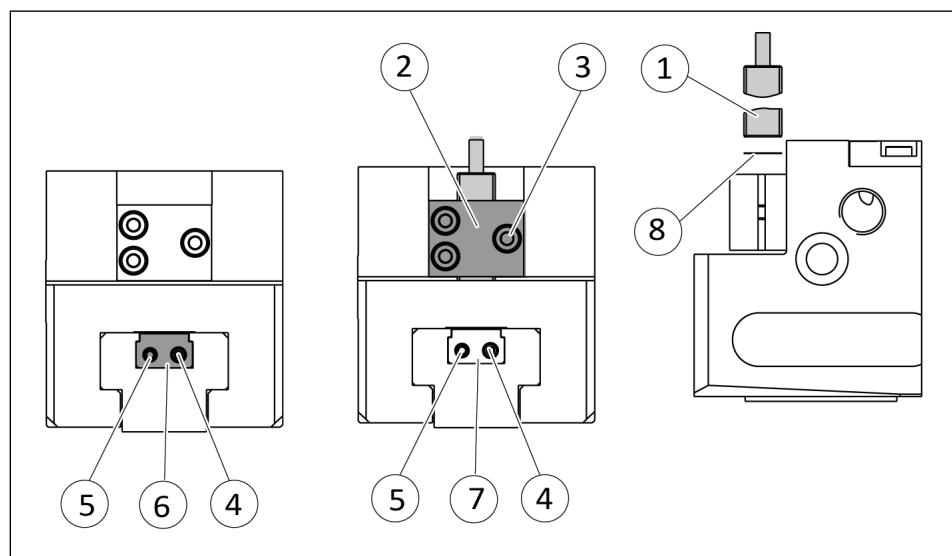
5.4.11.1 Mounting the MMS 22-A-5V

Note: In order to mount the sensor MMS 22-A-5V, no additional attachment kit is required.

1. Assembling the sensor, ▶ 5.4.9 [40] .
2. Connect the control unit output and adjust the sensor (see assembly and operating manual of the sensor).

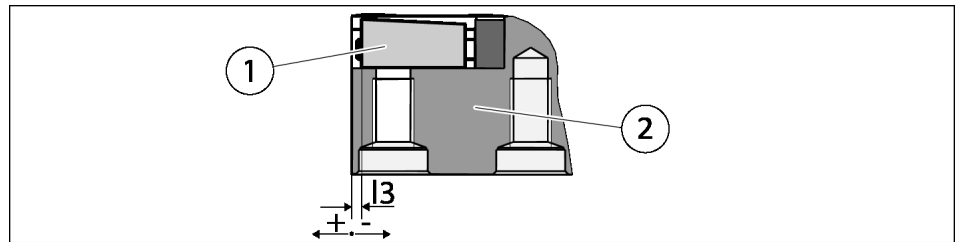
5.4.11.2 Mounting FPS-M8

To be able to mount the sensor, the gripper has to be retrofitted with a special mounting kit.



1. Move product to the "gripper open" position.
2. Loosen clamping spindle (4) and remove the switching cam (6) for inductive sensing from the base jaw by turning the adjusting spindle (5).
3. Slide control cam (7) from the mounting kit into the base jaw.
4. Screw the switching cam (7) into the base jaw by turning the adjusting spindle (5) until the adjustment dimension I3 is reached (see table below).

5. Fix the control cam (7) with the clamping spindle (4). It must not be possible to move the control cam after assembly.
6. **For sizes 125-1, 200-1 and 200-2:** Slide spacer (8) into the bracket (2) to the stop.
7. Slide the sensor (1) to the stop into the bracket (2).
8. Tighten the screw (3) on the bracket (2).
Tightening torque: 0.2 Nm
9. Connect the sensor (1), see assembly and operating manual of the sensor.



Setting dimension l3 of the base jaw (2) up to the front of the control cam (1)

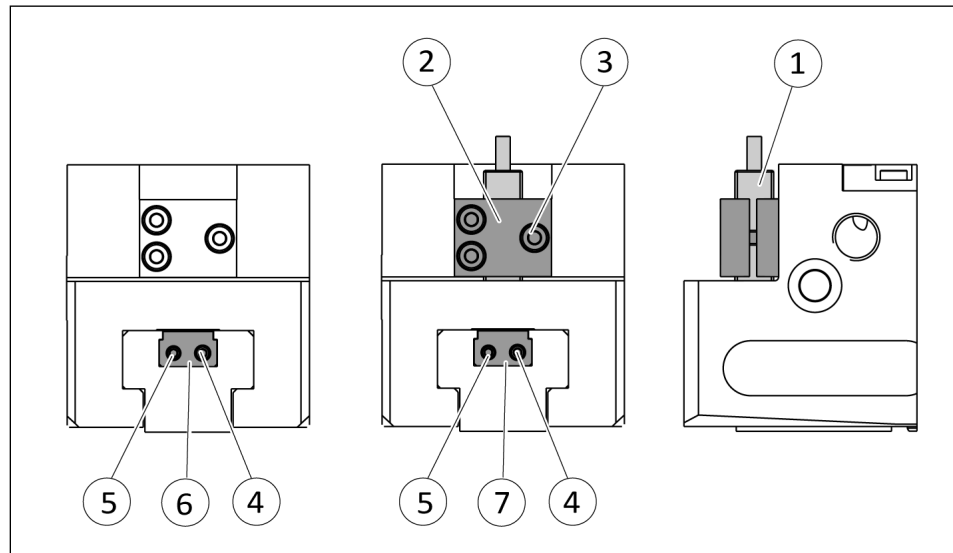
Size	Setting dimension l3 [mm]
64-1	-0.8
64-2	-1.1
80-1	-2
80-2	-2.6
100-1	-2.7
100-2	-3
125-1	-3.8
125-2	-7.8
160-1	0
160-2	-4.2
200-1	+2.2
200-2	-7.5
240-1	+4
240-2	-8.2

Tab.: Setting dimension

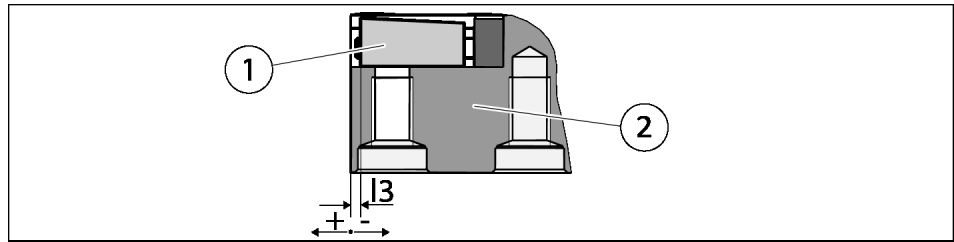
5.4.12 Mounting analog position sensor APS-M1

To be able to mount the sensor, the gripper has to be retrofitted with a special mounting kit.

