



Superior Clamping and Gripping

# **Product data sheet**

Quick change system SWS

# Modular. Robust. Flexible. Quick-change system SWS

Pneumatic tool changing system with patented locking system

# Field of application

Can be used wherever short changeover times between a handling device and a tool (pallet, gripper)

# Advantages – Your benefits

**Complete series of 14 sizes** for optimal size selection and a broad application range

Patented fail-safe locking mechanism for secure connection between the quick-change master and adapter

Manual emergency unlocking possible no counter-forces from springs

All functional components made from hardened steel for high mechanical resilience of the changing system

Wide range of signal, pneumatic, fluid and communication modules for universal energy transmission possibilities

Integrated pneumatic feed-through for a safe power supply of the handling modules and tools

Possibility of transmission of fluid systems with self-sealing couplings possible

Adapter side coding via plug connector possible

Suitable storage racks for all sizes to ensure the optimum adaption to each application

ISO mounting pattern for easy assembly to most types of robots without needing additional adapter plates











Moment load Mx 2.8 .. 7170 Nm



Moment load Mz 3.45 .. 3800 Nm

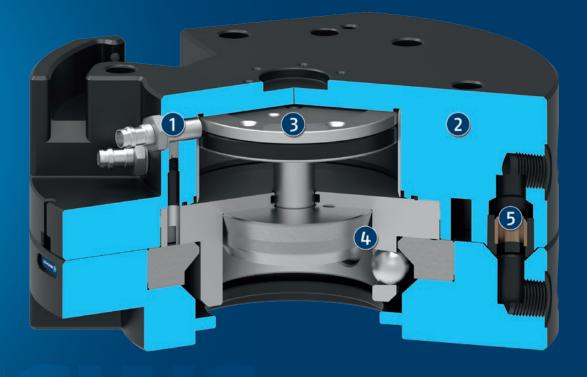
SWA 001

# **Functional description**

Automatic exchange of the end effector (e.g. gripper, pallets, vacuum gripping systems, pneumatically or electrically driven tools, welding guns, etc.) increases the flexibility of your robot.

The quick-change system (SWS) consists of a quick-change master (SWK) and a quick-change adapter (SWA). The SWK

is mounted onto the robot, and couples the SWA mounted onto your tool. A pneumatically driven locking piston, with its patented design, ensures that the connection is secure. After coupling, pneumatic and electric feedthroughs automatically supply your robot tool.



- Sensor monitoring of the locking device optional, for process-reliable monitoring of the locking condition
- **2** Housing

is weight-optimized due to the use of high-strength aluminum alloy

- ③ **Drive** pneumatic, efficient, and easy to handle
- Locking mechanism
   load-free locking and unlocking, fail-safe in locked
   condition
- (5) Air feed-through without interfering contours due to the integration into the housing. Also suitable for vacuum.

# **Detailed functional description**

# Sectional diagram SWS-001



- Drive pneumatic, efficient, and easy to handle
- Locking mechanism
   load-free locking and unlocking,
   fail-safe in locked condition
- Housing is weight-optimized due to the use of high-strength aluminum alloy
- Centering and mounting possibilities by using a standardized ISO 9409 interface for robots
- Electric feed-through no interfering contour, as integrated in the housing
- Air feed-through without interfering contours due to the integration into the housing. Also suitable for vacuum.

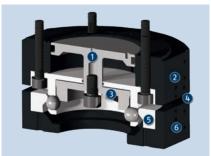
# Quick-change system in unlocked position



- Adapter plate
- Quick-change master SWK
- 3 Electrical module, robot-side
- 4 Locking mechanism

- **5** Locking ring
- **6** Quick-change adapter SWA
- Electrical module, tool-side

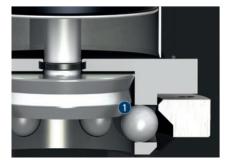
# Section view in ready-to-lock position



- Piston
- Quick-change master SWK
- Ocking piston

- ④ No-Touch-Locking™
- 6 Locking ring
- **6** Quick-change adapter SWA

# Detail view of the locking ball position in ready-to-lock position



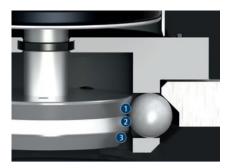
 Hardened locking ball is on the 1st taper of the cam. The 1st taper allow head and tool to be separate while locking.

# Section view of the quick-change system in locked position



When the piston is actuated, the locking balls are pushed under the hardened steel ring and the adapter is pulled onto the head.

# Detail view of the locking ball in locked position



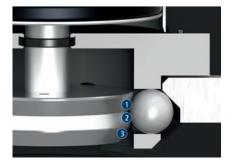
- Hardened steel balls on the 2nd taper of the cam create extremely high locking forces.
- **2** Fail-safe reverse taper
- **3** 1st taper of the cam

# Section view of the quick-change system in fail-safe position



The master and the adapter can only be separated from one another in the self-locking status if the piston is pneumatically actuated with the unlock air pressure.

# Detail view of locking ball while in fail-safe position



- In the case of pressure loss, the locking piston is held in place by the cylindrical part of the locking piston. The friction from the piston seal prevents the piston from moving from its own weight or vibrations. The head and adapter can only be separated by pneumatic actuation of the piston.
- 2 Fail-safe reverse taper
- **3** 1st taper of the cam

# General notes about the series

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

**Operating principle:** locking balls actuated by pistons for locking

Media transmission: variable via attachment feedthrough modules, depending on the unit size

**Housing:** The housing consists of high-strength, hardcoated aluminum alloy. The functional components are made of hardened steel.

Warranty: 24 months

Service life characteristics: on request

Harsh environmental conditions: Please note that use under harsh environmental conditions (e.g. in the coolant area, cast and grinding dust) can considerably reduce the service life of the units, and we will not take over any warranty. However, in many cases we can find a solution. Please contact us for assistance.

Handling weight: is the weight of the total load attached to the flange. When designing, the permissible forces and moments have to be paid attention to. Please note that exceeding the recommended handling weight will shorten the lifespan.

# **Application example**

Insertion tool for assembly of small to medium-sized workpieces. The tool can be used in both clean and dirty environments. Due to its quick-change system, other tools can alternately be fixed to the robot flange.

- Quick-change system SWS
- 2 Electric feed-through
- **3** Tolerance compensation unit TCU-Z
- 3-finger centric gripper PZN-plus



#### SCHURC offers more ... The following components make the product even more productive - the suitable addition for the ightest functionality, flexibility, reliability, and corrections Formersation unit Formersation un

 $\oplus\;$  For more information on these products can be found on the following product pages or at schunk.com.

# **Options and special information**

**No-Touch-Locking™:** Locking without touching. Ensures that the SWS is securely locked even when the SWK and SWA do not touch.

**Patented fail-safe locking mechanism:** A large piston diameter and an outside clamping locking increase the permissible moment capacity. Steel parts made of low corrosion Rc 58.

# Selection of a quick-change system SWS

# 1. Determining the size

# **Quick Method:**

When low or medium forces and moments act upon the SCHUNK quick-change system, you should choose a quick-change system with a payload comparable to that of your robot. If high moments and forces act upon the SCHUNK quick-change system, please use the following method, which is more precise.

# More precise Method:

Forces and moments are critical factors in choosing a suitable quick-change system. Proceed as follows to estimate the most unfavorable moment:

- Calculate the approximate center of gravity (COG) of the heaviest end-effector that will be used. Calculate the distance (D) from the COG to the bottom of the quick-change adapter.
- Calculate the weight (W) of the heaviest end-effector.
- Multiply W and D to find an approximate static moment (M) (or a moment based on 1 g of acceleration).
- Choose a quick-change system with a high moment load equal to or greater than M.
- Due to their potentially high accelerations, robots can produce moments that are two or three times as high as M.

# 2. Pneumatic and electrical systems

Determine the number of pneumatic connections and electrical contacts required. Larger quick-change systems feature a higher number of pneumatic connections and electrical contacts.

# 3. Temperature and chemicals

SCHUNK quick-change systems use nitrile gaskets for the feed-through of pneumatics. O-rings seal the pneumatic locking mechanism. These O-rings are resistant to most chemical influences and also withstand temperatures ranging from -25 to +65 °C. Please contact us if you should need information on temperatures or chemical influences in particular environments.

# 4. Precision applications

Always comply with the specifications if you work with applications that require high repeat accuracy.

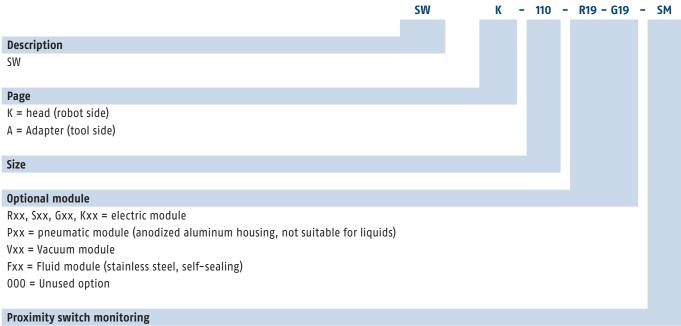
Please note:

A quick-change system has an influence on force and moment, payload, size, and repeat accuracy of the robot.

# **SWS Sizes**

Description	Recommended handling weight [kg]	Max. moment [Nm] $M_{\rm x}$ and $M_{\rm y}$	Max. moment [Nm] M <sub>z</sub>	Pneumatic feed-through	Air connections locked and unlocked
SWS 001	1.4	2.8	3.45	4x M5	M3
SWS 007	16	61	38	5x M5	M5
SWS 011	16	61	38	6x M5	M5
SWS 020	25	169.5	105	12x M5	M5
SWS 021	25	169.5	105	8x G1/8"	M5
SWS 029	35	169.5	230	2x G1/8"; 4x M5	M5
SWS 040Q	50	471	648	8x G1/8"	G1/8"
SWS 041	50	471	648	6x G3/8"; 4x G1/8"	G1/8"
SWS 046	50	678	450	-	G1/8"
SWS 060	75	591	326	8x G1/8"	G1/8"
SWS 071	79	1185	378	8x G1/4"	G1/8"
SWS 076	100	1626	2103	5x G3/8"	G1/8"
SWS 110	150	2352	2352	8x G3/8"	G1/8"
SWS 160	300	7170	3800	5x G3/8"; 4xG1/2"	G1/8"
SWS-L 210	300	7600	4060	-	-
SWS-L 310	510	9900	9600	-	-
SWS-L 510	700	10900	10500	-	-
SWS-L 1210	1350	13500	16200	-	-

# **Ordering example SWS**



SG = Inductive proximity switch (SWK-040Q/076)

SM = inductive proximity switch (SWK-007/022/029/110/160)

SQ = Inductive proximity switch (SWK-011H/020H/021H)

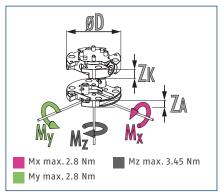
SIP-IN = monitoring prepared, inductive proximity switch included (SWK-011/020/021/027/041/046/060/071)

More versions on request





#### Dimensions and maximum loads



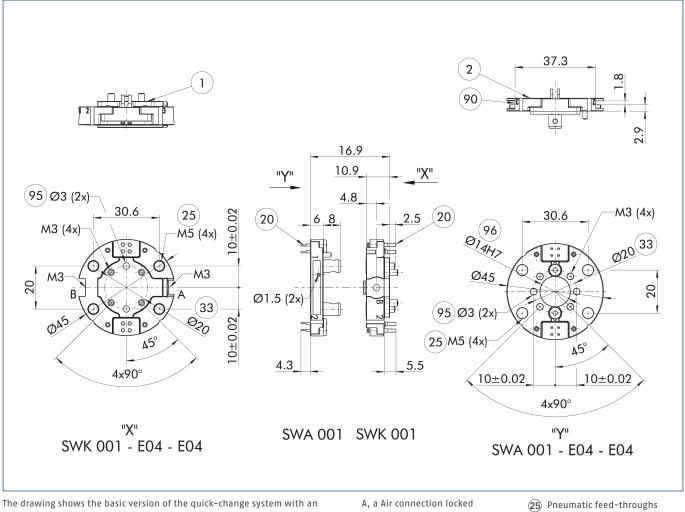
① This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

Description		SWK-001-000-000	SWA-001-000-000	SWK-001-E04-E04	SWA-001-E04-E04
		Quick-change master	Quick-change adapter	Quick-change master	Quick-change adapter
ID		0302290	0302291	0302292	0302293
Recommended handling weight	[kg]	1.4	1.4	1.4	1.4
Locking force	[N]	170	170	170	170
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01
Weight	[kg]	0.03	0.02	0.08	0.04
Max. distance when locking	[mm]	1	1	1	1
Air connection thread pneumatic feed-through		4x M5	4x M5	4x M5	4x M5
Lock/unlock main connection		M3		M3	
Number of electrical feed-throughs				8	8
Voltage	[V]			50	50
Max. current	[A]			3	3
Max. permissible XY axis offset	[mm]	±0.3	±0.3	±0.3	±0.3
Max. permissible angular offset	[°]	±0.8	±0.8	±0.8	±0.8
Min./max. ambient temperature	[°C]	5/60	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	45 x 10.9	45 x 6	45 x 10.9	45 x 6
Screw connection diagram		S1	S1	S1	S1

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

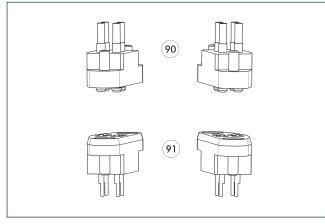
### Main view



electrical optional module.

- B, b Air connection unlocked
- $\bigcirc 1$  Robot-side connection
- (2) Tool-side connection
- (20) Connection for electric feed-through
- 33 DIN ISO-9409 bolt circle
- (90) Groove for tool rack
- 95 Fit for centering pins
- (96) Fit for centering

### Electric feed-through module



90 Robot side

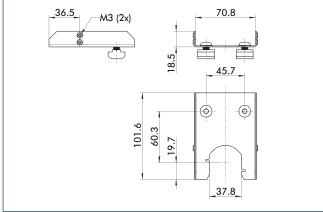
(91) Tool side

Modules for transmission of electrical signals.

Description	ID	No. Pins
Feed-through module	e for signal on	the robot side
SWO-EO4-K	9960359	4
SW0-E06-K	9962997	6
Feed-through module	e for signal on	the tool side
SWO-E04-A	9960360	4
SWO-E06-A	9962998	6

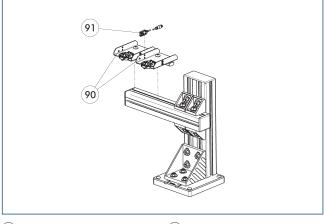
Tor more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.

#### SWS 001 Storage Plate



① Mounting grooves are not included in the scope of delivery.

