



Superior Clamping and Gripping



## Product Information

Random orbit sander A0V

## Compliant. Compact. Flexible. Pneumatic random orbit sander

Pneumatic random orbit sander with axial compensation for grinding and polishing of workpiece surfaces

### Field of application

Automated grinding and polishing of workpiece surfaces with a constant, adjustable contact pressure for reproducible quality.



### Advantages – Your benefits

**Compensation can be adjusted by means of a double-action pneumatic cylinder** for a constant contact pressure independent of the orientation of the tool

**Optional media change system** for automated exchange of grinding or polishing wheels

**Optional connection for suction** for reduced contamination and susceptibility to faults

**Flexibility in axial direction** for a simplified robot programming

**Use of proven, adhesive grinding and polishing wheels** for simplified automation of manual grinding and polishing tasks

**Simple exchange of wear parts** for maximum system availability and minimum spare parts requirements



Sizes  
Quantity: 1



Idle speed max.  
10000 1/min



Max. extension  
compensation force  
66.7 N



Max. retraction  
compensation force  
33.3 N

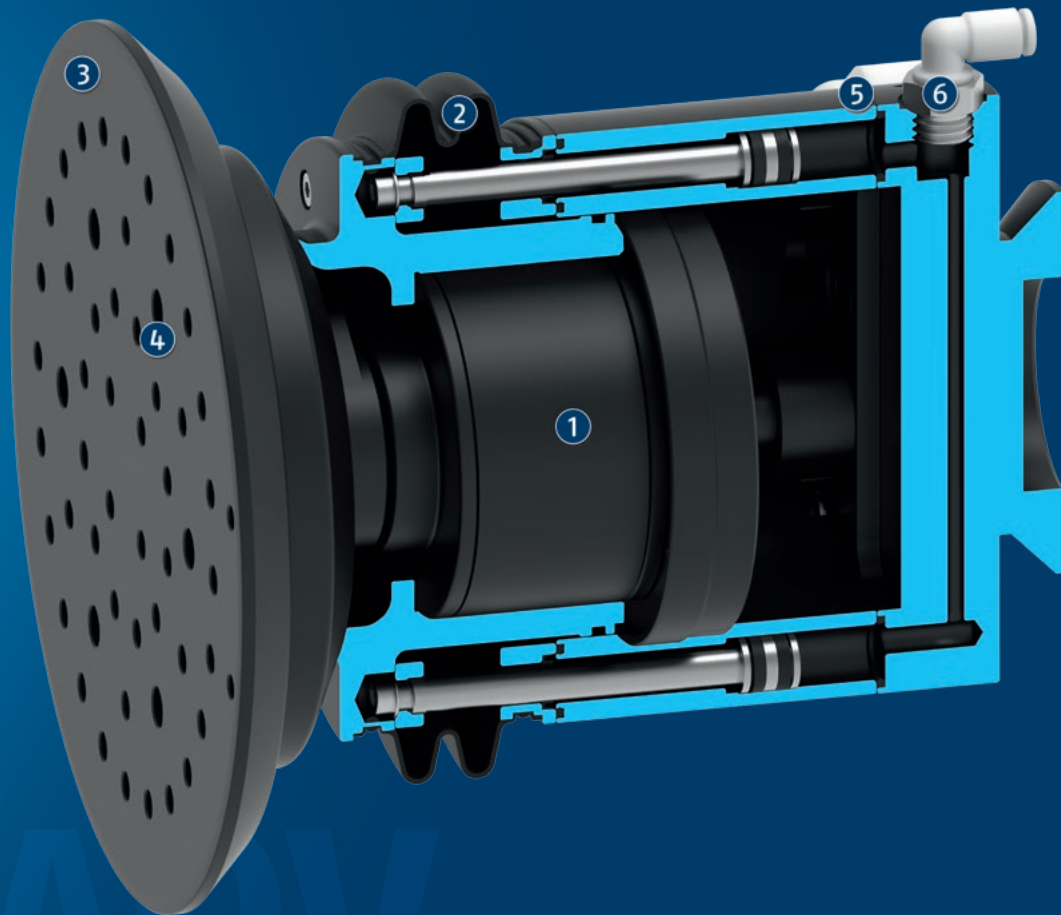


Compensation Z  
12.7 mm

## Functional description

The random orbit sander is driven by a vane-type air motor. The motor is driven by filtered and oiled air. The motor is axially and flexibly mounted to compensate for tolerances on the workpiece surface and to ensure a constant contact force during the grinding or polishing process. The contact force can be controlled separately in

two directions (retracting and extending) via two air connections, so that a variable contact pressure can be achieved. The random orbit sander can be used with two different sanding pad diameters and can be optionally equipped with a connection for an extraction system.