For sizes 64 and 80, the clamping brackets from the mounting kit must be mounted.



1. Move product to the "gripper open" position.
2. Loosen clamping spindle (4) and remove the switching cam (6) for inductive sensing from the base jaw by turning the adjusting spindle (5).
3. Schaltnocke (7) aus dem Anbausatz in Grundbacke schieben.
⇒ Darauf achten, dass die höhere Stirnseite der Schaltnocke (6) nach außen zeigt.
4. Screw the switching cam (7) into the base jaw by turning the adjusting spindle (5) until the adjustment dimension I3 is reached (see table below).
5. Fix the control cam (7) with the clamping spindle (4). It must not be possible to move the control cam after assembly.
6. Slide the sensor (1) to the stop into the bracket (2).
7. Tighten the screw (3) on the bracket (2).
Tightening torque: 0.2 Nm
8. Connect the sensor, see assembly and operating manual of the sensor.



Setting dimension I3 of the base jaw (2) up to the front of the control cam (1)

Size	Setting dimension I3 [mm]
64-1	0
64-2	0
80-1	0
80-2	0
100-1	0
100-2	0
125-1	0
125-2	0
160-1	0
160-2	0
200-1	0
200-2	0
240-1	0
240-2	0
300-1	0

Tab.: Setting dimension

6 Troubleshooting

6.1 Product does not move

Possible cause	Corrective action
Base jaws jam in housing, e.g. mounting surface is not sufficiently even.	Check the evenness of the mounting surface. ▶ 5.2.1 [21]
Pressure drops below minimum.	Check air supply. ▶ 3 [18]
Compressed air lines switched.	Check compressed air lines. ▶ 5.2.2 [24]
Proximity switch defective or set incorrect.	Readjust or change sensor.
Unused air connections open.	Close unused air connections.
Flow control valve closed.	Open the flow control valve.
Component part defective.	Replace component or send it to SCHUNK for repair.

6.2 Product is not executing the complete stroke

Possible cause	Corrective action
Dirt deposits between cover and piston.	Clean and if necessary re-lubricate. ▶ 7 [51]
Dirt deposits between basic jaws and guidance.	Disassemble and clean the product.
Pressure drops below minimum.	Check air supply. ▶ 3 [18]
Mounting surface is not sufficiently flat.	Check the evenness of the mounting surface. ▶ 5.2.1 [21]
Component part defective.	Replace component or send it to SCHUNK for repair.

6.3 Product opens or closes abruptly

Possible cause	Corrective action
Too little grease in the mechanical guiding areas.	Clean and lubricate product.
Compressed air lines blocked.	Check compressed air lines of damage.
Mounting surface is not sufficiently flat.	Check the evenness of the mounting surface. ▶ 5.2.1 [21]
One-way flow control valve is missing or adjustet incorrectly.	Install and adjust one-way flow control valve.
Loading too large.	Check permissible weight and length of the gripper fingers.

6.4 Product does not achieve the opening and closing times

Possible cause	Corrective action
Compressed air lines are not installed optimally.	<p>If present: Open the flow control couplings on the product to the maximum that the movement of the jaws occurs without bouncing and hitting.</p> <hr/> <p>Check compressed air lines.</p> <hr/> <p>Inner diameters of compressed air lines are of sufficient size in relation to compressed air consumption.</p> <hr/> <p>Flow rate of valve is sufficiently large relative to the compressed air consumption.</p> <hr/> <p>If you still cannot achieve the open and close times in the latest catalog, we recommend the use of quick-air-vent-valves directly at the product.</p>
Compressed air can escape.	Check seals, if necessary, disassemble the product and replace seals.
Component part defective.	Replace component or send it to SCHUNK for repair.
Too much grease in the mechanical movement space.	Clean and lubricate product.
Loading too large.	Check permissible weight and length of the gripper fingers.

6.5 Gripping force is dropping

Possible cause	Corrective action
Compressed air can escape.	Check seals, if necessary, disassemble the product and replace seals.
Too much grease in the mechanical movement space.	Clean and lubricate product.
Pressure drops below minimum.	<p>Check air supply.</p> <p>▶ 3 [18]</p>
Component part defective.	Replace component or send it to SCHUNK for repair.

7 Maintenance

7.1 Notes

Original spare parts

Use only original spare parts of SCHUNK when replacing spare and wear parts.

Replacement of the housing and base jaws

The base jaws and the guides in the housing are matched to each other. To replace these parts, send the product to SCHUNK with a repair order.

7.2 Maintenance intervals

If products are used at room temperature and the ambient and operating conditions are adhered to, these variants are maintenance-free, ▶ 3 [□ 18].

If products are not used at room temperature or in special ambient conditions, the following maintenance intervals apply

Interval (million cycles):	10 (Size 40 – 160)
	5 (Size 200– 300)

Maintenance work:	<ul style="list-style-type: none"> • Clean the product dry without a degreasing agent, check for damage and wear. • If required: Replace seals, ▶ 7.5 [□ 54]. • Treat all grease areas with lubricant, ▶ 7.3 [□ 52], ▶ 7.4 [□ 53].
-------------------	---

For extreme ambient and application conditions, shortened maintenance cycles can ensure the lifespan is maintained.

CAUTION

Material damage due to hardening lubricants!

Lubricants harden more quickly at temperatures above 60°C, leading to possible product damage.