### Modular SWM-S-001 quick-change rack



90 Storage plate

(91) Sensor

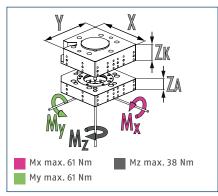
The modular storage rack is designed for the specific size. The system's modular design allows you to compile your individual storage rack. This provides you with a storage rack that meets your individual requirements, taking into account the number of tools, deposition positions, and tool size. For further information please refer to the chapter "SWM storage rack"

Description	ID
Storage plate	
SWM-TSS-MM-7869	0303276
Sensor	
SWM-SMA-7869	0303277





#### Dimensions and maximum loads



This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

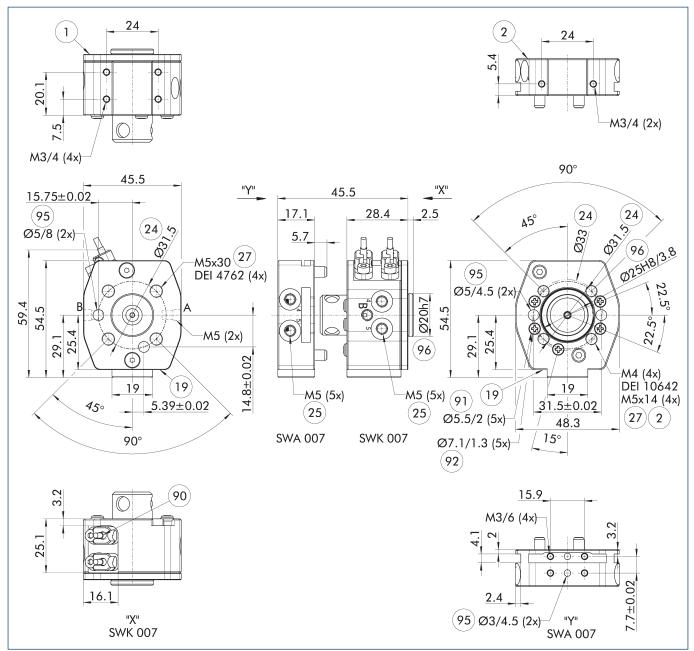
# **Technical data**

Description		SWK-007-000-000-IN03	SWA-007-000-000
		Quick-change master	Quick-change adapter
ID		1405836	1365513
Recommended handling weight	[kg]	16	16
Piston stroke monitoring		integrated	
Locking force	[N]	1100	1100
Repeat accuracy	[mm]	0.015	0.015
Weight	[kg]	0.16	0.08
Max. distance when locking	[mm]	1.5	1.5
Air connection thread pneumatic feed-through		5x M5	5x M5
Lock/unlock main connection		M5	
Max. permissible XY axis offset	[mm]	±1	±1
Max. permissible angular offset	[°]	±2	±2
Robot-side connection		ISO 9409-1-31.5-4-M5	ISO 9409-1-31.5-4-M5
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9
Dimensions X x Y x Z*	[mm]	54.5 x 45.5 x 28.4	54.5 x 48.3 x 17.1
Screw connection diagram		S7	S7

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

# SWS 007 Quick change system

### Main view

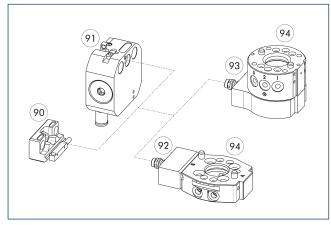


The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

A, a Air connection locked

- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (19) Mounting surface for options
- 24 Bolt circle
- (25) Pneumatic feed-throughs
- (27) Through holes for screw connections(90) Sensor IN ...
- (91) Axial air connection (supplied with locking screw)
- (92) Bore hole for sealing ring (back)
- 95) Fit for centering pins
- 96 Fit for centering

#### Storage system SWM-B



- (90) SWM-B 050
- (93) Intermediate plate
- (91) SWM-B 050-V

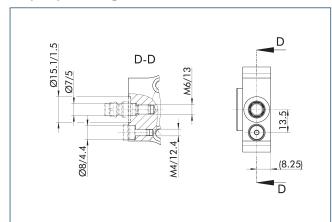
(92) Side plate

94 Quick-change adapter SWA

Storage system with (-V) and without locking for safe tool storage. Detailed information and further accessories can be found in the catalog chapter "SWM-B" and "SWM.".

Description	ID	
Storage system		
SWM-B 050	1459336	
SWM-B 050-V	1442568	

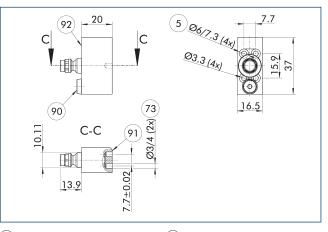
#### Adapter plate design SWM-B



Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

Description	ID	Suitable for
Adapter plates		
A-SWA-007-SWM-B 050	1523812	SWA 007
A-SWA-007-SWM-B 050-V	1523842	SWA 007

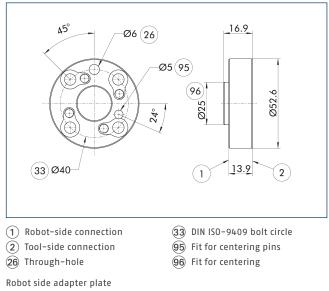
### Adapter plate SWA 007



- (5) Through hole for connection with screws
- (73) Fit for centering pins
- (9) Anti-rotation protection (only for the SWM-B -V adapter plate)
  (91) Mounting side SWA
  (92) Attachment side SWM-B (-V)

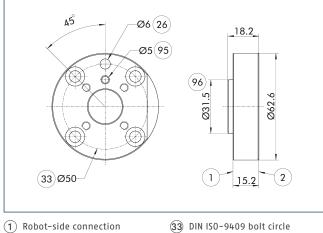
Description	ID	Suitable for
Adapter plates		
A-SWA-007-SWM-B 050	1523812	SWA 007
A-SWA-007-SWM-B 050-V	1523842	SWA 007

### Adapter plate ISO-A40-R



Description	ID
Robot side	
A-SWK-007-IS0-A40	1369388

# Adapter plate ISO-A50-R



- 3 DIN ISO-9409 bolt circle
- (2) Tool-side connection

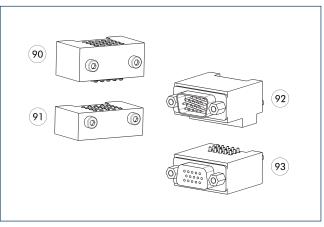
95 Fit for centering pins 96 Fit for centering

#### Robot side adapter plate

26 Through-hole

Description	ID
Robot side	
A-SWK-007-IS0-A50	1369392

# Electric feed-through module



90 E..., robot-side 91) E..., tool-side

92 A.../B... robot-side

93 A.../B... tool-side

Modules for transmission of electrical signals.

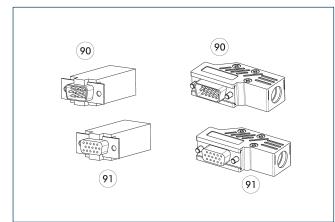
Description	ID	No. Pins
Feed-through mod	dule for signal	on the robot side
SW0-A15-K	9936357	15
SW0-E10-011-K	9935801	10
SW0-E20-011-K	9936525	20
SW0-EM8-011-K	9966153	8
SWO-ML12R-K	1426575	12
SWO-ML8A-K	1426624	8
Feed-through mod	dule for signal	on the tool side
SWO-A15-A	9936356	15
SW0-E10-011-A	9935802	10
SW0-E20-011-A	9936526	20
SW0-EM8-011-A	9966154	8
SWO-ML12R-A	1426576	12
SWO-ML6-A	1426626	6
SWO-ML8A-A	1426625	8

() For more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.

# SWS 007

Quick change system

#### **Cable connector**



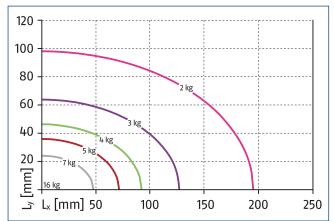
90 D-sub connecting plug

(91) D-sub connector

Decemination:	ID
Description	ID
Angled cable connector, re	obot-side
KAS-A15-K-90	0301301
Angled cable connector, to	ool-side
KAS-A15-A-90	0301302
Straight cable connector,	robot-side
KAS-A15-K-O	0301264
Straight cable connector, t	tool-side
KAS-A15-A-0	0301265
Cable extension	
KV-2-SWA-08G-M8-0	0302181
KV-2-SWA-08G-M8-90	0302183
KV-5-SWK-08G-M8-0	0302180
KV-5-SWK-08G-M8-90	0302182

Detailed information and further cable connectors can be found at schunk.com

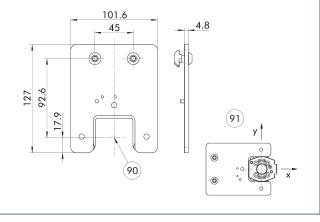
### Load diagram with storage rack



If the center of gravity of the tool is offset by more than 10 mm in the x or y direction (see storage tray drawing), the SWA will tilt after being set down in the storage module. The use of this storage tray in applications with SCARA robots or Cartesian robots is not recommended in this case.

Tooling plate, horizontal SWM-TSS-MMS-11345 1459976	Description	ID
SWM-TSS-MMS-11345 1459976	Tooling plate, horizontal	
	SWM-TSS-MMS-11345	1459976

# Tooling plate, horizontal



(90) Center SWS 007 (reference point for load diagram)

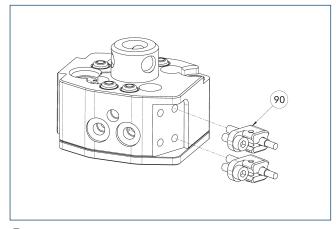
(91) View center of gravity offset in x or y direction

The storage stand serves as a storage rack for the quick-change adapter with tools which are mounted by the customer himself.

Description	ID		
Tooling plate, horizontal			
SWM-TSS-MMS-11345	1459976		

① When using the storage rack, the load diagram must be observed.

### Assembly situation of the locking monitoring



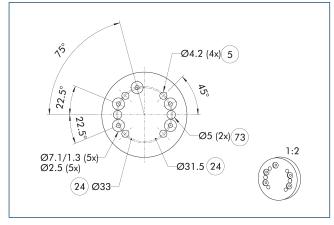
(90) AS-SWK 007

The drawing shows the installation situation of the integrated piston stroke monitoring with built-in proximity switch on the quick-change master.

Description	ID	
Robot side		
AS-SWK-007-SM Attachment kit including PNP sensor	1421347	
AS-SWK-007-SP attachment kit including NPN sensor	1428672	

The -SG/-SM/-SQ/-IN variants of the SWK include the piston stroke monitoring option. An additional order of the mounting kit is not necessary. The scope of delivery of a mounting kit contains one preset sensor with holder each, meaning that two mounting kits are required per SWK.

# Design of an adapter plate for using the axial air feed-through



- (5) Through hole for connection with screws
- (24) Bolt circle(73) Fit for centering pins

The adapter plate serves as an interface between the quick-change adapter and the tool of the customer. To ensure correct use of the axial air feed-throughs, the counterbores shown in the drawing must be taken into account when designing the adapter plate. The appropriate seals are included in the accessory kit.

23



#### **Dimensions and maximum loads**



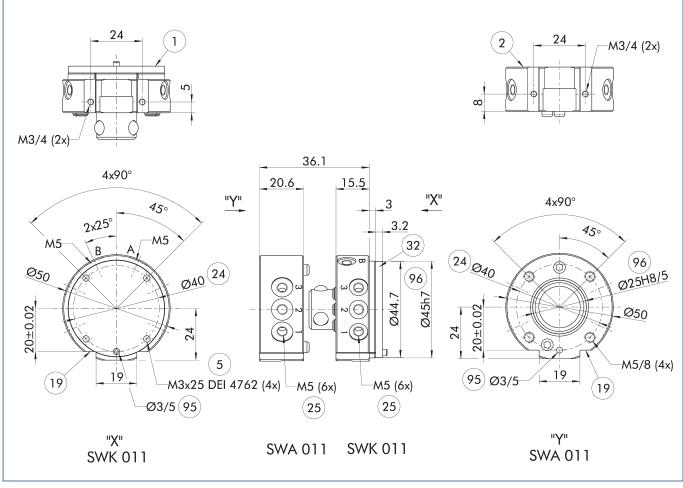
This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

Description		SWK-011-000-000	SWK-011HM-000-000-SQ	SWA-011-000-000
		Quick-change master	Quick-Change master for hollow wrist robots	Quick-change adapter
ID		0302316		0302317
Recommended handling weight	[kg]	16	16	16
Piston stroke monitoring		optional	integrated	
Locking force	[N]	1100	1100	1100
Repeat accuracy	[mm]	0.015	0.015	0.015
Weight	[kg]	0.13	0.29	0.09
Max. distance when locking	[mm]	1.5	1.5	1.5
Air connection thread pneumatic feed-through		6x M5	6x M5	6x M5
Lock/unlock main connection		М5	М5	
Max. permissible XY axis offset	[mm]	±1	±1	±1
Max. permissible angular offset	[°]	±2	±2	±2
Min./max. ambient temperature	[°C]	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	50 x 15.5	50 x 46.4	50 x 20.6
Screw connection diagram		S7	S7	S7

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

#### Main view



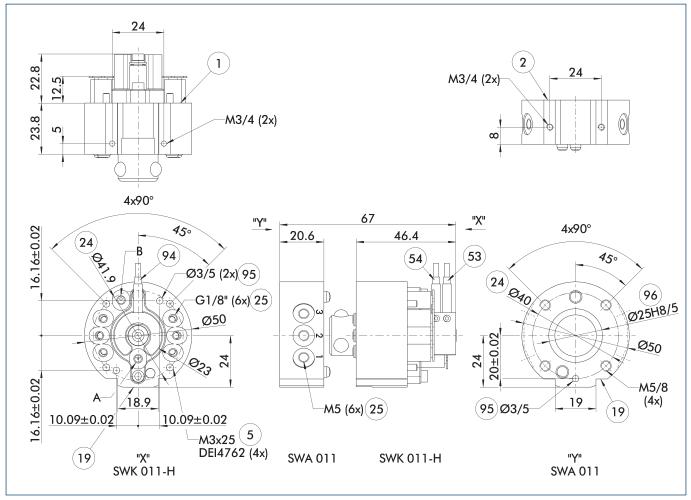
The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

- The robot-side plate mounted on the SWK is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate.
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24 Bolt circle
- (25) Pneumatic feed-throughs
- 32 Cover
- (95) Fit for centering pins
- (96) Fit for centering

# SWS 011

Quick change system

### SWK-011-H main view



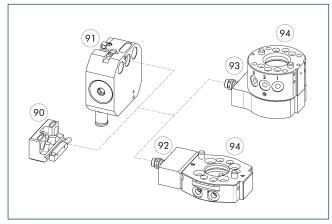
Via axial air connections it is perfectly suited for robots with through bores.

- A, a Air connection locked
- B, b Air connection unlocked
- $\bigcirc$  **1** Robot-side connection
- (2) Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options

- (25) Pneumatic feed-throughs
- (53) Monitoring Position unlocked
- 54 Monitoring Position locked
- (94) Optional proximity switch
- 95 Fit for centering pins
- 96 Fit for centering

<sup>(24)</sup> Bolt circle

#### Storage system SWM-B



(90) SWM-B 050

(93) Intermediate plate

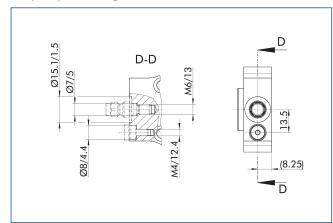
(91) SWM-B 050-V

- (92) Side plate
- (94) Quick-change adapter SWA

Storage system with (-V) and without locking for safe tool storage. Detailed information and further accessories can be found in the catalog chapter "SWM-B" and "SWM.".