- ① **Rotating piston air engine**  
for a high torque and a short stopping time
- ② **Dust cover**  
protects the bearing against contamination
- ③ **Grinding pad**  
for adhesive grinding or polishing wheels
- ④ **Bore holes**  
for extraction of grinding and polishing dust
- ⑤ **Air connection**  
for the supply of the motor
- ⑥ **Air connection**  
for adjusting the contact pressure to the workpiece

# AOV

Random orbit sander

## General notes about the series

**Mounting:** on the robot arm or as a stationary unit

**Actuation:** pneumatic, via filtered (<5 µm, dry) and oiled compressed air (2-3 drops per hour)

**Warranty:** 24 months

**Ambient conditions:** Please note that the unit is not suitable for use in an area where coolants or cutting fluids are present.



## Application example

Robot-guided surface treatment of sheet metal with automatic abrasive changer consisting of disk magazine, presence detector and remover.

- |   |                          |    |                                 |
|---|--------------------------|----|---------------------------------|
| 1 | Orbital Sander Tool AOV  | 7  | Tool stand module CDB           |
| 2 | Deburring tool CDB       | 8  | Mounting module pin and bushing |
| 3 | Workpiece                | 9  | Washer rack                     |
| 4 | Magnetic gripper EMH     | 10 | Washer presence detector        |
| 5 | Quick-change system SWS  | 11 | Washer remover                  |
| 6 | Quick-change adapter SWA |    |                                 |

## SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Quick change system



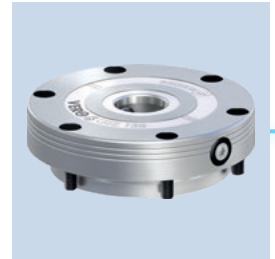
Manual change system



Force/torque sensor



Clamping force block



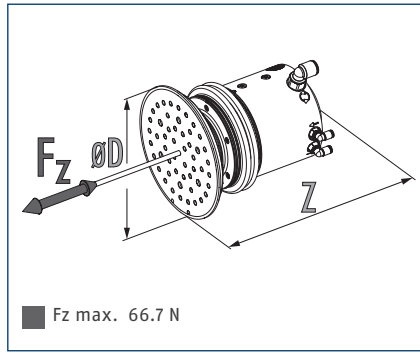
Quick-change Pallet System

① For more information on these products can be found on the following product pages or at [schunk.com](http://schunk.com).