- Reduce the lubricant intervals accordingly.

7.3 Lubricants/Lubrication points (basic lubrication)

During maintenance, treat all greased areas with lubricant. Thinly apply lubricant with a lint-free cloth.

SCHUNK recommends the lubricants listed.

Lubricant point	Lubricant
Metallic sliding surfaces	SCHUNK grease 3
Seals and sealing surfaces	SCHUNK grease 1
Cylinder surfaces	SCHUNK grease 1

Details regarding SCHUNK lubricant designations are available at [schunk.com/lubricants](https://www.schunk.com/lubricants).

The product contains food-compliant lubricants as standard.

The requirements of standard EN 1672-2:2020 are not fully met.

NOTE

- Change contaminated food-compliant lubricant.
 - Observe information in the safety data sheet from the lubricant manufacturer.
-

7.4 Lubricate product

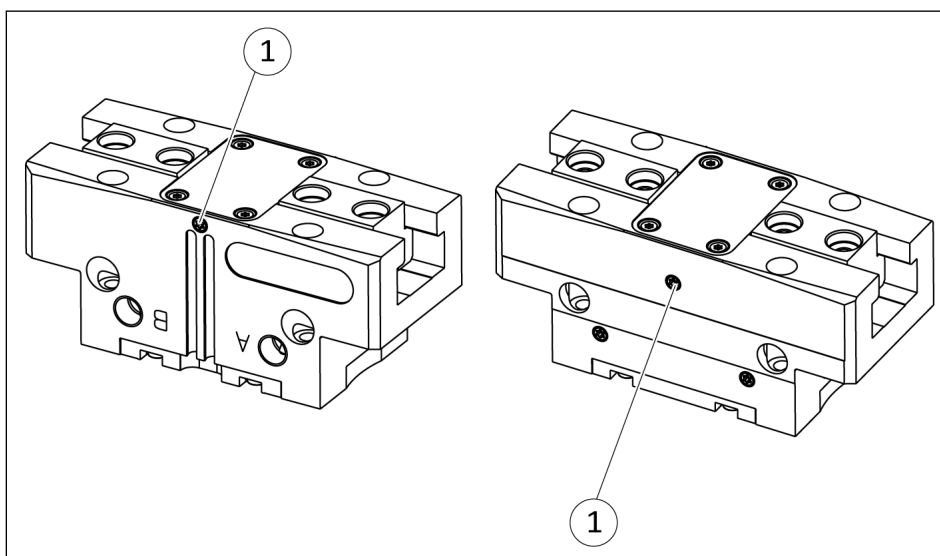


⚠ WARNING

Risk of injury due to moving parts!

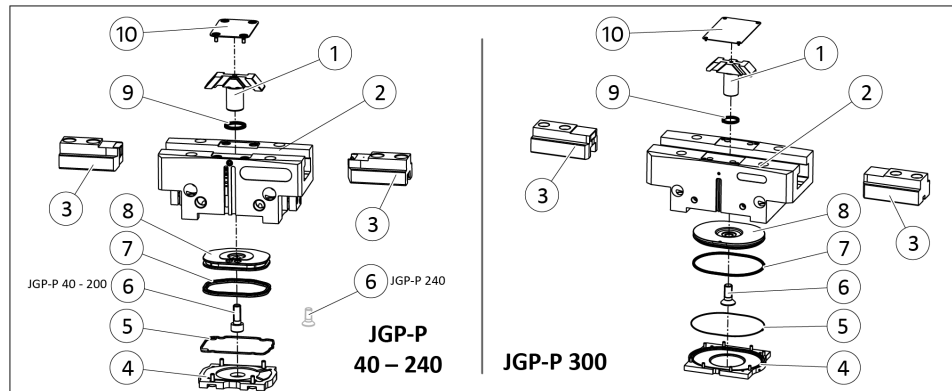
When moving the gripper fingers, body parts may get squashed/hit causing severe injuries.

- Do not interfere with moving parts during operation.
- Observe position and direction of movement of the gripper fingers.



1. Remove set-screw on an air purge connection (1).
2. Screw in lubrication nipple.
3. Apply a layer of grease to metallic sliding surfaces of the gripper using the lubrication nipple, ▶ 7.3 [52].
 - ⇒ While lubricating, completely open and close the gripper alternately.
4. Unscrew the lubrication nipple.
5. Screw set-screws into both air purge connections (1).

7.5 Replace seal (variant without gripping force maintenance)



1. Remove all compressed air lines, ▶ 5.2.2 [24].
2. Remove product from the system/machine.
3. Remove the cover (10).
4. Mark the installation position of the base jaws (3) on the housing (2).
5. Remove the screws and the cover (4).
6. Unscrew screw (6) and take cylinder piston (8) out of the housing (2).
7. Push the wedge hook (1) out of the housing (2).
8. Take base jaws (3) out of the housing (2).
9. Remove old seals (9, 5 and 7).
10. Clean guiding areas.
11. Mount new seals (9 and 7) from the seal kit.
12. Re-lubricating guiding areas
13. Insert base jaws (3) into the housing (2). **IMPORTANT! Observe installation position of the base jaws (3) in the housing (2).**
14. Insert wedge hook (1) into the housing (2).
15. Insert cylinder piston (8) into the housing (2) and while doing so, observe the installation position of the magnets, ▶ 7.8 [59].
16. Tighten screw (6). Secure the screw with medium-strength threadlocker.
Tightening torque: ▶ 7.9 [60]
17. Insert flat gasket (5).
18. Fasten the cover (4) with the screws.
Tightening torque: ▶ 7.9 [60]
19. Fasten the cover (10) with the screws.
20. Mount product onto the system/machine.
21. Connect all compressed air lines.