Description	ID	
Storage system		
SWM-B 050	1459336	
SWM-B 050-V	1442568	

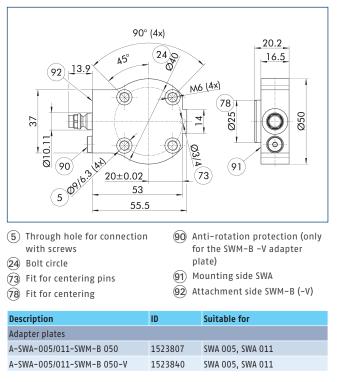
#### Adapter plate design SWM-B



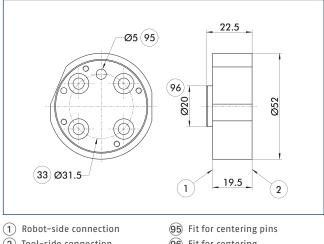
Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

Description	ID	Suitable for
Adapter plates		
A-SWA-005/011-SWM-B 050	1523807	SWA 005, SWA 011
A-SWA-005/011-SWM-B 050-V	1523840	SWA 005, SWA 011

#### Adapter plate SWA 005/011



### Adapter plate ISO-A31.5-R



- (2) Tool-side connection
- (33) DIN ISO-9409 bolt circle

Robot side adapter plate

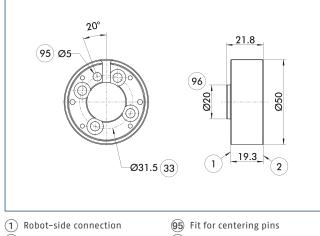
(96) Fit for centering

Description	ID	
Robot side		
A-SWK-011-IS0-A31.5	0302221	

① Adapter plate for quick-change master without piston stroke control, not suitable on quick-change head for hollow wrist robots.

Quick change system

### Adapter plate ISO-A31.5-SIP-R



- (2) Tool-side connection
- (33) DIN ISO-9409 bolt circle

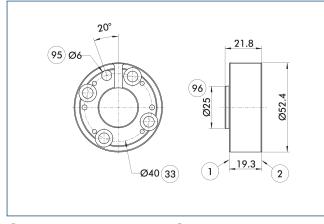
(96) Fit for centering

#### Robot side adapter plate

Description	ID	
Robot side		
A-SWK-011-ISO-A31.5-SIP	0302226	

() Adapter plate for quick-change master with piston stroke control, not suitable on quick-change head for hollow wrist robots.

# Adapter plate ISO-A40-SIP-R



(1) Robot-side connection

(95) Fit for centering pins 96 Fit for centering

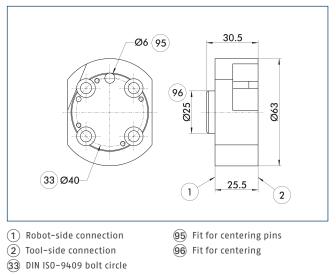
 $(\mathbf{2})$  Tool-side connection (33) DIN ISO-9409 bolt circle

Robot side adapter plate

Description	ID
Robot side	
A-SWK-011-ISO-A40-SIP	0302227

① Adapter plate for quick-change master with piston stroke control, not suitable on quick-change head for hollow wrist robots.

### Adapter plate ISO-A40-R

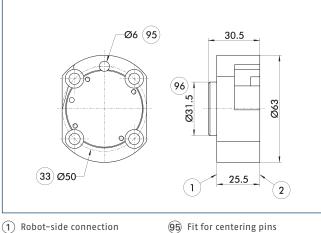


Robot side adapter plate

Description	ID
Robot side	
	0202222
A-SWK-011-IS0-A40	0302222

① Adapter plate for quick-change master without piston stroke control, not suitable on quick-change head for hollow wrist robots.

### Adapter plate ISO-A50-R

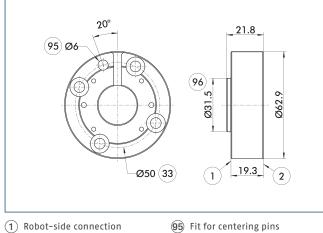


- (2) Tool-side connection
- (95) Fit for centering pins (96) Fit for centering
- 3 DIN ISO-9409 bolt circle

Description	ID
Robot side	
A-SWK-011-IS0-A50	0302223

① Adapter plate for quick-change master without piston stroke control, not suitable on quick-change head for hollow wrist robots.

# Adapter plate ISO-A50-SIP-R



- 2 Tool-side connection 3 DIN ISO-9409 bolt circle

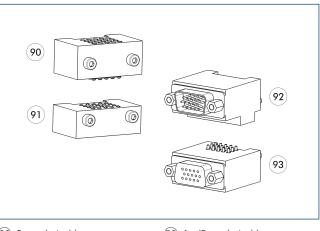
96 Fit for centering

#### Robot side adapter plate

Description	ID
Robot side	
A-SWK-011-ISO-A50-SIP	0302228

 Adapter plate for quick-change master with piston stroke control, not suitable on quick-change head for hollow wrist robots.

### Electric feed-through module



90 E..., robot-side 91) E..., tool-side

(92) A.../B... robot-side 93 A.../B... tool-side

Modules for transmission of electrical signals.

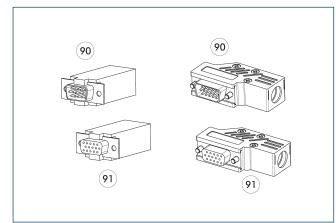
Description	ID	No. Pins		
Feed-through mod	lule for signal	on the robot side		
SWO-A15-K	9936357	15		
SW0-E10-011-K	9935801	10		
SW0-E20-011-K	9936525	20		
SW0-EM8-011-K	9966153	8		
SWO-ML8A-K	1426624	8		
Feed-through module for signal on the tool side				
SWO-A15-A	9936356	15		
SW0-E10-011-A	9935802	10		
SW0-E20-011-A	9936526	20		
SW0-EM8-011-A	9966154	8		
SWO-ML6-A	1426626	6		
SWO-ML8A-A	1426625	8		

() For more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.

# SWS 011

Quick change system

# **Cable connector**



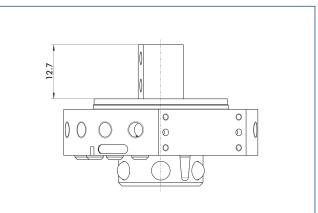
90 D-sub connecting plug

(91) D-sub connector

- · ·	
Description	ID
Angled cable connector, re	obot-side
KAS-A15-K-90	0301301
Angled cable connector, to	ool-side
KAS-A15-A-90	0301302
Straight cable connector,	robot-side
KAS-A15-K-O	0301264
Straight cable connector,	tool-side
KAS-A15-A-0	0301265
Cable extension	
KV-2-SWA-08G-M8-0	0302181
KV-2-SWA-08G-M8-90	0302183
KV-5-SWK-08G-M8-0	0302180
KV-5-SWK-08G-M8-90	0302182

 $\ensuremath{\textcircled{}}$  Detailed information and further cable connectors can be found at schunk.com

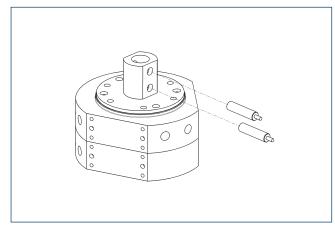
# Piston stroke control



The drawing shows the minimal height of the adapter plate for installing a piston stroke control.

Description	ID
Piston stroke co	ontrol
SWK-011-SIP	0302318

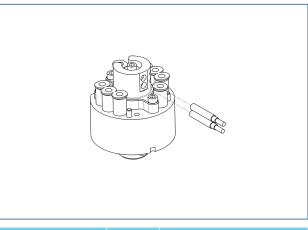
### **Piston stroke control**



Description	ID	Often combined
Inductive proximity switch		
IN 41-S-M8-PNP	1325755	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	

Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

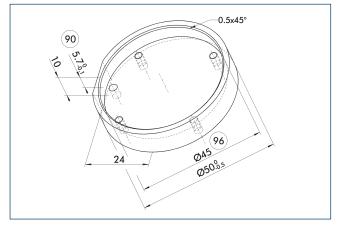
# Piston stroke monitoring for SWK-011-H



Description	ID	Often combined
Inductive proximity switch		
IN 41-S-M8-PNP	1325755	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	

 Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available.
 Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

## Adapter plate design

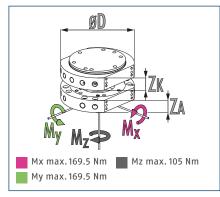


(90) Recommended adapter plate (96) Fit for centering depth

Recommendation for the design of the adapter plate.



#### **Dimensions and maximum loads**



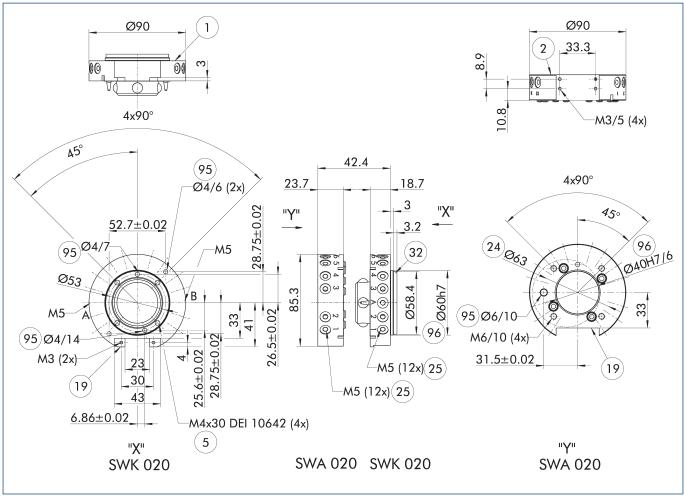
① This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

Description		SWK-020-000-000	SWK-020HM-000-000-SQ	SWA-020-000-000
		Quick-change master	Quick-Change master for hollow wrist robots	Quick-change adapter
ID		0302322		0302323
Recommended handling weight	[kg]	25	25	25
Piston stroke monitoring		optional	integrated	
Locking force	[N]	2300	2300	2300
Repeat accuracy	[mm]	0.015	0.015	0.015
Weight	[kg]	0.54	0.68	0.32
Max. distance when locking	[mm]	2	2	2
Air connection thread pneumatic feed-through		12x M5	12x M5	12x M5
Lock/unlock main connection		М5	M5	
Max. permissible XY axis offset	[mm]	±1	±1	±1
Max. permissible angular offset	[°]	±2	±2	±2
Min./max. ambient temperature	[°C]	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	90 x 18.7	90 x 46	90 x 23.7
Screw connection diagram		К	К	К

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

### Main view



The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

The robot-side plate mounted on the SWK is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate. A, a Air connection locked

- B, b Air connection unlocked
- $\underbrace{1}$  Robot-side connection

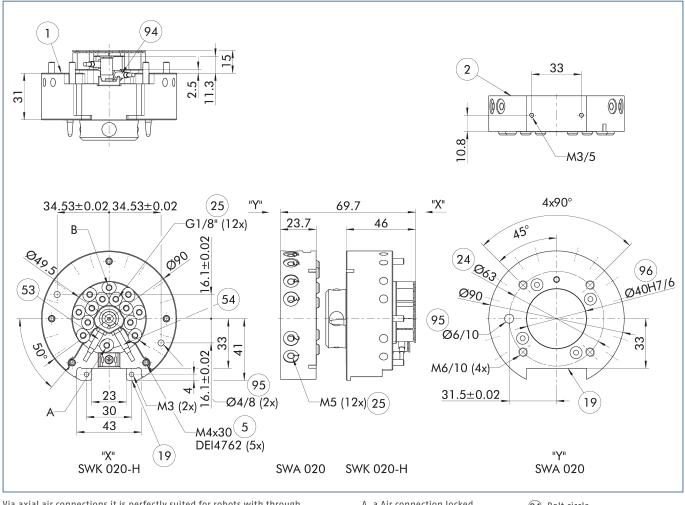
with screws

- Tool-side connection
   Through hole for connection
  - 96 Fit fo
- 19 Mounting surface for options
- 24 Bolt circle
- (25) Pneumatic feed-throughs
- 32 Cover
- (95) Fit for centering pins
  - (96) Fit for centering

# **SWS 020**

Quick change system

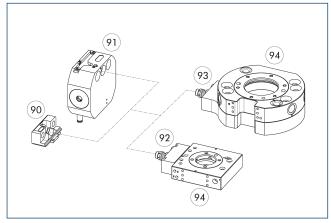
### SWK-020-H main view



Via axial air connections it is perfectly suited for robots with through bores.

- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- $(\mathbf{5})$  Through hole for connection with screws
- (19) Mounting surface for options
- (24) Bolt circle
- (25) Pneumatic feed-throughs
- (53) Monitoring Position unlocked
- (54) Monitoring Position locked
- (94) Optional proximity switch
- (95) Fit for centering pins
- (96) Fit for centering

#### Storage system SWM-B



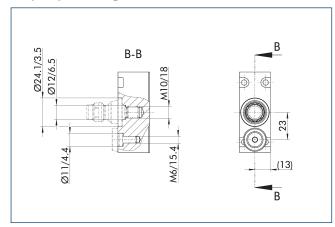
(90) SWM-B 085

- (93) Intermediate plate
- (91) SWM-B 085-V (92) Side plate
- (94) Quick-change adapter SWA

Storage system with (-V) and without locking for safe tool storage. Detailed information and further accessories can be found in the catalog chapter "SWM-B" and "SWM.".

Description	ID	
Storage system		
SWM-B 085	1459339	
SWM-B 085-V	1442590	

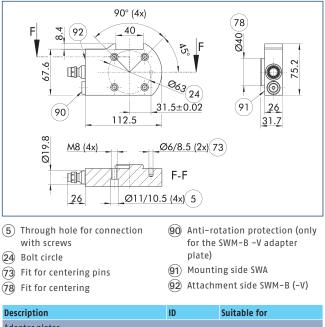
#### Adapter plate design SWM-B



Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

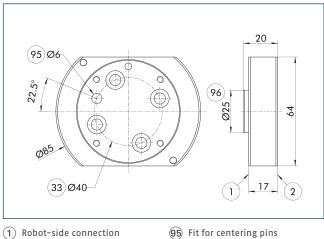
Description	ID	Suitable for
Adapter plates		
A-SWA-020/021/022-SWM-B 085	1523816	SWA 020/021/022
A-SWA-020/021/022-SWM-B 085-V	1523845	SWA 020/021/022

#### Adapter plate SWA 020/021/022



Adapter plates		
A-SWA-020/021/022-SWM-B 085	1523816	SWA 020/021/022
A-SWA-020/021/022-SWM-B 085-V	1523845	SWA 020/021/022

#### Adapter plate ISO-A40-R



- (1) Robot-side connection
- (2) Tool-side connection
- (33) DIN ISO-9409 bolt circle

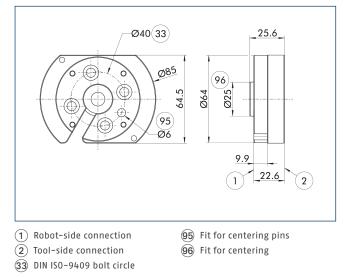
Robot side adapter plate

Description	ID
Robot side	
A-SWK-020/021-IS0-A40	0302200

(96) Fit for centering

① Adapter plate for quick-change master without piston stroke control, not suitable on quick-change head for hollow wrist robots.