# AOV 10

Random orbit sander

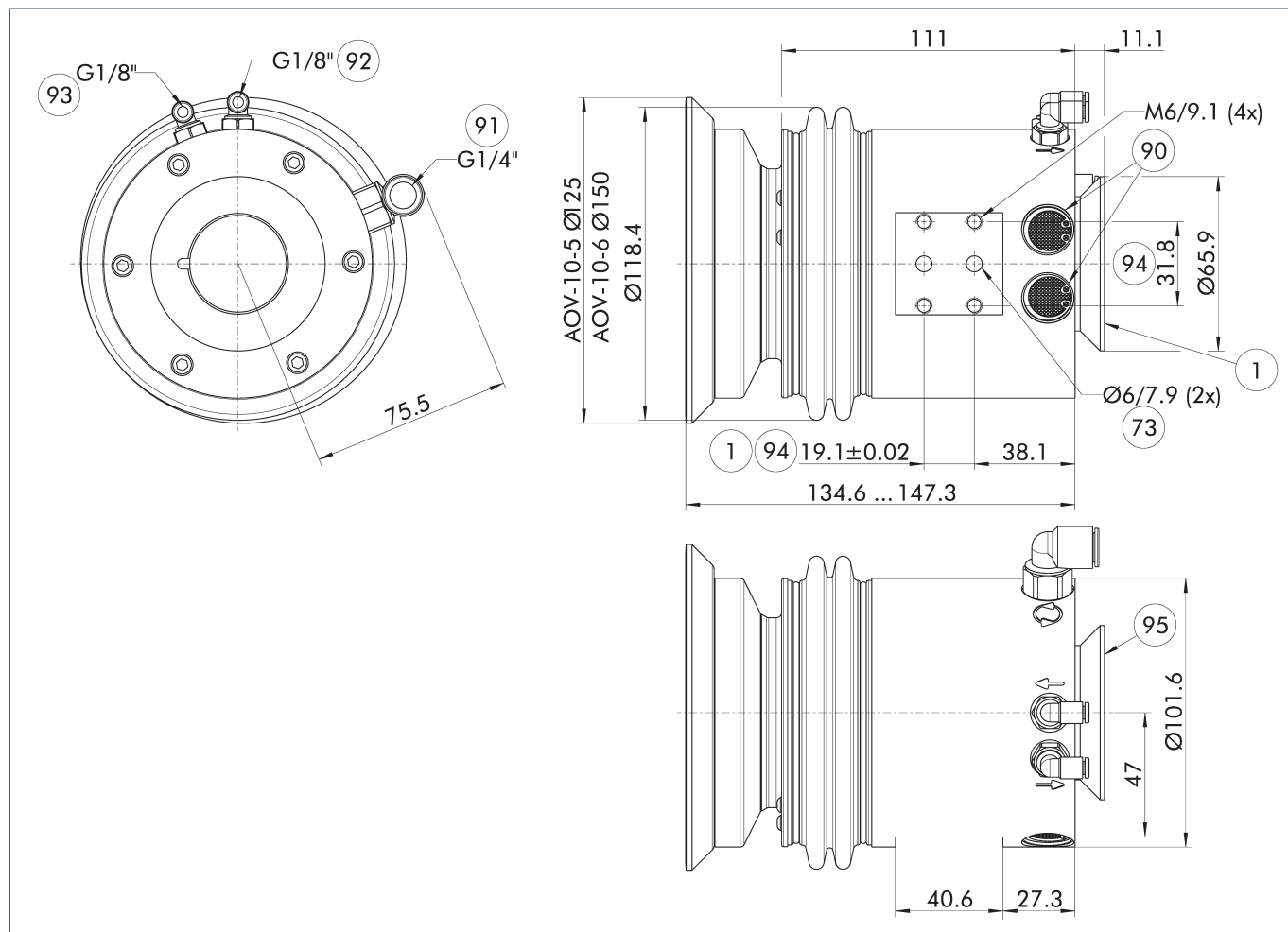
## Dimensions and maximum loads



## Technical data

| Description                              |         | AOV-10-5    | AOV-10-6    |
|--|---------|-------------|-------------|
| ID                                       |         | 1434817     | 1435146     |
| Grinding disk size                       |         | 125 mm (5") | 150 mm (6") |
| Compensation Z                           | [mm]    | 12.7        | 12.7        |
| Recommended compensation path            | [mm]    | ±5          | ±5          |
| Min./max. extension compensation force   | [N]     | 13.3/66.7   | 13.3/66.7   |
| Min./max. retraction compensation force  | [N]     | 6.7/33.3    | 6.7/33.3    |
| Min./max. compensation pressure          | [bar]   | 1/4.1       | 1/4.1       |
| Grinding stroke                          | [mm]    | 5           | 5           |
| Idle speed                               | [1/min] | 10000       | 10000       |
| Operating pressure                       | [bar]   | 6.2         | 6.2         |
| Noise emission                           | [dB(A)] | <85         | <85         |
| maximum air consumption                  | [l/s]   | 9.5         | 9.5         |
| Air connection motor                     |         | 10 mm       | 10 mm       |
| Compensation air connection              |         | 4 mm        | 4 mm        |
| Weight                                   | [kg]    | 2.68        | 2.68        |
| Min./max. ambient temperature            | [°C]    | 5/35        | 5/35        |
| Dimensions $\varnothing D \times Z$      | [mm]    | 125 x 148   | 150 x 148   |
| <b>Options and their characteristics</b> |         |             |             |
| Description                              |         | AOV-10-5-V  | AOV-10-6-V  |
| with optional connection for suction     |         | 1434818     | 1435148     |

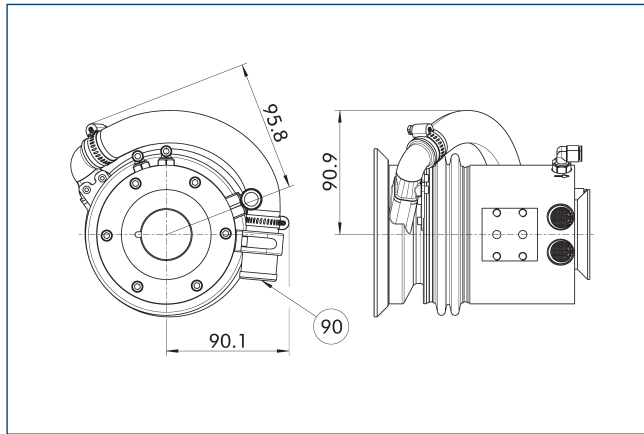
## Main view



The drawing shows the unit in the basic version.