7.6 Replace seal (variant with gripping force maintenance "O.D. gripping")



⚠ WARNING

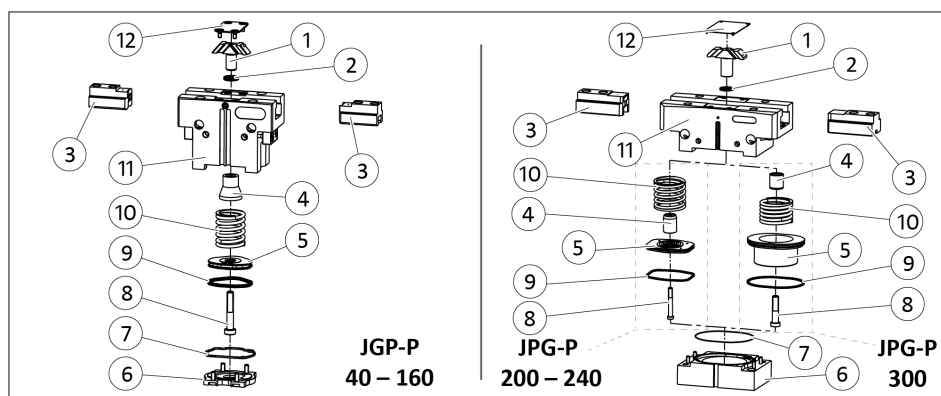
Risk of injury due to spring forces!

Products that use spring force or have gripping force maintenance contain parts that are under spring tension. This can cause components to move unexpectedly when being dismantled, which may result in serious injuries.

- Carefully dismantle the product.

NOTE

During assembly, the cylinder piston must be aligned precisely. We therefore recommend having SCHUNK change the seals.



- Remove all compressed air lines, ▶ 5.2.2 [24].
- Remove product from the system/machine.
- Remove the cover (12).
- Mark the installation position of the base jaws (3) on the housing (11).
- WARNING Risk of injury due to spring forces! The cover (6) is under spring tension. Carefully disassemble the product.** Clamp the product between the base jaws (3) and the cover (6) in the vise so that it is still possible to remove the screws.
- Remove cover (6).
- WARNING The cylinder piston is under spring tension. Remove carefully.** Unscrew screw (8) carefully and take cylinder piston (5), spring (10) and the spacer (4) out of the housing (11).
- Push the wedge hook (1) out of the housing (11).
- Take base jaws (3) out of the housing (11).
- Remove old seals (2, 7 and 9).
- Clean guiding areas.

12. Attach new seals (2 and 9) from the seal kit.
13. Re-lubricating guiding areas
14. Insert base jaws (3) into the housing (11). **IMPORTANT! Observe installation position of the base jaws (3) in the housing (11).**
15. Insert wedge hook (1) into the housing (11).
16. Insert spring (10) and spacer (4) into the housing (11).
17. Place the cylinder piston (5) in the housing (11) and while doing so, observe the installation position of the magnets, ▶ 7.8 [📄 59].
18. Align the cylinder piston (5) exactly.
19. Tighten the screw (8) and secure with medium-strength threadlocker.
Tightening torque: ▶ 7.9 [📄 60]
20. Insert cylinder piston (5), slide towards the housing and tighten screw (8). Secure the screw with medium-strength threadlocker.
Tightening torque: ▶ 7.9 [📄 60]
21. Insert flat gasket (7).
22. Fasten the cover (6) with the screws.
Tightening torque: ▶ 7.9 [📄 60]
23. Fasten the cover (12) with the screws.
24. Mount product onto the system/machine.
25. Connect all compressed air lines.

7.7 Replace seal (variant with gripping force maintenance "I.D. gripping")

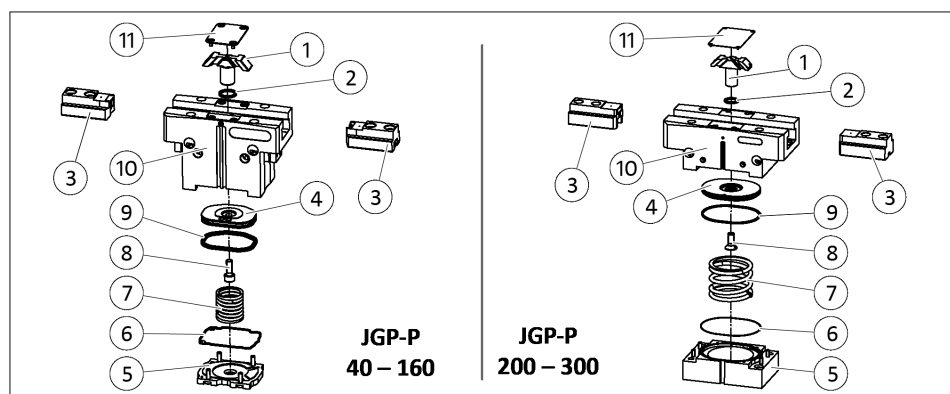


⚠ WARNING

Risk of injury due to spring forces!

Products that use spring force or have gripping force maintenance contain parts that are under spring tension. This can cause components to move unexpectedly when being dismantled, which may result in serious injuries.

- Carefully dismantle the product.