## Adapter plate ISO-A40-SIP-R

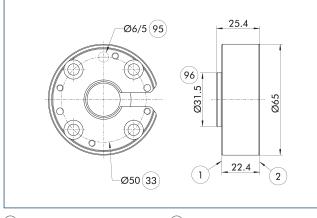


#### Robot side adapter plate

Description	ID	
Robot side		
A-SWK-020/021-IS0-A40-SIP	0302229	

 $\textcircled$  Adapter plate for quick-change master with piston stroke control, not suitable on quick-change head for hollow wrist robots.

## Adapter plate ISO-A50-SIP-R

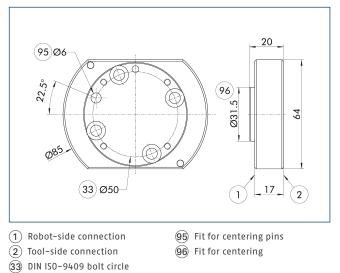


- $\bigcirc$  **1** Robot-side connection
- (95) Fit for centering pins(96) Fit for centering
- (2) Tool-side connection(33) DIN ISO-9409 bolt circle
- Robot side adapter plate

Description	ID	
Robot side		
A-SWK-020/021-IS0-A50-SIP	0302230	

① Adapter plate for quick-change master with piston stroke control, not suitable on quick-change head for hollow wrist robots.

#### Adapter plate ISO-A50-R

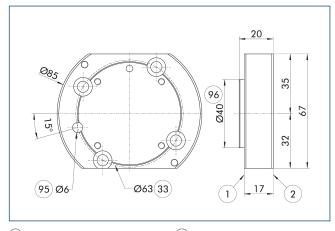


Robot side adapter plate

Description	ID		
Robot side			
A-SWK-020/021-IS0-A50	0302201		

① Adapter plate for quick-change master without piston stroke control, not suitable on quick-change head for hollow wrist robots.

#### Adapter plate ISO-A63-R



- 1 Robot-side connection
- 2 Tool-side connection
- (33) DIN ISO-9409 bolt circle

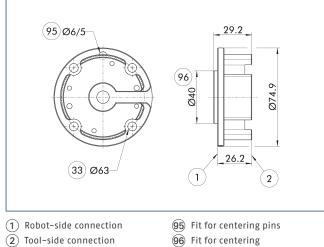
(95) Fit for centering pins(96) Fit for centering

Robot side adapter plate

Description	ID
Robot side	
A-SWK-020/021-IS0-A63	0302202

① Adapter plate for quick-change master without piston stroke control, not suitable on quick-change head for hollow wrist robots.

# Adapter plate ISO-A63-SIP-R



# 96 Fit for centering

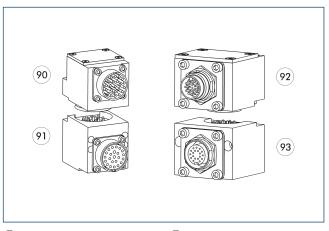
3 DIN ISO-9409 bolt circle

#### Robot side adapter plate

ID	
0302231	

 Adapter plate for quick-change master with piston stroke control, not suitable on quick-change head for hollow wrist robots.

#### Electric feed-through module



90 Electric module with bayonet fitting, robot-side (91) Electric module with bayonet

fitting, tool-side

(92) Electric module with metric thread, robot-side (93) Electric module with metric thread, tool-side

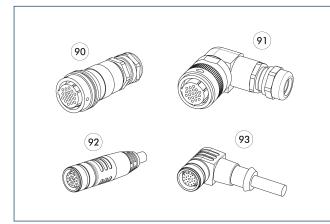
Modules for transmission of electrical signals.

Description	ID	No. Pins
Feed-through module	e for communi	ication on the robot side
SWO-KE7-K	9960993	
Feed-through module	e for communi	ication on the tool side
SWO-KE7-A	9960994	
Feed-through module	e for signal on	the robot side
SW0-K12-K	9948701	12
SW0-K19-K	9937328	19
SWO-K19P-K	9949315	15
SW0-K26-K	9937798	26
SWO-KF19-K	9959886	19
Feed-through module	e for signal on	the tool side
SWO-K12-A	9948702	12
SW0-K19-A	9937329	19
SWO-K26-A	9937799	26
SWO-KF19-A	9959887	19

() For more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.



# Cable plug/cable extension



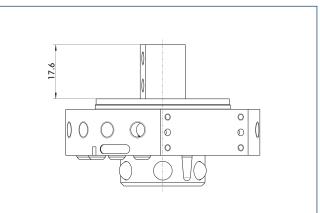
- 90 Plug/socket straight
- (91) Connector/angled socket
- (92) Connector/straight socket with extension cable(93) Connector/angled socket with
- extension cable

#### Other cable lengths on request.

Description	ID	Length
		[m]
Angled cable connect	or, robot-side	
KAS-19B-K-90-C	0301294	
KAS-19F-K-90	1316879	
KAS-26B-K-90-C	0301296	
Angled cable connect	or, tool-side	
KAS-19B-A-90-C	0301295	
KAS-19F-A-90	1316873	
KAS-26B-A-90-C	0301297	
Angled cable connect	or with cable,	robot-side
KV-5-SWK-19B-90	0302190	5
KV-5-SWK-19F-90	0302172	5
Angled cable connect	or with cable,	tool-side
KV-3-SWA-19B-90	0302191	3
KV-3-SWA-19F-90	0302175	3
Straight cable connec	tor, robot-sid	e
KAS-08G-K-0	0301268	
KAS-19B-K-O-C	0301283	
KAS-19F-K-0	1351134	
KAS-26B-K-0-C	0301290	
Straight cable connec	tor, tool-side	
KAS-08G-A-0	0301269	
KAS-19B-A-0-C	0301284	
KAS-19F-A-0	1351135	
KAS-26B-A-0-C	0301291	
Straight cable connec	tor with cable	, robot-side
KV-5-SWK-19B-0	0302177	5
KV-5-SWK-19F-0	0302170	5
Straight cable connec	tor with cable	, tool-side
KV-3-SWA-19B-0	0302178	3
KV-3-SWA-19F-0	0302174	3

 $\ensuremath{\textcircled{}}$  Detailed information and further cable connectors can be found at schunk.com

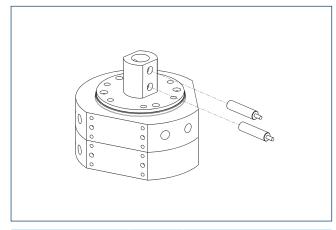
# Piston stroke control



The drawing shows the minimal height of the adapter plate for installing a piston stroke control.

Description	ID
Piston stroke co	ontrol
SWK-020-SIP	0302325

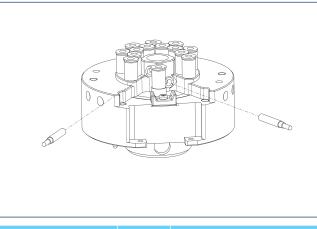
# **Piston stroke control**



Description	ID	Often combined
Inductive proximity switch		
IN 41-S-M8-PNP	1325755	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	

Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

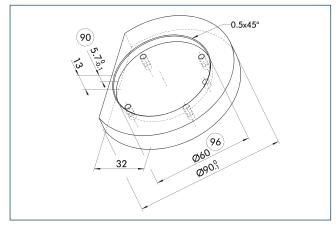
# **Piston stroke control**



Description	ID	Often combined
Inductive proximity switch		
IN 41-S-M8-PNP	1325755	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	

 Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available.
 Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

# Adapter plate design

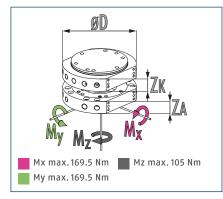


(90) Recommended adapter plate (96) Fit for centering depth

Recommendation for the design of the adapter plate.



#### Dimensions and maximum loads



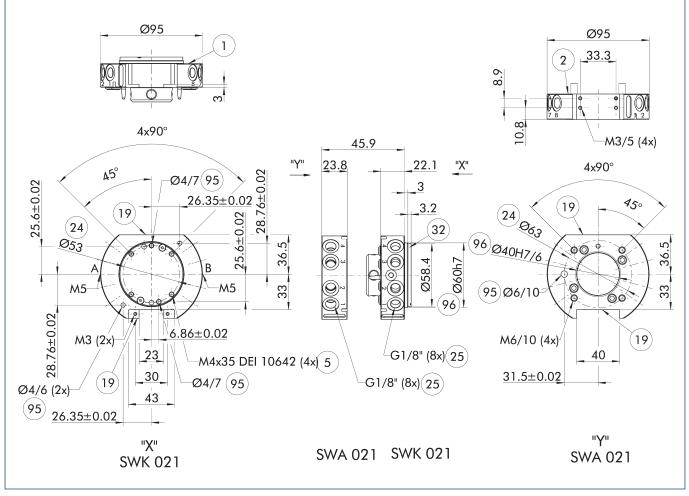
This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

Description		SWK-021-000-000	SWK-021HM-000-000-SQ	SWA-021-000-000
		Quick-change master	Quick-Change master for hollow wrist robots	Quick-change adapter
ID		0302326		0302327
Recommended handling weight	[kg]	25	25	25
Piston stroke monitoring		optional	integrated	
Locking force	[N]	2300	2300	2300
Repeat accuracy	[mm]	0.015	0.015	0.015
Weight	[kg]	0.5	0.7	0.3
Max. distance when locking	[mm]	2	2	2
Air connection thread pneumatic feed-through		8x G1/8"	8x G1/8"	8x G1/8"
Lock/unlock main connection		М5	М5	
Max. permissible XY axis offset	[mm]	±1	±1	±1
Max. permissible angular offset	[°]	±1	±1	±1
Min./max. ambient temperature	[°C]	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	95 x 22.1	95 x 58.9	95 x 23.8
Screw connection diagram		K side A/K J via adapter plate side B	K side A/K J via adapter plate side B	K side A/K J via adapter plate side B

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

#### Main view



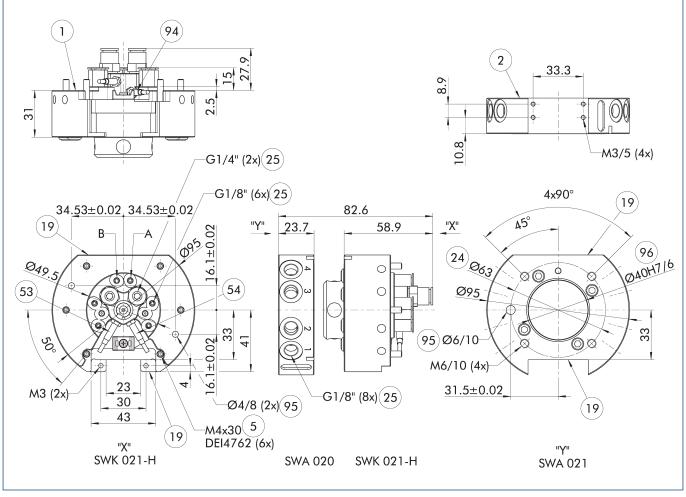
The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

- The robot-side plate mounted on the SWK is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate.
- A, a Air connection locked
- B, b Air connection unlocked
- $\bigcirc$  Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24 Bolt circle
- (25) Pneumatic feed-throughs
- 32 Cover
- (95) Fit for centering pins
- (96) Fit for centering

# SWS 021

Quick change system

# SWK-021-H main view



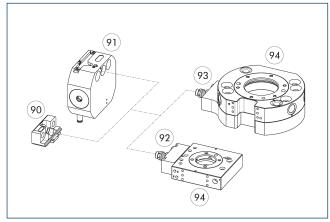
Via axial air connections it is perfectly suited for robots with through bores.

- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- $(\widetilde{2})$  Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options

- 25 Pneumatic feed-throughs
- 53 Monitoring Position unlocked
- 54 Monitoring Position locked
- 94 Optional proximity switch
- 95 Fit for centering pins
- 96 Fit for centering

<sup>(24)</sup> Bolt circle

#### Storage system SWM-B



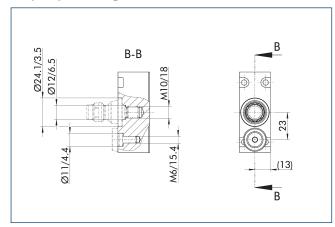
(90) SWM-B 085

- (93) Intermediate plate
- (91) SWM-B 085-V (92) Side plate
- (94) Quick-change adapter SWA

Storage system with (-V) and without locking for safe tool storage. Detailed information and further accessories can be found in the catalog chapter "SWM-B" and "SWM.".

Description	ID	
Storage system		
SWM-B 085	1459339	
SWM-B 085-V	1442590	

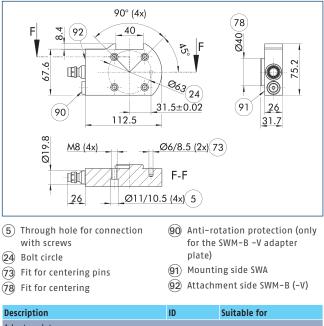
#### Adapter plate design SWM-B



Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

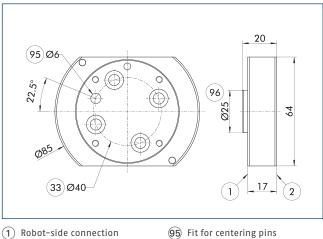
Description	ID	Suitable for
Adapter plates		
A-SWA-020/021/022-SWM-B 085	1523816	SWA 020/021/022
A-SWA-020/021/022-SWM-B 085-V	1523845	SWA 020/021/022

#### Adapter plate SWA 020/021/022



Description	10	Sultable for
Adapter plates		
A-SWA-020/021/022-SWM-B 085	1523816	SWA 020/021/022
A-SWA-020/021/022-SWM-B 085-V	1523845	SWA 020/021/022

#### Adapter plate ISO-A40-R



- (1) Robot-side connection
- (2) Tool-side connection
- (33) DIN ISO-9409 bolt circle

#### Robot side adapter plate

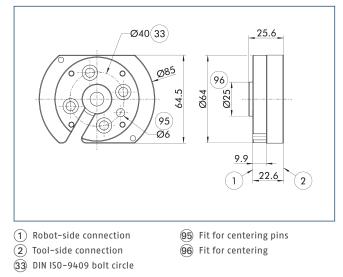
Description	ID	
Robot side		
A-SWK-020/021-IS0-A40	0302200	

(96) Fit for centering

① Adapter plate for quick-change master without piston stroke control, not suitable on quick-change head for hollow wrist robots.

Quick change system

# Adapter plate ISO-A40-SIP-R

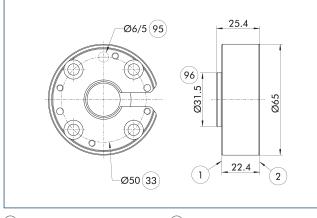


#### Robot side adapter plate

Description	ID	
Robot side		
A-SWK-020/021-IS0-A40-SIP	0302229	

() Adapter plate for quick-change master with piston stroke control, not suitable on quick-change head for hollow wrist robots.

# Adapter plate ISO-A50-SIP-R

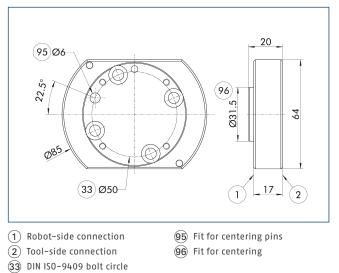


- (1) Robot-side connection
- (95) Fit for centering pins 96 Fit for centering
- $(\mathbf{2})$  Tool-side connection (33) DIN ISO-9409 bolt circle
- Robot side adapter plate

Description	ID	
Robot side		
A-SWK-020/021-IS0-A50-SIP	0302230	

① Adapter plate for quick-change master with piston stroke control, not suitable on quick-change head for hollow wrist robots.