- |   |   |
|---|---|
| ① Robot-side connection                                       | ⑨② Extend air connection compensation, hose screw connection for 4 mm hose  |
| ⑦③ Fit for centering pins                                     | ⑨③ Retract air connection compensation, hose screw connection for 4 mm hose |
| ⑨① Ventilation opening  | ⑨④ radial mounting option   |
| ⑨① Air connection motor, hose screw connection for 10 mm hose | ⑨⑤ axial mounting option  |

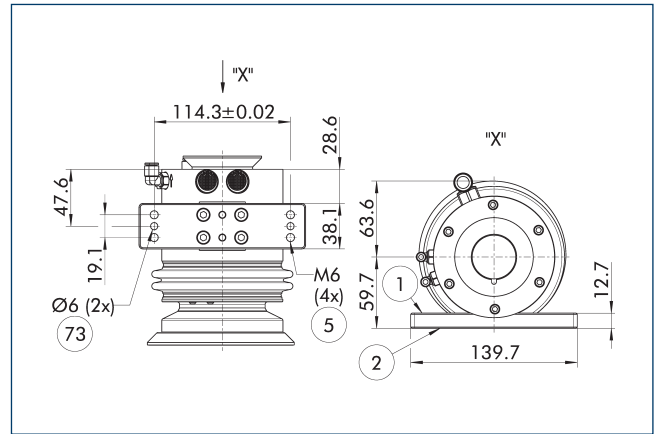
## Suction connection



⑨⑩ Vacuum connection  $\varnothing$  25.4 mm

The drawing shows the unit with the optional connection for a suction unit.

## Adapter plates, radial



① Robot-side connection

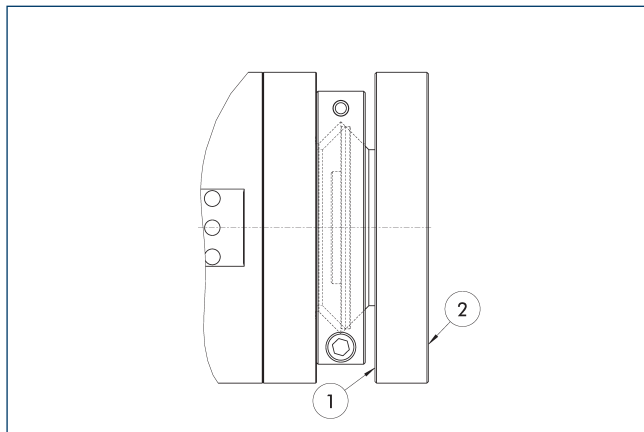
② Tool-side connection

⑤ Through hole for connection with screws

⑦③ Fit for centering pins

| Description                      | ID      |
|----------------------------------|---------|
| Adapter plate                    |         |
| A-AOV/CRT/RVC-250/490/RCE-radial | 1420116 |

## Adapter plates axial

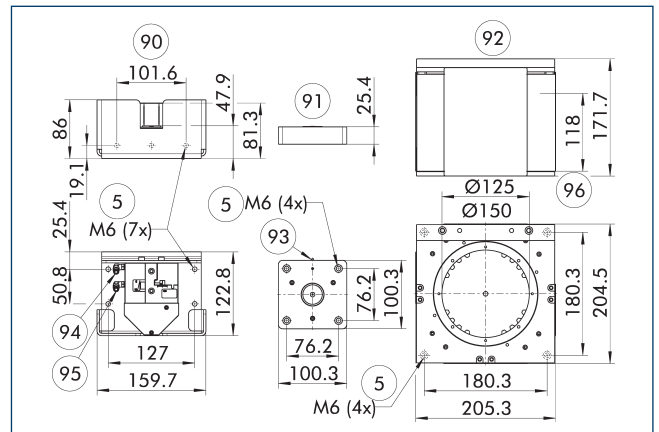


① Robot-side connection

② Tool-side connection

| Description                      | ID      |
|----------------------------------|---------|
| Adapter plate                    |         |
| A-AOV-Axial-ISO-A50              | 1453540 |
| A-FDB-660-1040/RCE-710/AOV-Axial | 0322211 |

## Automated media changer



⑤ Through hole for connection with screws

⑨⑩ Washer remover

⑨① Washer presence detector

⑨② Washer rack

⑨③ Cable outlet, proximity switch with screws

⑨④ Retract air connection needles

⑨⑤ Extend air connection needles

⑨⑥ max. media storage capacity

The drawing shows the three necessary components of the media changer.

| Description             | ID      | Disk diameter |
|-------------------------|---------|---------------|
| Automated media changer |         |               |
| AOV-MCH                 | 1460790 |               |
| AOV-MF5                 | 1460781 | 125 mm (5")   |
| AOV-MF6                 | 1460783 | 150 mm (6")   |
| AOV-MRA                 | 1460797 |               |

① All three components are necessary in order to use the media changer. These can be ordered separately and positioned individually.







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