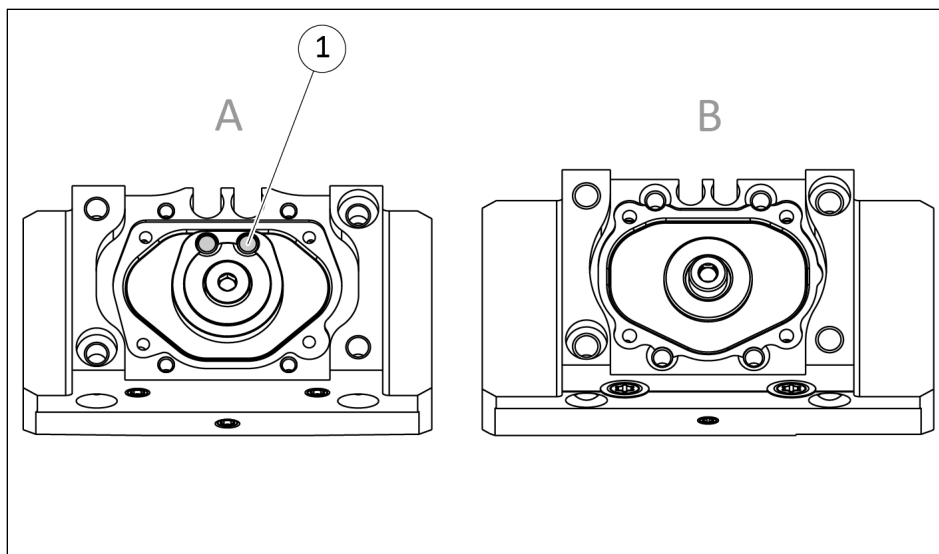


1. Remove all compressed air lines, ▶ 5.2.2 [24].
2. Remove product from the system/machine.
3. Remove the cover (11).
4. Mark the installation position of the base jaws (3) on the housing (10).
5. **IMPORTANT! Cover (5) is under spring tension. Remove carefully.**
Carefully unscrew the screws and remove the cover (5) and the spring (7).
6. Unscrew screw (8) and take cylinder piston (4) out of the housing (10).
7. Push the wedge hook (1) out of the housing (10).
8. Take base jaws (3) out of the housing (10).
9. Remove old seals (2, 6 and 9).
10. Clean guiding areas.
11. Attach new seals (2 and 9) from the seal kit.
12. Re-lubricating guiding areas
13. Insert base jaws (3) into the housing (10). **IMPORTANT! Observe installation position of the base jaws (3) in the housing (10).**
14. Insert wedge hook (1) into the housing (10).

- 15.** Insert the cylinder piston (4) into the housing (10) and while doing so, observe the installation position of the magnets, ▶ 7.8 [□ 59].
- 16.** Tighten screw (8). Secure the screw with medium-strength threadlocker.
Tightening torque: ▶ 7.9 [□ 60]
- 17.** Insert spring (7) into the housing (10). In doing so, observe the alignment of the spring in relation to the cylinder piston.
- 18.** Insert flat gasket (6).
- 19.** Fasten the cover (5) with the screws.
Tightening torque: ▶ 7.9 [□ 60]
- 20.** Fasten the cover (11) with the screws.
- 21.** Mount product onto the system/machine.
- 22.** Connect all compressed air lines.

7.8 Installation position of the magnets in the piston

The installation position of the piston in the housing depends on the size and variant. The magnets (1) attached to the piston can either point upwards (A) or downwards (B).



Installation position of the piston in the housing, A: Magnet (1) above, B: Magnet below

JGP-P	A	B
Variant without maintenance of gripping force		
40	X	-
50 - 240	-	X
300	-	X
Variant with "O.D. gripping" maintenance of gripping force		
40 AS	X	-
50-125 AS	-	X
160-240 AS	X	-
300 AS	-	X
Variant with "I.D. gripping" maintenance of gripping force		
40 IS	X	-
50 - 240 IS	-	X
300 IS	-	X

In the variant described in these operating instructions, the installation position corresponds to **Detail A**.

In the variant described in these operating instructions, the installation position corresponds to **Detail B**.

In the variant described in these operating instructions, the installation position corresponds to **Detail B**.

7.9 Tightening torques

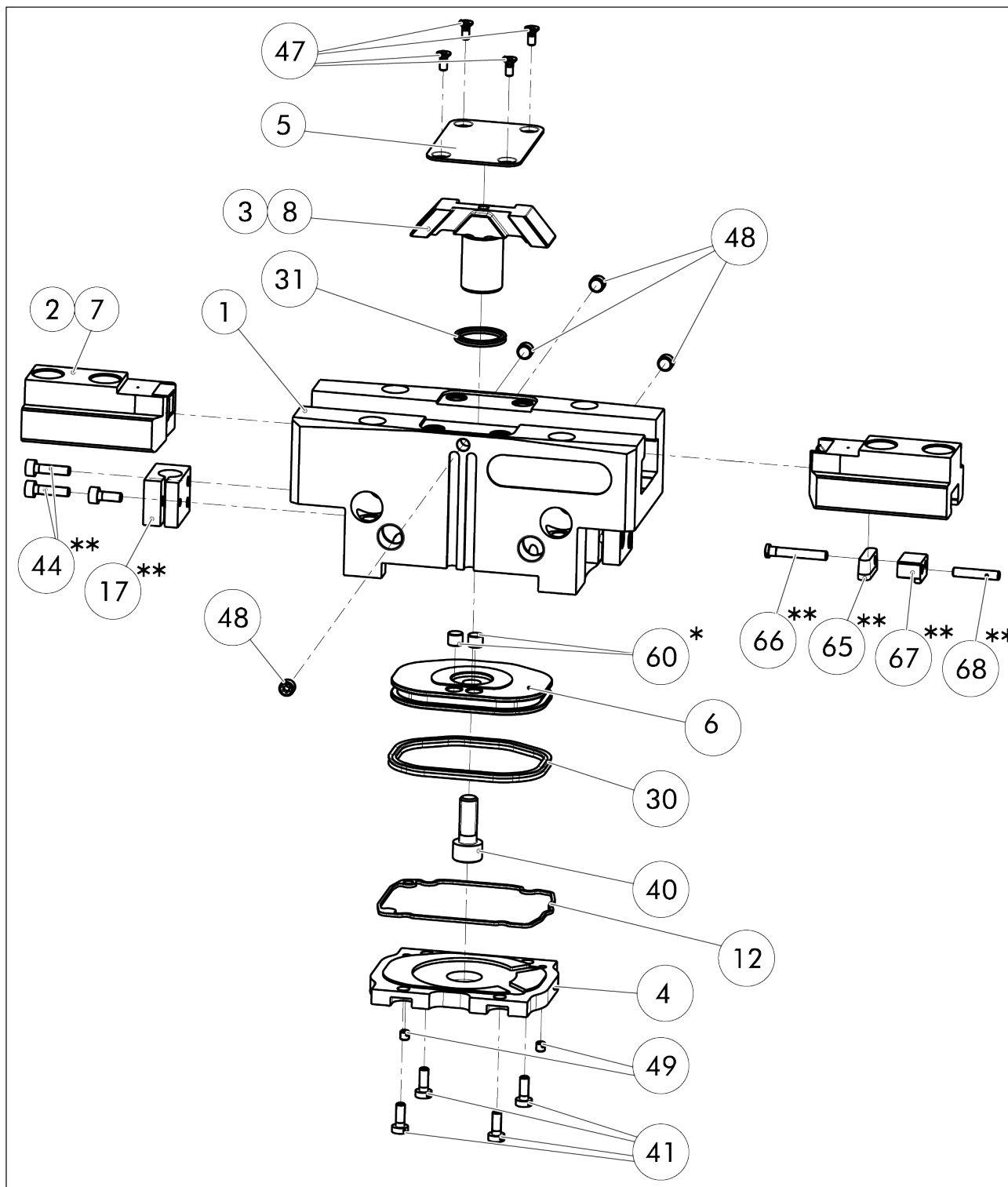
Position of the item numbers: ▶ 7.10 [61]