#### Adapter plate ISO-A50-R

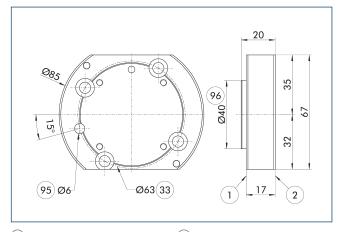


Robot side adapter plate

Description	ID		
Robot side			
A-SWK-020/021-IS0-A50	0302201		

① Adapter plate for quick-change master without piston stroke control, not suitable on quick-change head for hollow wrist robots.

#### Adapter plate ISO-A63-R



- (1) Robot-side connection (2) Tool-side connection
- (33) DIN ISO-9409 bolt circle

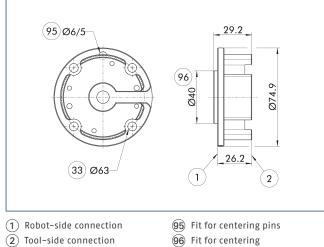
(95) Fit for centering pins (96) Fit for centering

Robot side adapter plate

Description	ID
Robot side	
A-SWK-020/021-IS0-A63	0302202

① Adapter plate for quick-change master without piston stroke control, not suitable on quick-change head for hollow wrist robots.

# Adapter plate ISO-A63-SIP-R



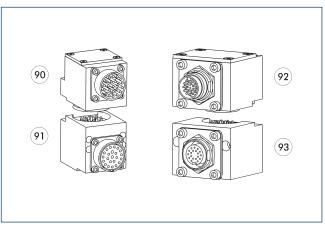
- 3 DIN ISO-9409 bolt circle

Robot side adapter plate

Description	ID	
Robot side		
A-SWK-020/021-IS0-A63-SIP	0302231	

 Adapter plate for quick-change master with piston stroke control, not suitable on quick-change head for hollow wrist robots.

#### Electric feed-through module



90 Electric module with bayonet fitting, robot-side (91) Electric module with bayonet

fitting, tool-side

(92) Electric module with metric thread, robot-side (93) Electric module with metric thread, tool-side

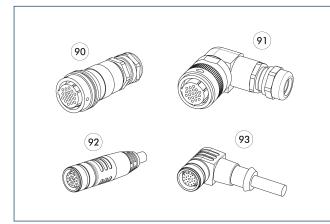
Modules for transmission of electrical signals.

Description	ID	No. Pins	
Feed-through module	ication on the robot side		
SWO-KE7-K	9960993		
Feed-through module	e for communi	ication on the tool side	
SWO-KE7-A	9960994		
Feed-through module	e for signal on	the robot side	
SW0-K12-K	9948701	12	
SW0-K19-K	9937328	19	
SWO-K19P-K	9949315	15	
SW0-K26-K	9937798	26	
SWO-KF19-K	9959886	19	
Feed-through module for signal on the tool side			
SWO-K12-A	9948702	12	
SW0-K19-A	9937329	19	
SW0-K26-A	9937799	26	
SWO-KF19-A	9959887	19	

() For more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.



# Cable plug/cable extension



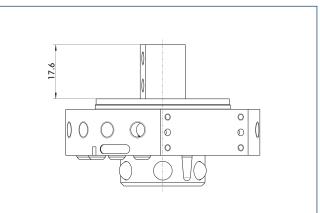
- 90 Plug/socket straight
- (91) Connector/angled socket
- (92) Connector/straight socket with extension cable(93) Connector/angled socket with
- extension cable

#### Other cable lengths on request.

Description	ID	Length		
		[m]		
Angled cable connect	or, robot-side			
KAS-19B-K-90-C	0301294			
KAS-19F-K-90	1316879			
KAS-26B-K-90-C	0301296			
Angled cable connect	or, tool-side			
KAS-19B-A-90-C	0301295			
KAS-19F-A-90	1316873			
KAS-26B-A-90-C	0301297			
Angled cable connect	or with cable,	robot-side		
KV-5-SWK-19B-90	0302190	5		
KV-5-SWK-19F-90	0302172	5		
Angled cable connect	or with cable,	tool-side		
KV-3-SWA-19B-90	0302191	3		
KV-3-SWA-19F-90	0302175	3		
Straight cable connector, robot-side				
KAS-19B-K-O-C	0301283			
KAS-19F-K-0	1351134			
KAS-26B-K-0-C	0301290			
Straight cable connec	tor, tool-side			
KAS-19B-A-O-C	0301284			
KAS-19F-A-0	1351135			
KAS-26B-A-0-C	0301291			
Straight cable connector with cable, robot-side				
KV-5-SWK-19B-0	0302177	5		
KV-5-SWK-19F-0	0302170	5		
Straight cable connec	tor with cable	, tool-side		
KV-3-SWA-19B-0	0302178	3		
KV-3-SWA-19F-0	0302174	3		

 $\ensuremath{\textcircled{}}$  Detailed information and further cable connectors can be found at schunk.com

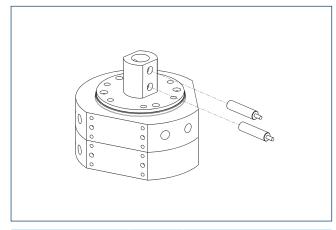
# Piston stroke control



The drawing shows the minimal height of the adapter plate for installing a piston stroke control.

Description	ID
Piston stroke co	ontrol
SWK-021-SIP	0302328

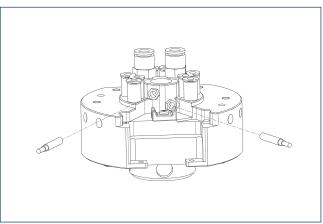
# **Piston stroke control**



Description	ID	Often combined
Inductive proximity switch		
IN 41-S-M8-PNP	1325755	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	

Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

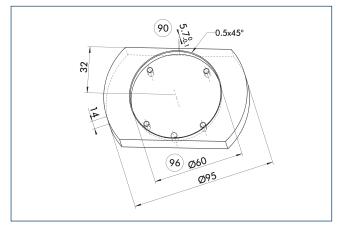
# **Piston stroke control**



Description	ID	Often combined
Inductive proximity switch		
IN 41-S-M8-PNP	1325755	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	

 Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available.
 Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

# Adapter plate design

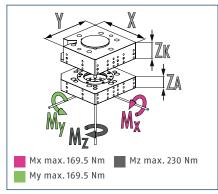


(90) Recommended adapter plate (96) Fit for centering depth

Recommendation for the design of the adapter plate.



#### Dimensions and maximum loads



This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

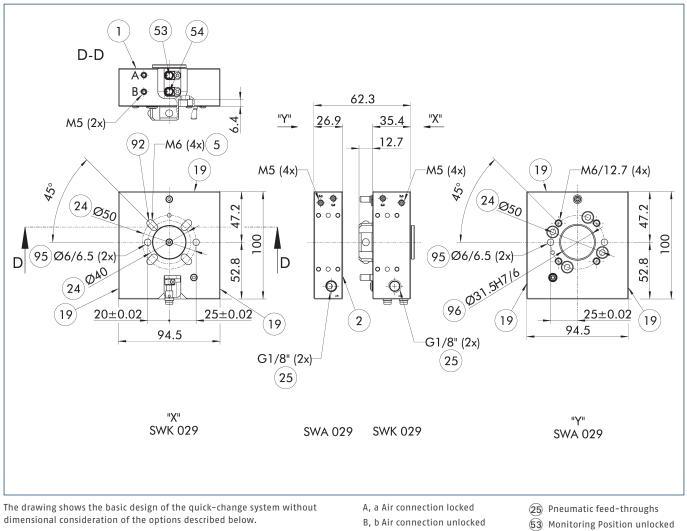
Description		SWK-029-0-0-SM	SWA-029-0-0-0
		Quick-change master	Quick-change adapter
ID		1499175	1499191
Recommended handling weight	[kg]	35	35
Piston stroke monitoring		integrated	
Locking force	[N]	2850	2850
Repeat accuracy	[mm]	0.0152	0.0152
Weight	[kg]	0.99	0.67
Max. distance when locking	[mm]	1.5	1.5
Air connection thread pneumatic feed-through		2x G1/8"	2x G1/8"
Air connection thread pneumatic feed-through		4x M5	4x M5
Lock/unlock main connection		M5	M5
Max. permissible XY axis offset	[mm]	0.9	0.9
Max. permissible angular offset	[°]	0.8	0.8
Robot-side connection		ISO 9409-1-50-4-M6 **	ISO 9409-1-50-4-M6
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9
Dimensions X x Y x Z*	[mm]	100 x 94.5 x 35.4	100 x 94.5 x 26.9
Screw connection diagram		2 x J	3 x J

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

\*\* Robot side direct connection for ISO 9409-40-4-M6 available on request.

# **SWS 029** Quick change system

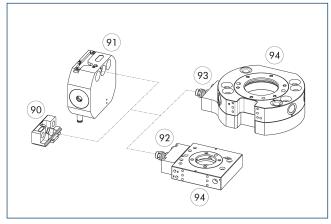
#### Main view



- (1) Robot-side connection (2) Tool-side connection
- $(\mathbf{5})$  Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle

- (54) Monitoring Position locked
- (92) Oblong hole with countersink
- (from opposite side)
- (95) Fit for centering pins
- (96) Fit for centering

# Storage system SWM-B



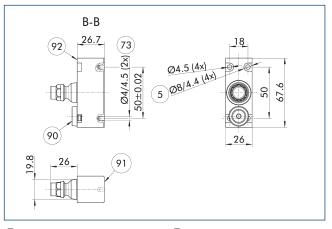
- 90 SWM-B 085
- 93 Intermediate plate
- (91) SWM-B 085-V
- 94) Quick-change adapter SWA

92 Side plate

Storage system with (-V) and without locking for safe tool storage. Detailed information and further accessories can be found in the catalog chapter "SWM-B" and "SWM.".

Description	ID
Storage system	
SWM-B 085	1459339
SWM-B 085-V	1442590

# Adapter plate J screw connection diagram



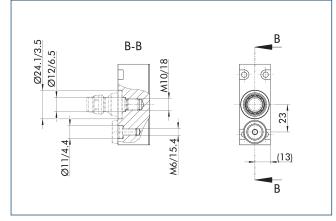
(5) Through hole for connection with screws

(73) Fit for centering pins

- Anti-rotation protection (only for the SWM-B -V adapter plate)
   Mounting side SWA
- (92) Attachment side SWM-B (-V)

Description	ID	Suitable for
Adapter plates		
A-SWA-J16-SWM-B 085	1523836	all SWA with J screw connection diagram
A-SWA-J16-SWM-B 085-V	1523875	all SWA with J screw connection diagram

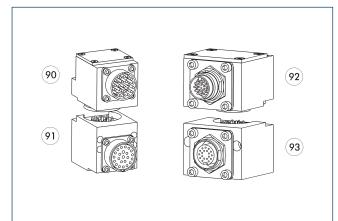
#### Adapter plate design SWM-B



Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

Description	ID	Suitable for
Adapter plates		
A-SWA-J16-SWM-B 085	1523836	all SWA with J screw connection diagram
A-SWA-J16-SWM-B 085-V	1523875	all SWA with J screw connection diagram

# Electric feed-through module



- 90 Electric module with bayonet fitting, robot-side
- (91) Electric module with bayonet fitting, tool-side
  - e with bayonet ④ Electric module with metric de thread, tool-side

(92) Electric module with metric

thread, robot-side

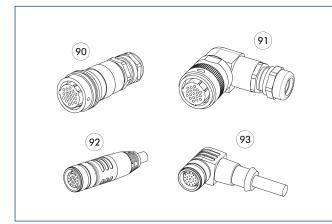
Modules for transmission of electrical signals.

Description	ID	No. Pins			
Feed-through module for communication on the robot side					
SWO-RE5-K	9957444				
Feed-through module	e for communi	ication on the tool side			
SWO-RE5-A	9957445				
Feed-through module	e for power or	the robot side			
SWO-MT8-K	9937157				
Feed-through module	e for power or	the tool side			
SWO-MT8-A	9937158				
Feed-through module	e for signal on	the robot side			
SW0-G19-K	9940649	19			
SWO-R19-K	9935815	19			
SWO-R19R-K	9942391	15			
SWO-R26-K	9935819	26			
SWO-RF19-K	9948654	19			
Feed-through module	Feed-through module for signal on the tool side				
SWO-G19-A	9940650	19			
SWO-R19-A	9935816	19			
SWO-R26-A	9935820	26			
SWO-RF19-A	9948657	19			

 For more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.



# Cable plug/cable extension



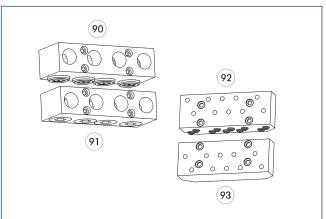
- 90 Plug/socket straight
- (91) Connector/angled socket
- (2) Connector/straight socket with extension cable
   (93) Connector/angled socket with
- extension cable

#### Other cable lengths on request.

Description	ID	Length		
		[m]		
Angled cable connector, robot-side				
KAS-08G-K-90	0301270			
KAS-19B-K-90-C	0301294			
KAS-19F-K-90	1316879			
KAS-26B-K-90-C	0301296			
Angled cable connect	or, tool-side			
KAS-08G-A-90	0301271			
KAS-19B-A-90-C	0301295			
KAS-19F-A-90	1316873			
KAS-26B-A-90-C	0301297			
Angled cable connect	or with cable,	robot-side		
KV-5-SWK-19B-90	0302190	5		
KV-5-SWK-19F-90	0302172	5		
Angled cable connect	or with cable,	tool-side		
KV-3-SWA-19B-90	0302191	3		
KV-3-SWA-19F-90	0302175	3		
Straight cable connec	tor, robot-sid	e		
KAS-08G-K-0	0301268			
KAS-19B-K-0-C	0301283			
KAS-19F-K-0	1351134			
KAS-26B-K-0-C	0301290			
Straight cable connec	tor, tool-side			
KAS-08G-A-0	0301269			
KAS-19F-A-0	1351135			
KAS-26B-A-0-C	0301291			
Straight cable connec	tor with cable	e, robot-side		
KV-5-SWK-19B-0	0302177	5		
KV-5-SWK-19F-0	0302170	5		
Straight cable connec	tor with cable	e, tool-side		
KV-3-SWA-19B-0	0302178	3		
KV-3-SWA-19F-0	0302174	3		

 $\ensuremath{\textcircled{}}$  Detailed information and further cable connectors can be found at schunk.com

# Pneumatic/ fludic feed-through modules



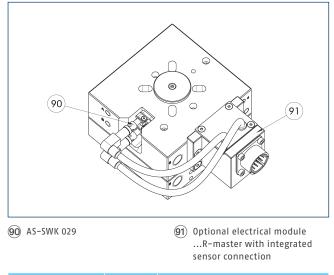
- Self-sealing fluid module, robot-side
- (92) Pneumatic module, robot-side(93) Pneumatic module, tool-side
- (91) Self-sealing fluid module, tool-side

Modules for transferring fluids (air, vacuum or fluid).