Size	Item 40	Item 41	Item 45	Item 46	Item 51
40	1.2	0.27	–	–	–
50	1.2	1.2	–	–	–
64	6.1	1.2	–	–	–
80	10	3.1	–	–	–
100	15	3.1	–	–	–
125	25	3.1	–	–	–
160	49	2.2	–	–	–
200	65.5	4.3	–	25	–
240	85	4.3	–	25	–
240-1 AS	85	4.3	–	–	25
300	120	6	–	–	–
300 AS	–	–	150	25	–
300 IS	120	–	–	25	–

Tab.: Tightening torque [Nm]

7.10 Assembly drawing

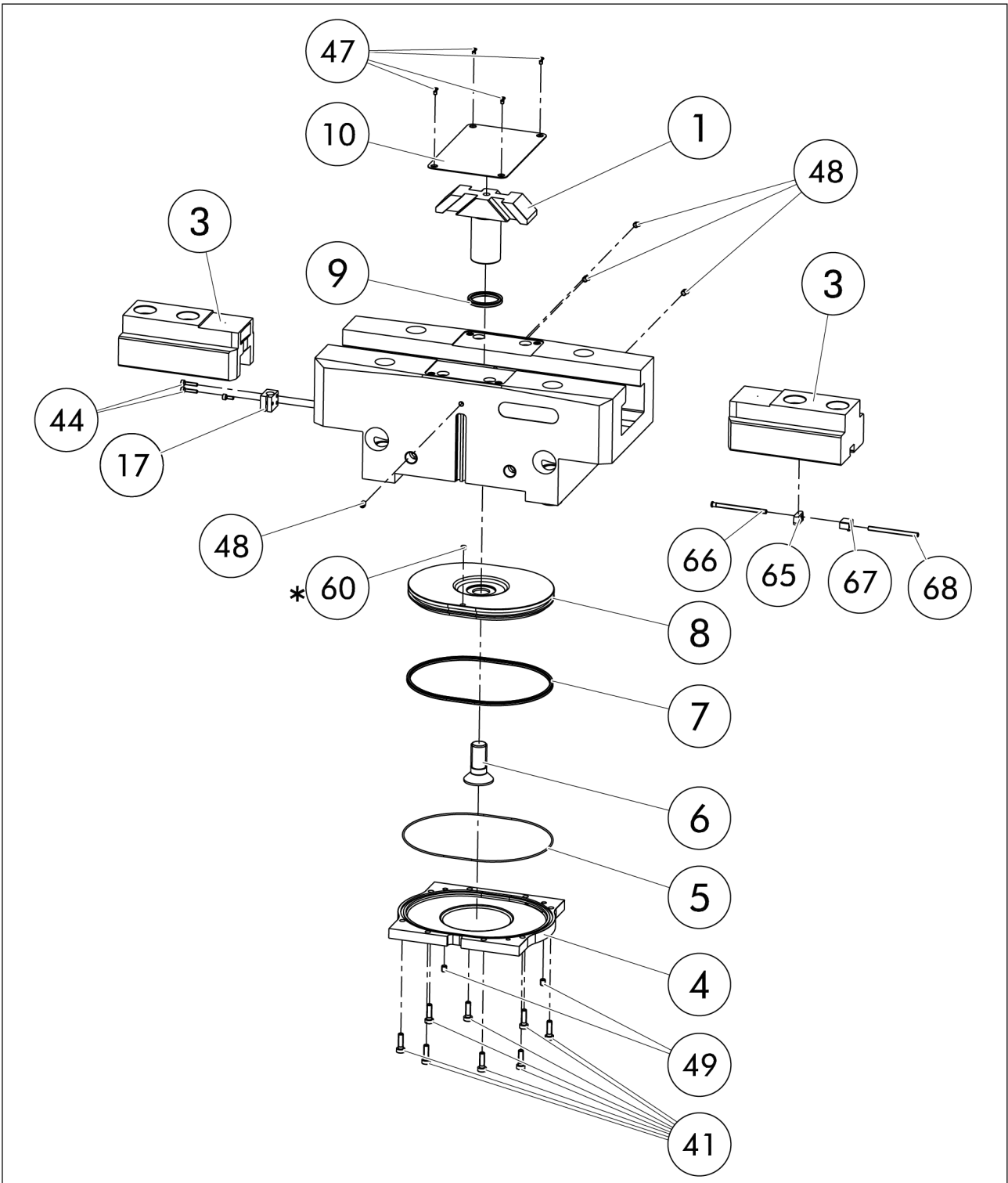
JGP-P 40 – 240 standard



* Position of the magnets in the piston depends on the variant and size, ► 7.8 [59].