Description	ID	No. of fluid feed-throughs			
Feed-through module for liquids on the robot side					
SWO-FG2-K	9936817	2			
Feed-through module	e for liquids o	n the tool side			
SWO-FG2-A	9936818	2			
Feed-through module for pneumatics on the robot side					
SW0-P238-K	9940578	2			
SWO-P8M5-K	9872067	8			
Feed-through module for pneumatics on the tool side					
SW0-P238-A	9940580	2			
SWO-P8M5-A	9872068	8			

Tor other pneumatic and fluid modules, see catalog chapter "Options" or visit our website.

# Assembly situation of the locking monitoring

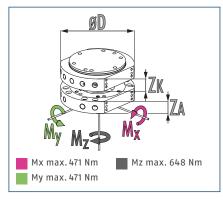


Description	ID	
Robot side		
AS-SWK-022/029-SM	1501841	

The -SG/-SM/-SQ/-IN variants of the SWK include the piston stroke monitoring option. An additional order of the mounting kit is not necessary. The scope of delivery of a mounting kit contains one preset sensor with holder each, meaning that two mounting kits are required per SWK.



#### Dimensions and maximum loads



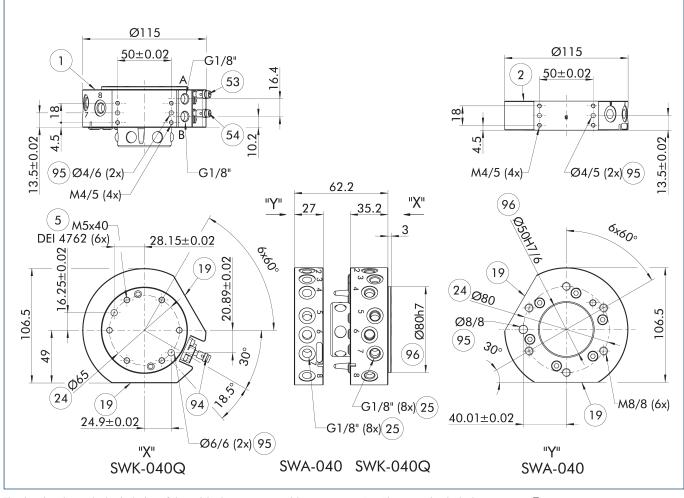
This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

Description		SWK-040Q-000-000-SG	SWA-040-000-000
		Quick-change master	Quick-change adapter
ID		0302364	0302343
Recommended handling weight	[kg]	50	50
Piston stroke monitoring		integrated	
Locking force	[N]	5650	5650
Repeat accuracy	[mm]	0.015	0.015
Weight	[kg]	1.27	0.6
Max. distance when locking	[mm]	3	3
Air connection thread pneumatic feed-through		8x G1/8"	8x G1/8"
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset	[°]	±2	±2
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	115 x 35.2	115 x 27.1
Screw connection diagram		J	J

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

#### Main view



The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

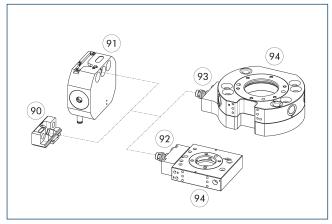
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options

(24) Bolt circle

- (25) Pneumatic feed-throughs
- (53) Monitoring Position unlocked
- (54) Monitoring Position locked
- (94) Optional proximity switch
- 95 Fit for centering pins
- 96 Fit for centering

55

#### Storage system SWM-B

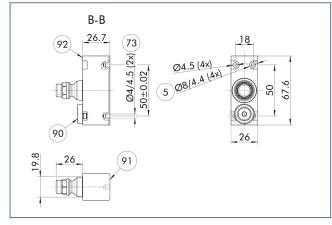


- (90) SWM-B 085
- 93 Intermediate plate
- 91) SWM-B 085-V 92) Side plate
- 94 Quick-change adapter SWA

Storage system with (-V) and without locking for safe tool storage. Detailed information and further accessories can be found in the catalog chapter "SWM-B" and "SWM.".

Description	ID	
Storage system		
SWM-B 085	1459339	
SWM-B 085-V	1442590	

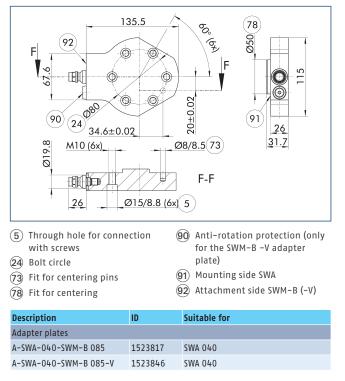
#### Adapter plate J screw connection diagram



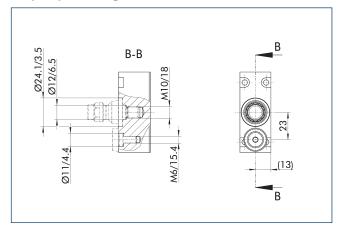
- (5) Through hole for connection with screws
- (73) Fit for centering pins
- Anti-rotation protection (only for the SWM-B -V adapter plate)
- (91) Mounting side SWA
- (92) Attachment side SWM-B (-V)

Description	ID	Suitable for
Adapter plates		
A-SWA-J16-SWM-B 085	1523836	all SWA with J screw connection diagram
A-SWA-J16-SWM-B 085-V	1523875	all SWA with J screw connection diagram

#### Adapter plate SWA 040



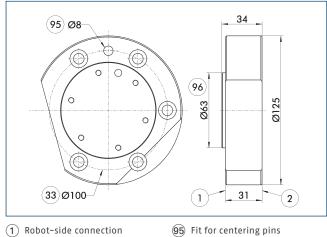
#### Adapter plate design SWM-B



Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

Description	ID	Suitable for
Adapter plates		
A-SWA-040-SWM-B 085	1523817	SWA 040
A-SWA-040-SWM-B 085-V	1523846	SWA 040
A-SWA-J16-SWM-B 085	1523836	all SWA with J screw connection diagram
A-SWA-J16-SWM-B 085-V	1523875	all SWA with J screw connection diagram

# Adapter plate ISO-A100-R

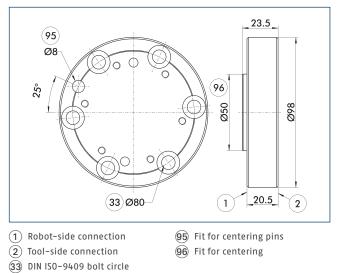


- Robot-side connection
   Tool-side connection
  - 96 Fit for centering
- 3 DIN ISO-9409 bolt circle

#### Robot side adapter plate

Description	ID
Robot side	
A-SWK-040-IS0-A100	0302204

# Adapter plate ISO-A80-R



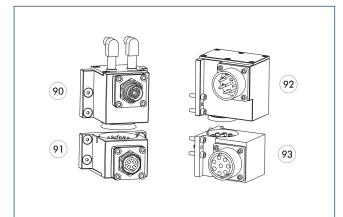
Robot side adapter plate

Description	ID
Robot side	
A-SWK-040-IS0-A80	0302203

57

Quick change system

# Electric feed-through module



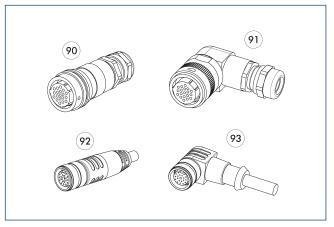
- (90) Electric module with metric thread, robot-side
- (91) Electric module with metric thread, tool-side
- (92) Electric module with MIL-Spec thread, robot-side
- (93) Electric module with MIL-Spec thread, tool-side

Modules for transmission of electrical signals.

Description	ID	No. Pins
Feed-through module	e for communi	ication on the robot side
SWO-RE5-K	9957444	
Feed-through module	e for communi	ication on the tool side
SWO-RE5-A	9957445	
Feed-through module	e for power or	n the robot side
SWO-MT8-K	9937157	
Feed-through module	e for power or	n the tool side
SWO-MT8-A	9937158	
Feed-through module	e for signal on	the robot side
SWO-G19-K	9940649	19
SWO-R19-K	9935815	19
SWO-R19W-K	9942041	15
SWO-R26-K	9935819	26
SWO-RF19-K	9948654	19
Feed-through module	e for signal on	the tool side
SWO-G19-A	9940650	19
SWO-R19-A	9935816	19
SWO-R26-A	9935820	26
SWO-RF19-A	9948657	19

For more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.

# Cable plug/cable extension



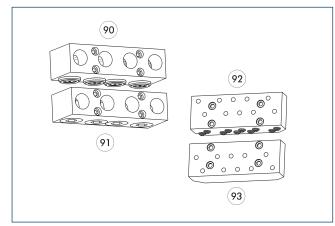
- 90 Plug/socket straight91 Connector/angled socket
- (92) Connector/straight socket with extension cable
- (93) Connector/angled socket with extension cable

Other cable lengths on request.

Description	ID	Length		
		[m]		
Angled cable connector, robot-side				
KAS-19B-K-90-C	0301294			
KAS-19F-K-90	1316879			
KAS-26B-K-90-C	0301296			
Angled cable connect	or, tool-side			
KAS-19B-A-90-C	0301295			
KAS-19F-A-90	1316873			
KAS-26B-A-90-C	0301297			
Angled cable connect	or with cable,	robot-side		
KV-5-SWK-19B-90	0302190	5		
KV-5-SWK-19F-90	0302172	5		
Angled cable connect	or with cable,	tool-side		
KV-3-SWA-19B-90	0302191	3		
KV-3-SWA-19F-90	0302175	3		
Straight cable connec	tor, robot-sid:	e		
KAS-08G-K-0	0301268			
KAS-19B-K-O-C	0301283			
KAS-19F-K-0	1351134			
KAS-26B-K-0-C	0301290			
Straight cable connec	tor, tool-side:			
KAS-08G-A-0	0301269			
KAS-19B-A-0-C	0301284			
KAS-19F-A-0	1351135			
KAS-26B-A-O-C	0301291			
Straight cable connector with cable, robot-side				
KV-5-SWK-19B-0	0302177	5		
KV-5-SWK-19F-0	0302170	5		
Straight cable connector with cable, tool-side				
KV-3-SWA-19B-0	0302178	3		

 $\ensuremath{\textcircled{}}$  Detailed information and further cable connectors can be found at schunk.com

# Pneumatic/ fludic feed-through modules



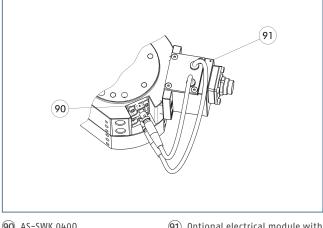
- (90) Self-sealing fluid module, robot-side
- (92) Pneumatic module, robot-side
- (93) Pneumatic module, tool-side
- (91) Self-sealing fluid module, tool-side

Modules for transferring fluids (air, vacuum or fluid).

Description	ID	No. of fluid feed-throughs
Feed-through module	e for liquids o	n the robot side
SWO-FG2-K	9936817	2
Feed-through module	e for liquids o	n the tool side
SWO-FG2-A	9936818	2
Feed-through module for pneumatics on the robot side		
SWO-P8M5-K	9872067	8
Feed-through module for pneumatics on the tool side		
SWO-P8M5-A	9872068	8

() For other pneumatic and fluid modules, see catalog chapter "Options" or visit our website.

#### Assembly situation of the locking monitoring



90 AS-SWK 040Q

(91) Optional electrical module with integrated sensor connection

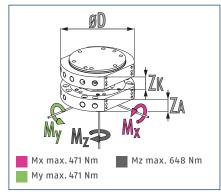
The drawing shows the quick-change system with integrated piston stroke monitoring and built-in proximity switch; this is directly connected to the electric modules.

Description	ID	
Attachment kit for proximity switch		
AS-SWK-40Q/076 attachment kit including sensor	9955216	

The -SG/-SM/-SQ/-IN variants of the SWK include the piston stroke monitoring option. An additional order of the mounting kit is not necessary. The scope of delivery of a mounting kit contains one preset sensor with holder each, meaning that two mounting kits are required per SWK.



#### Dimensions and maximum loads



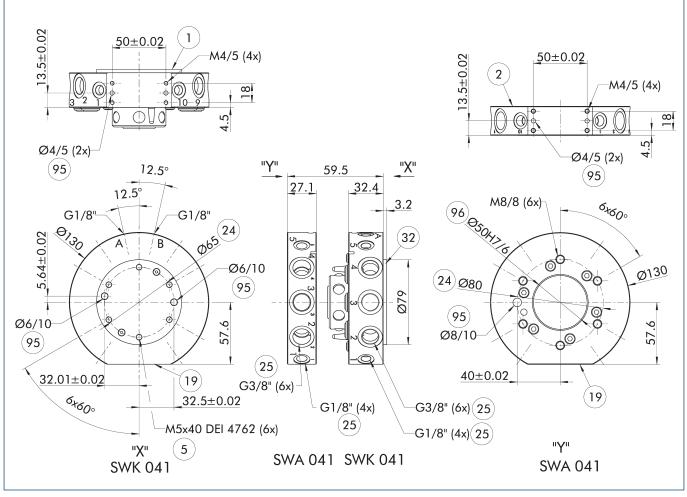
This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

Description		SWK-041-000-000	SWA-041-000-000
		Quick-change master	Quick-change adapter
ID		0302346	0302347
Recommended handling weight	[kg]	50	50
Piston stroke monitoring		optional	
Locking force	[N]	4500	4500
Repeat accuracy	[mm]	0.015	0.015
Weight	[kg]	1.4	0.7
Max. distance when locking	[mm]	3	3
Air connection thread pneumatic feed-through		6x G3/8"	6x G3/8"
Air connection thread pneumatic feed-through		4x G1/8"	4x G1/8"
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset	[°]	±2	±2
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	130 x 32.3	130 x 27
Screw connection diagram		J	J

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

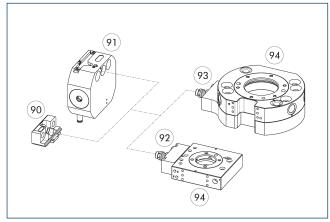
#### Main view



The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

- The robot-side plate mounted on the SWK is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate.
- A, a Air connection locked
- B, b Air connection unlocked
- $\underbrace{1}$  Robot-side connection
- 2 Tool-side connection
- Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle
- (25) Pneumatic feed-throughs
- (32) Cover
- (95) Fit for centering pins
- 96 Fit for centering

#### Storage system SWM-B



(90) SWM-B 085

(93) Intermediate plate

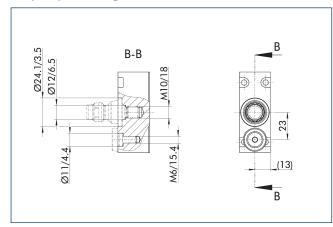
(91) SWM-B 085-V (92) Side plate

(94) Quick-change adapter SWA

Storage system with (-V) and without locking for safe tool storage. Detailed information and further accessories can be found in the catalog chapter "SWM-B" and "SWM.".

Description	ID	
Storage system		
SWM-B 085	1459339	
SWM-B 085-V	1442590	

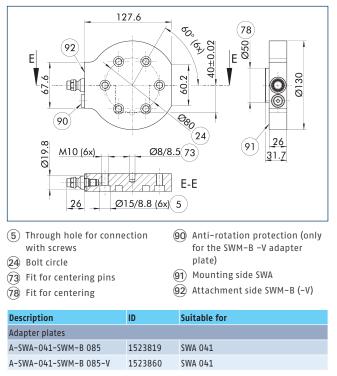
#### Adapter plate design SWM-B



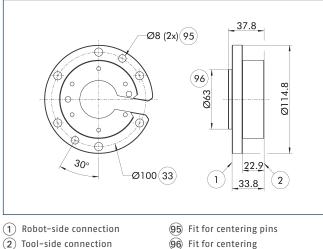
Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

Description	ID	Suitable for
Adapter plates		
A-SWA-041-SWM-B 085	1523819	SWA 041
A-SWA-041-SWM-B 085-V	1523860	SWA 041

#### Adapter plate SWA 041



#### Adapter plate ISO-A100-SIP-R



(33) DIN ISO-9409 bolt circle

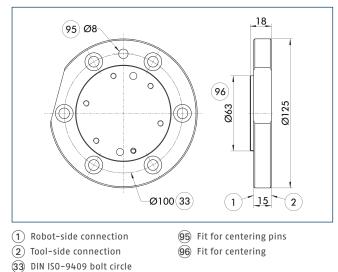
(96) Fit for centering

Robot side adapter plate			
Description	ID		
Deliver the			

Robot side A-SWK-040/041-IS0-A100-SIP 0302232

① Adapter plate for quick change master with piston stroke control

# Adapter plate ISO-A100-R



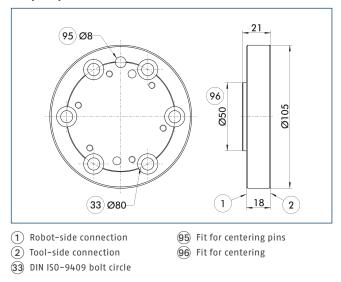
# Robot side adapter plate

Adapter plate ISO-A80-SIP-R

Description	ID
Robot side	
A-SWK-041-IS0-A100	0302206

① Adapter plate for quick change master without piston stroke control

#### Adapter plate ISO-A80-R



Robot side adapter plate

Description	ID
Robot side	
A-SWK-041-IS0-A80	0302205

① Adapter plate for quick change master without piston stroke control

# (1) Robot-side connection

- (2) Tool-side connection
- (95) Fit for centering pins(96) Fit for centering
- (33) DIN ISO-9409 bolt circle
  - אויש=סכו אויש

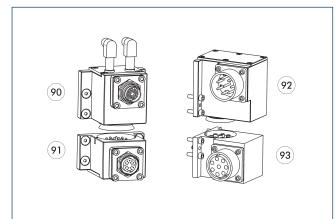
# Robot side adapter plate

Description	ID
Robot side	
A-SWK-041-ISO-A80-SIP	0302235

Adapter plate for quick change master with piston stroke control

Quick change system

# Electric feed-through module



(92) Electric module with MIL-Spec

(93) Electric module with MIL-Spec

thread, robot-side

- (90) Electric module with metric thread, robot-side
- (91) Electric module with metric thread, tool-side
- thread, tool-side thread, tool-side

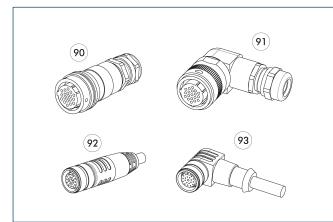
Modules for transmission of electrical signals.

Description	ID	No. Pins		
Feed-through module	ication on the robot side			
SWO-RE5-K	9957444			
Feed-through module	e for communi	ication on the tool side		
SWO-RE5-A	9957445			
Feed-through module	e for power or	n the robot side		
SWO-MT8-K	9937157			
Feed-through module	e for power or	n the tool side		
SWO-MT8-A	9937158			
Feed-through module	e for signal on	the robot side		
SW0-G19-K	9940649	19		
SWO-R19-K	9935815	19		
SWO-R19W-K	9942041	15		
SWO-R26-K	9935819	26		
SWO-RF19-K	9948654	19		
Feed-through module for signal on the tool side				
SWO-G19-A	9940650	19		
SWO-R19-A	9935816	19		
SWO-R26-A	9935820	26		
SWO-RF19-A	9948657	19		

Tor more detailed information and further modules and matching cable connectors, see catalog chapter "SW0" or visit our website.

64

# Cable plug/cable extension



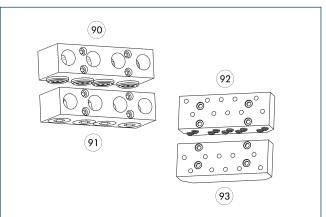
- 90 Plug/socket straight
- (91) Connector/angled socket
- (92) Connector/straight socket with extension cable
- (93) Connector/angled socket with extension cable

#### Other cable lengths on request.

Description	ID	Length	
		[m]	
Angled cable connect	or, robot-side	1	
KAS-19B-K-90-C	0301294		
KAS-19F-K-90	1316879		
KAS-26B-K-90-C	0301296		
Angled cable connect	or, tool-side		
KAS-19B-A-90-C	0301295		
KAS-19F-A-90	1316873		
KAS-26B-A-90-C	0301297		
Angled cable connect	or with cable,	robot-side	
KV-5-SWK-19B-90	0302190	5	
KV-5-SWK-19F-90	0302172	5	
Angled cable connect	or with cable,	, tool-side	
KV-3-SWA-19B-90	0302191	3	
KV-3-SWA-19F-90	0302175	3	
Straight cable connec	tor, robot-sid	e	
KAS-08G-K-0	0301268		
KAS-19B-K-O-C	0301283		
KAS-19F-K-0	1351134		
KAS-26B-K-0-C	0301290		
Straight cable connec	tor, tool-side		
KAS-08G-A-0	0301269		
KAS-19B-A-0-C	0301284		
KAS-19F-A-0	1351135		
KAS-26B-A-0-C	0301291		
Straight cable connector with cable, robot-side			
KV-5-SWK-19B-0	0302177	5	
KV-5-SWK-19F-0		5	
Straight cable connec	tor with cable	e, tool-side	
KV-3-SWA-19B-0	0302178	3	
KV-3-SWA-19F-0	0302174	3	

 $\ensuremath{\textcircled{}}$  Detailed information and further cable connectors can be found at schunk.com

# Pneumatic/ fludic feed-through modules



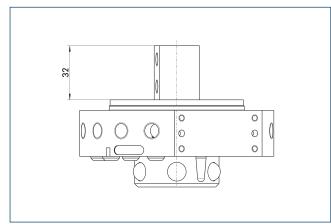
- Self-sealing fluid module, robot-side
   Self-sealing fluid module,
- (92) Pneumatic module, robot-side(93) Pneumatic module, tool-side
- tool-side

Modules for transferring fluids (air, vacuum or fluid).

liquids or	a tha rabat sida			
	i the lobot side			
6817	2			
Feed-through module for liquids on the tool side				
6818	2			
Feed-through module for pneumatics on the robot side				
2067	8			
Feed-through module for pneumatics on the tool side				
2068	8			
	liquids or 6818 pneumat 2067 pneumat			

Tor other pneumatic and fluid modules, see catalog chapter "Options" or visit our website. Quick change system

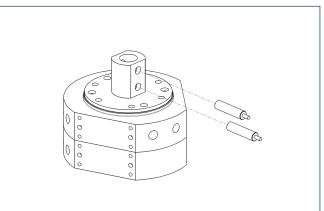
# **Piston stroke control**



The drawing shows the minimal height of the adapter plate for installing a piston stroke control.

Description	ID			
Piston stroke co	ontrol			
SWK-041-SIP	0302348			

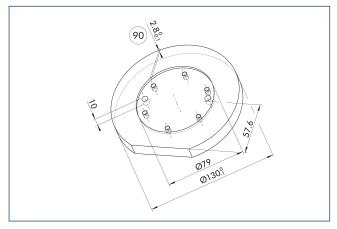
# Piston stroke control



Description	ID	Often combined
Inductive proximity switch		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	
INK 80-S	0301550	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
Clip for connector/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M12	0301776	•
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

① Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

# Adapter plate design



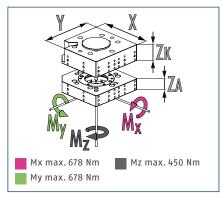
(90) Recommended adapter plate depth

Recommendation for the design of the adapter plate.





#### Dimensions and maximum loads



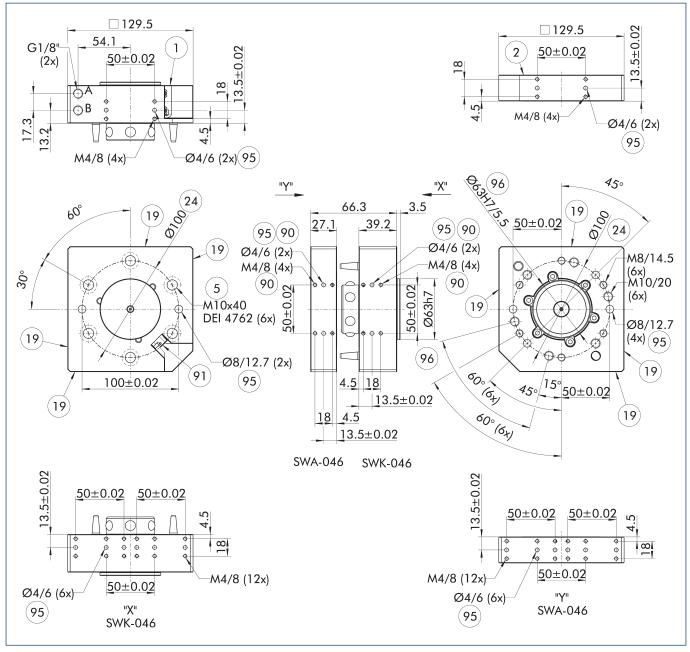
This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

Description		SWK-046-0-0-000-0-SM	SWA-046-0-0-000-0
		Quick-change master	Quick-change adapter
ID		1330577	1315663
Recommended handling weight	[kg]	50	50
Piston stroke monitoring		integrated	
Locking force	[N]	5800	5800
Repeat accuracy	[mm]	0.015	0.015
Weight	[kg]	1.95	1.03
Max. distance when locking	[mm]	2.5	2.5
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±1.5	±1.5
Max. permissible angular offset	[°]	±2	±2
Robot-side connection		ISO 9409-1-100-6-M8	ISO 9409-1-100-6-M8
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9
Dimensions X x Y x Z*	[mm]	129.5 x 129.5 x 39.1	129.5 x 129.5 x 27
Screw connection diagram		5 x J	5 x J

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

#### Main view

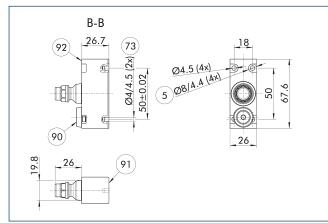


The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

A, a Air connection locked

- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (5) Through hole for connection
  - with screws n
- (19) Mounting surface for options
- (20) Connection for electric feed-through
- 24 Bolt circle
- 90 on both sides
- (91) Sensor connections for the lock monitoring
- 95) Fit for centering pins
- 96 Fit for centering

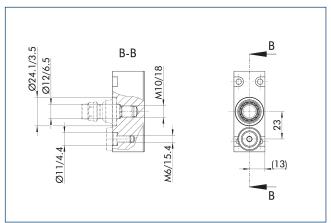
# Adapter plate J screw connection diagram



- (5) Through hole for connection with screws
- (73) Fit for centering pins
- Anti-rotation protection (only for the SWM-B -V adapter plate)
- (91) Mounting side SWA
- (92) Attachment side SWM-B (-V)

Description	ID	Suitable for
Adapter plates		
A-SWA-J16-SWM-B 085	1523836	all SWA with J screw connection diagram
A-SWA-J16-SWM-B 085-V	1523875	all SWA with J screw connection diagram

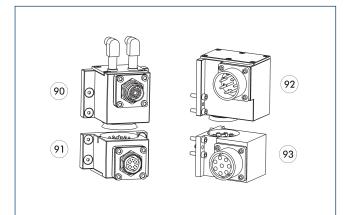
# Adapter plate design SWM-B



Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

Description	ID	Suitable for
Adapter plates		
A-SWA-J16-SWM-B 085	1523836	all SWA with J screw connection diagram
A-SWA-J16-SWM-B 085-V	1523875	all SWA with J screw connection diagram

#### Electric feed-through module



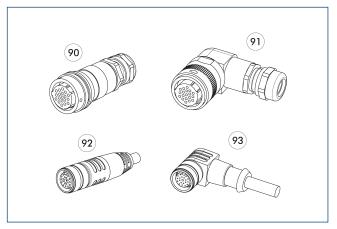
- (90) Electric module with metric thread, robot-side
- (91) Electric module with metric thread, tool-side
- (92) Electric module with MIL-Spec thread, robot-side
- (93) Electric module with MIL-Spec thread, tool-side

Modules for transmission of electrical signals.

Description	ID	No. Pins		
Feed-through module for communication on the robot side				
SWO-RE5-K	9957444			
Feed-through module	e for communi	ication on the tool side		
SWO-RE5-A	9957445			
Feed-through module	e for power or	the robot side		
SWO-MT8-K	9937157			
Feed-through module	e for power or	the tool side		
SWO-MT8-A	9937158			
Feed-through module	e for signal on	the robot side		
SW0-G19-K	9940649	19		
SWO-R19-K	9935815	19		
SWO-R19W-K	9942041	15		
SWO-R26-K	9935819	26		
SWO-RF19-K	9948654	19		
Feed-through module for signal on the tool side				
SWO-G19-A	9940650	19		
SWO-R19-A	9935816	19		
SWO-R26-A	9935820	26		
SWO-RF19-A	9948657	19		

Tor more detailed information and further modules and matching cable connectors, see catalog chapter "SW0" or visit our website.

# Cable plug/cable extension



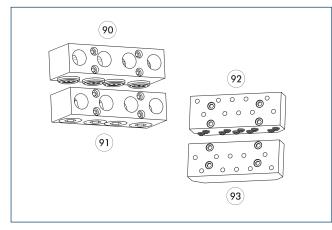
- 90 Plug/socket straight91 Connector/angled socket
- (92) Connector/straight socket with extension cable
- (93) Connector/angled socket with extension cable

Other cable lengths on request.

Description	ID	Length			
		[m]			
Angled cable connec	tor, robot-side				
KAS-08G-K-90	0301270				
KAS-19B-K-90-C	0301294				
KAS-26B-K-90-C	0301296				
Angled cable connec	tor, tool-side				
KAS-08G-A-90	0301271				
KAS-19B-A-90-C	0301295				
KAS-26B-A-90-C	0301297				
Angled cable connec	tor with cable,	robot-side			
KV-5-SWK-19B-90	0302190	5			
Angled cable connec	Angled cable connector with cable, tool-side				
KV-3-SWA-19F-90	0302175	3			
Straight cable conne	ctor, robot-sid	e			
KAS-08G-K-0	0301268				
KAS-19B-K-O-C	0301283				
KAS-26B-K-0-C	0301290				
Straight cable conne	ctor, tool-side				
KAS-08G-A-0	0301269				
KAS-19B-A-0-C	0301284				
KAS-26B-A-O-C	0301291				
Straight cable connector with cable, robot-side					
KV-5-SWK-19B-0	0302177	5			
Straight cable conne	ctor with cable	e, tool-side			
KV-3-SWA-19F-0	0302174	3			

Detailed information and further cable connectors can be found at schunk.com

# Pneumatic/ fludic feed-through modules



- 90 Self-sealing fluid module, robot-side
- (92) Pneumatic module, robot-side(93) Pneumatic module, tool-side
- (91) Self-sealing fluid module, tool-side

Modules for transferring fluids (air, vacuum or fluid).