** Not for JGP-P 40/50

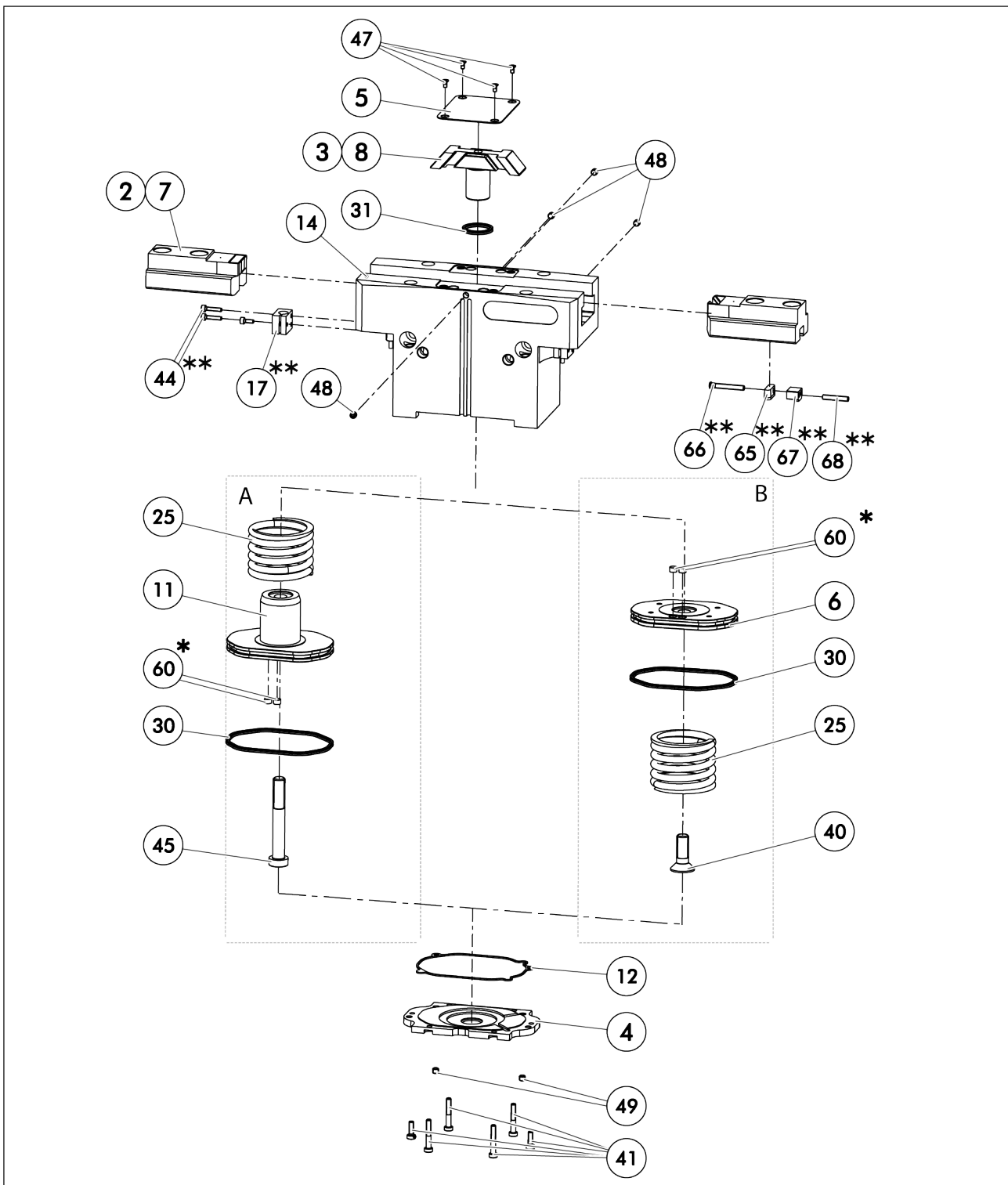
JGP-P 300 standard



* Position of the magnets in the piston depends on the variant and size, ▶ 7.8 [59].

** Not for JGP-P 40/50

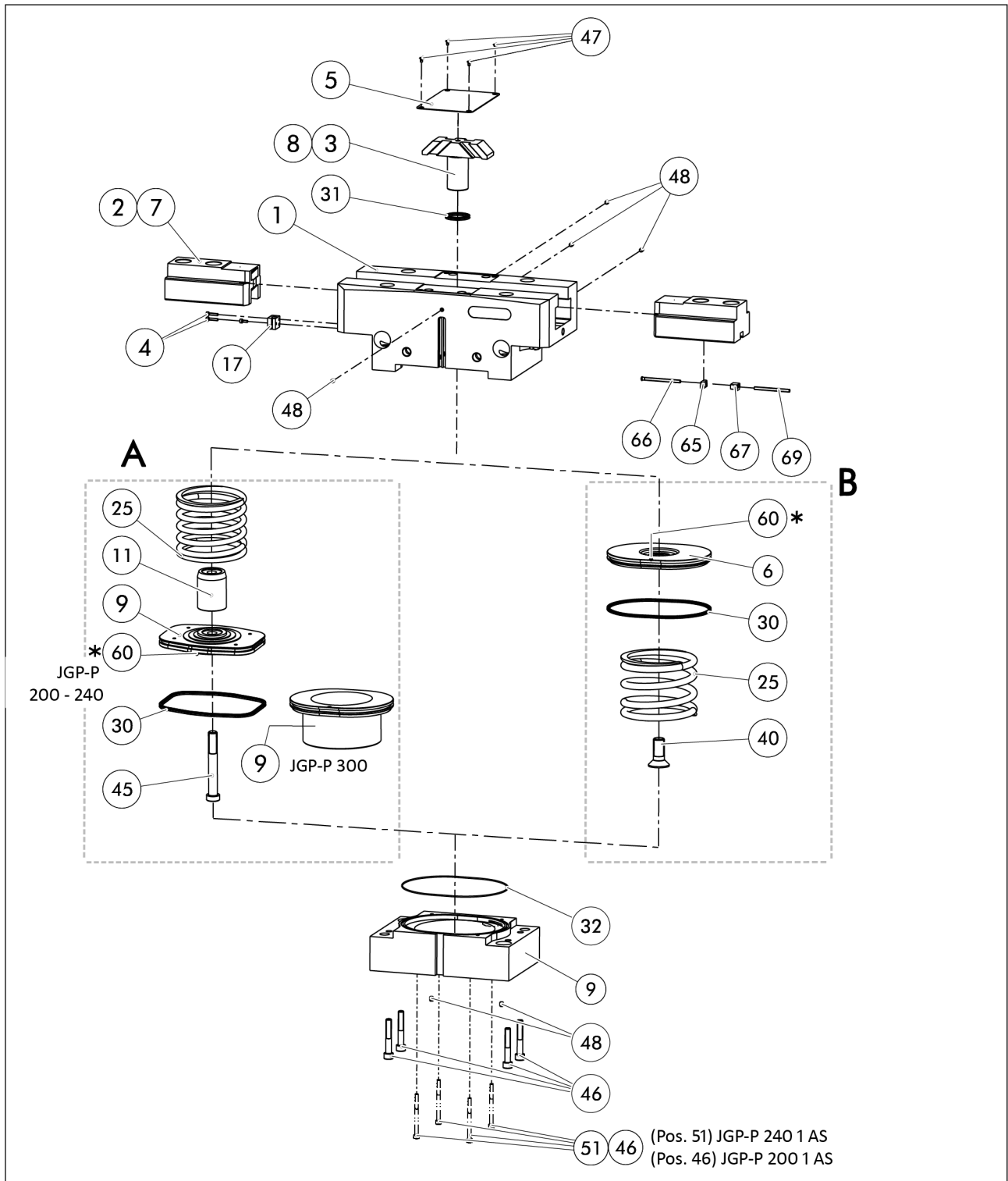
JGP-P 40 – 160 with maintenance of gripping force *O.D. gripping* (A) and *I.D. gripping* (B)



* Position of the magnets in the piston depends on the variant and size, ▶ 7.8 [59].

** Not for JGP-P 40/50

JGP-P 200 – 300 with maintenance of gripping force *O.D.* gripping (A) and *I.D.* gripping (B)



* Position of the magnets in the piston depends on the variant and size, ▶ 7.8 [59].

8 Translation of the original declaration of incorporation

in terms of the Directive 2006/42/EG, Annex II, Part 1 Section B.

Manufacturer/
Distributor SCHUNK SE & Co. KG
Spanntechnik | Greiftechnik | Automatisierungstechnik
Bahnhofstr. 106 – 134
D-74348 Lauffen/Neckar

We hereby declare that the partly completed machine described below

Product designation: 2-finger parallel gripper / JGP-P /pneumatic
ID number 1460247 ... 1460270, 1460272 ... 1460279, 1460281 ... 1460284,
1460287 ... 1460289, 1460291 ... 1460294, 1460296 ... 1460300

meets the following basic occupational health and safety of the Machinery Directive 2006/42/EC:

No. 1.1.1, No. 1.1.2, No. 1.1.3, No. 1.1.5, No. 1.3.2, No. 1.5.3, No. 1.5.4, No. 1.5.6, No. 1.5.8, No. 1.5.10, No. 1.5.11, No. 1.5.13

The partly completed machinery may not be put into operation until it has been confirmed that the machine into which the partly completed machinery is to be installed complies with the provisions of the Machinery Directive (2006/42/EC). The declaration shall be rendered invalid if modifications are made to the product.

Applied harmonized standards, especially:

EN ISO 12100:2010 Safety of machinery – General principles for design –
Risk assessment and risk reduction

The special technical documentation according to Annex VII, Part B, belonging to the partly completed machine, has been created.

Person authorized to compile the technical documentation:
Stefanie Walter, Address: see manufacturer's address

Signature: see original declaration

Lauffen/Neckar, October 2024

Dr.-Ing. Manuel Baumeister,
Head of Systems Engineering,
Technology & Innovation

9 UKCA declaration of incorporation

in accordance with the Supply of Machinery (Safety) Regulations 2008.

Manufacturer/ Distributor SCHUNK Intec Limited
Clamping and gripping technology
3 Drakes Mews, Crownhill
MK8 0ER Milton Keynes

We hereby declare that on the date of the declaration the following partly completed machine complied with all basic safety and health regulations found in the "Supply of Machinery (Safety) Regulations 2008".

The declaration shall be rendered invalid if modifications are made to the product.

Product designation: 2-finger parallel gripper / JGP-P / pneumatic
ID number 1460247 ... 1460270, 1460272 ... 1460279, 1460281 ... 1460284,
1460287 ... 1460289, 1460291 ... 1460294, 1460296 ... 1460300

The partly completed machine may not be put into operation until it has been confirmed that the machine into which the partly completed machine is to be installed complies with the provisions of the "Supply of Machinery (Safety) Regulations 2008".

Applied harmonized standards, especially:

EN ISO 12100:2010 Safety of machinery – General principles for design –
Risk assessment and risk reduction

The special technical documentation according to Annex VII, Part B, belonging to the partly completed machine, has been created.

Person authorized to compile the technical documentation:
Marcel Machado, address: refer to manufacturer's address



Lauffen/Neckar, October 2024

Dr.-Ing. Manuel Baumeister,
Head of Systems Engineering,
Technology & Innovation

10 Information on the RoHS Directive, REACH Regulation and Substances of Very High Concern (SVHC)

RoHS Directive

SCHUNK products are classified as "large-scale stationary installations" or as "large-scale stationary industrial tools" within the meaning of Directive 2011/65/EU and its extension 2015/863/EU "on the restriction of the use of certain hazardous substances in electrical and electronic equipment (RoHS)", or fulfill their intended function only as part of one. Therefore products from SCHUNK do not fall within the scope of the directive at this time.

REACH Regulation

Products from SCHUNK fully comply with the regulations of Regulation (EC) No. 1907/2006 "concerning the Registration, Evaluation, Authorization and Restriction of Chemicals (REACH)" and its amendment 2022/477. SCHUNK attaches great importance to completely avoiding chemicals of concern to humans and the environment wherever possible.

Only in rare exceptional cases do SCHUNK products contain SVHC substances on the candidate list with a mass content above 0.1%. In accordance with Article. 33 (1) of Regulation (EC) No. 1907/2006, SCHUNK complies with its duty to "communicate information on substances in articles" and lists the components concerned and the substances used in an overview that can be viewed at schunk.com/SVHC.

Signature: see original declaration

Lauffen/Neckar, October 2024

Dr.-Ing. Manuel Baumeister,
Head of Systems Engineering,
Technology & Innovation



SCHUNK SE & Co. KG
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