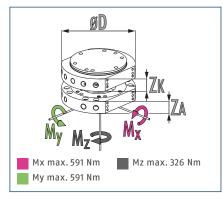
Description	ID	No. of fluid feed-throughs		
Feed-through module for liquids on the robot side				
SWO-FG2-K	9936817	2		
Feed-through module for liquids on the tool side				
SWO-FG2-A	9936818	2		
Feed-through module for pneumatics on the robot side				
SWO-P8M5-K	9872067	8		
Feed-through module for pneumatics on the tool side				
SWO-P8M5-A	9872068	8		

 $\ensuremath{\textcircled{}}$  For other pneumatic and fluid modules, see catalog chapter "Options" or visit our website.





#### Dimensions and maximum loads



This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

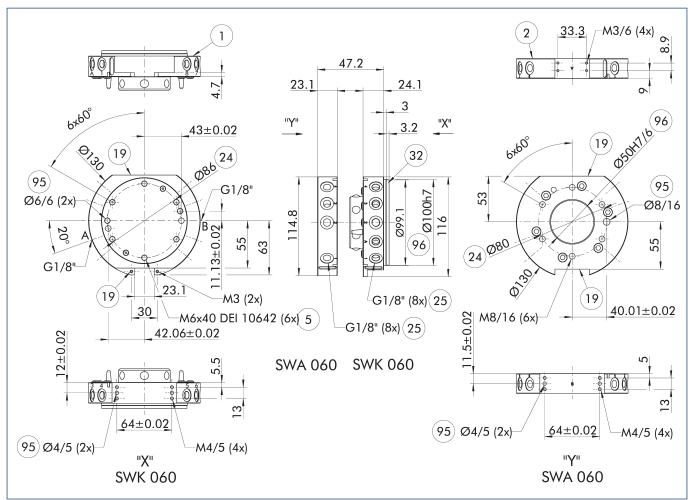
# **Technical data**

Description		SWK-060-000-000	SWA-060-000-000
		Quick-change master	Quick-change adapter
ID		0302362	0302363
Recommended handling weight	[kg]	75	75
Piston stroke monitoring		optional	
Locking force	[N]	7400	7400
Repeat accuracy	[mm]	0.015	0.015
Weight	[kg]	1.3	0.7
Max. distance when locking	[mm]	3	3
Air connection thread pneumatic feed-through		8x G1/8"	8x G1/8"
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset	[°]	±1	±1
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	130 x 24.1	130 x 23.1
Screw connection diagram		K side S/J via adapter plate side B	K side S/J via adapter plate side B

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

# **SWS 060** Quick change system

#### Main view

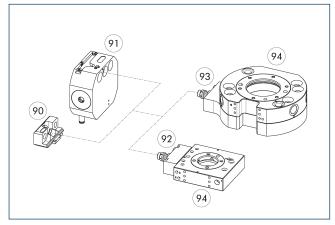


The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

The robot-side plate mounted on the SWK is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate. A, a Air connection locked

- B, b Air connection unlocked
- $\underbrace{1}_{i}$  Robot-side connection
- Tool-side connection
   Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle
- (25) Pneumatic feed-throughs
- (32) Cover
- (95) Fit for centering pins
- (96) Fit for centering

#### Storage system SWM-B



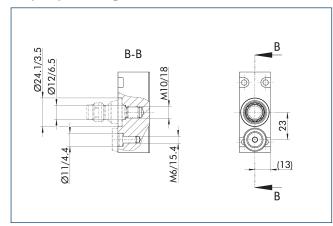
(90) SWM-B 085

- (93) Intermediate plate
- (91) SWM-B 085-V (92) Side plate
- (94) Quick-change adapter SWA

Storage system with (-V) and without locking for safe tool storage. Detailed information and further accessories can be found in the catalog chapter "SWM-B" and "SWM.".

Description	ID	
Storage system		
SWM-B 085	1459339	
SWM-B 085-V	1442590	

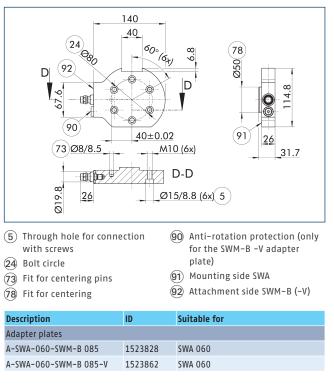
#### Adapter plate design SWM-B



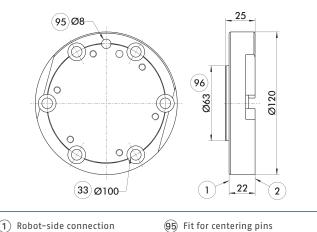
Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

Description	ID	Suitable for
Adapter plates		
A-SWA-060-SWM-B 085	1523828	SWA 060
A-SWA-060-SWM-B 085-V	1523862	SWA 060

#### Adapter plate SWA 060



### Adapter plate ISO-A100-R



- (1) Robot-side connection
- (2) Tool-side connection
- (33) DIN ISO-9409 bolt circle

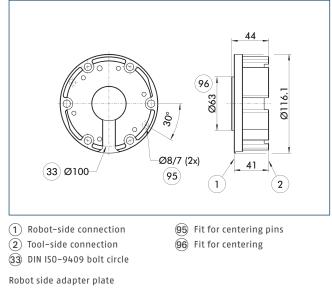
(96) Fit for centering

Robot side adapter plate

ID Description Robot side A-SWK-060/062-ISO-A100 0302208

① Adapter plate for quick change master without piston stroke control

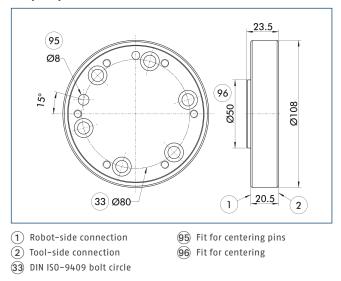
### Adapter plate ISO-A100-SIP-R



Description	ID
Robot side	
A-SWK-060/062-IS0-A100-SIP	0302236

① Adapter plate for quick change master with piston stroke control

#### Adapter plate ISO-A80-R



Robot side adapter plate

Description	ID	
Robot side		
A-SWK-060/062-IS0-A80	0302207	

① Adapter plate for quick change master without piston stroke control

# 41 Ø80 (33) (96) 28 Ø50 ର୍ ဇ္တိ Ø8 95 38 (1 2 (1) Robot-side connection (95) Fit for centering pins $(\mathbf{2})$ Tool-side connection

- (96) Fit for centering
- (33) DIN ISO-9409 bolt circle

Adapter plate ISO-A80-SIP-R

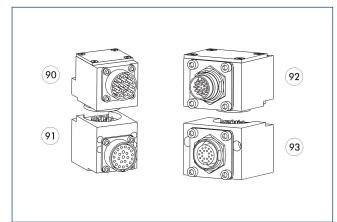
Robot side adapter plate

Description	ID
Robot side	
A-SWK-060/062-IS0-A80-SIP	0302237

① Adapter plate for quick change master with piston stroke control

Quick change system

# Electric feed-through module



(92) Electric module with metric

(93) Electric module with metric

thread, robot-side

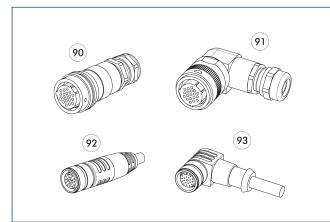
thread, tool-side

- (90) Electric module with bayonet fitting, robot-side
- (91) Electric module with bayonet fitting, tool-side
- Modules for transmission of electrical signals.

Description	ID	No. Pins
Feed-through module	e for commun	ication on the robot side
SWO-KE7-K	9960993	
Feed-through module	e for commun	ication on the tool side
SWO-KE7-A	9960994	
Feed-through module	e for signal on	the robot side
SW0-K12-K	9948701	12
SW0-K19-K	9937328	19
SWO-K19W-K	9949316	15
SW0-K26-K	9937798	26
SWO-KF19-K	9959886	19
Feed-through module	e for signal on	the tool side
SWO-K12-A	9948702	12
SW0-K19-A	9937329	19
SW0-K26-A	9937799	26
SWO-KF19-A	9959887	19

 For more detailed information and further modules and matching cable connectors, see catalog chapter "SW0" or visit our website.

# Cable plug/cable extension



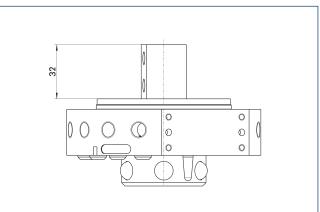
- 90 Plug/socket straight
- 91 Connector/angled socket
- (92) Connector/straight socket with extension cable
- (93) Connector/angled socket with extension cable

#### Other cable lengths on request.

Description	ID	Length
		[m]
Angled cable connect	or, robot-side	
KAS-19B-K-90-C	0301294	
KAS-19F-K-90	1316879	
KAS-26B-K-90-C	0301296	
Angled cable connect	or, tool-side	
KAS-19B-A-90-C	0301295	
KAS-19F-A-90	1316873	
KAS-26B-A-90-C	0301297	
Angled cable connect	or with cable,	robot-side
KV-5-SWK-19B-90	0302190	5
KV-5-SWK-19F-90	0302172	5
Angled cable connect	or with cable,	tool-side
KV-3-SWA-19B-90	0302191	3
KV-3-SWA-19F-90	0302175	3
Straight cable connec	tor, robot-sid	e
KAS-19B-K-O-C	0301283	
KAS-19F-K-0	1351134	
KAS-26B-K-0-C	0301290	
Straight cable connec	tor, tool-side	
KAS-19B-A-0-C	0301284	
KAS-19F-A-0	1351135	
KAS-26B-A-0-C	0301291	
Straight cable connec	tor with cable	e, robot-side
KV-5-SWK-19B-0	0302177	5
KV-5-SWK-19F-0	0302170	5
Straight cable connec	tor with cable	e, tool-side
KV-3-SWA-19B-0	0302178	3
KV-3-SWA-19F-0	0302174	3

 $\ensuremath{\textcircled{}}$  Detailed information and further cable connectors can be found at schunk.com

### **Piston stroke control**



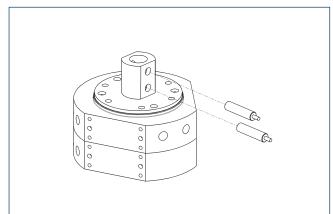
The drawing shows the minimal height of the adapter plate for installing a piston stroke control.

Description	ID
Piston stroke co	control
SWK-060-SIP	0302365

79

Quick change system

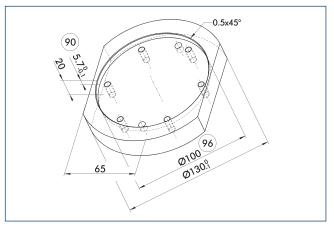
# Piston stroke control



Description	ID	Often combined
Inductive proximity switch		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	
INK 80-S	0301550	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
Clip for connector/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M12	0301776	•
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

# Adapter plate design



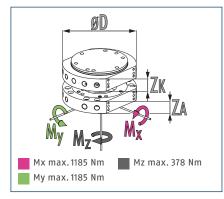
(90) Recommended adapter plate (96) Fit for centering depth

Recommendation for the design of the adapter plate.





#### Dimensions and maximum loads



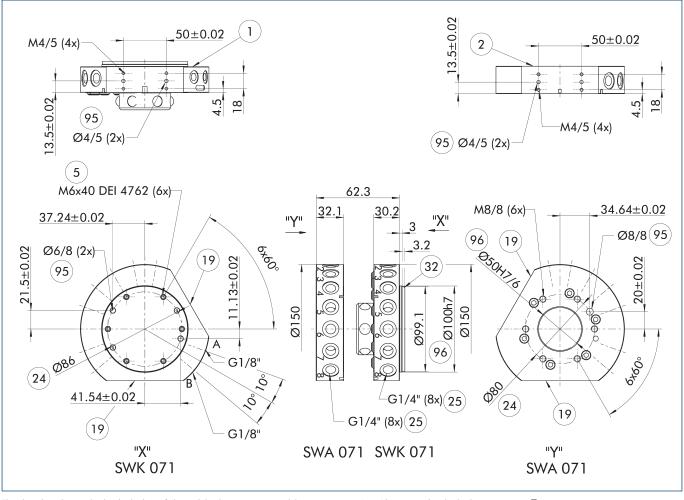
This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

Description		SWK-071-000-000	SWA-071-000-000
		Quick-change master	Quick-change adapter
ID		0302370	0302371
Recommended handling weight	[kg]	79	79
Piston stroke monitoring		optional	
Locking force	[N]	8100	8100
Repeat accuracy	[mm]	0.015	0.015
Weight	[kg]	1.8	1.3
Max. distance when locking	[mm]	3	3
Air connection thread pneumatic feed-through		8x G1/4"	8x G1/4"
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset	[°]	±1	±1
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	150 x 30.2	150 x 32.1
Screw connection diagram		2 x J	2 x J

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

#### Main view

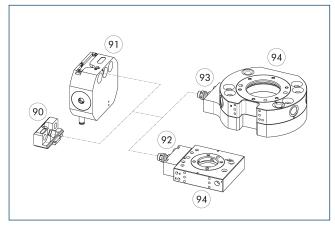


The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

- The robot-side plate mounted on the SWK is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate.
- A, a Air connection locked
- B, b Air connection unlocked
- 1 Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle
- (25) Pneumatic feed-throughs
- 32 Cover
- (95) Fit for centering pins
- 96 Fit for centering



#### Storage system SWM-B



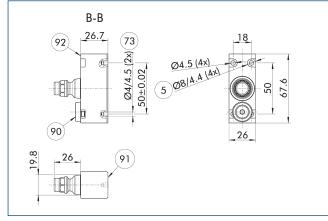
90 SWM-B 085

- 93 Intermediate plate
- (91) SWM-B 085-V(92) Side plate
- 94 Quick-change adapter SWA

Storage system with (-V) and without locking for safe tool storage. Detailed information and further accessories can be found in the catalog chapter "SWM-B" and "SWM.".

Description	ID	
Storage system		
SWM-B 085	1459339	
SWM-B 085-V	1442590	

#### Adapter plate J screw connection diagram



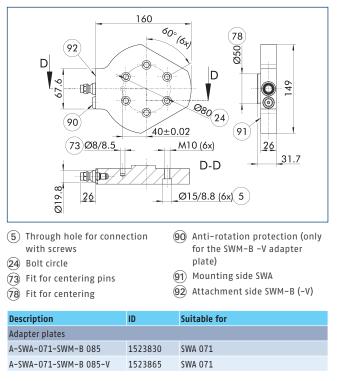
(5) Through hole for connection with screws

(73) Fit for centering pins

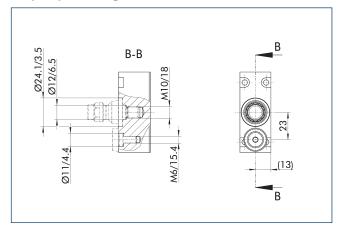
- Anti-rotation protection (only for the SWM-B -V adapter plate)
- (91) Mounting side SWA
- (92) Attachment side SWM-B (-V)

Description	ID	Suitable for
Adapter plates		
A-SWA-J16-SWM-B 085	1523836	all SWA with J screw connection diagram
A-SWA-J16-SWM-B 085-V	1523875	all SWA with J screw connection diagram

#### Adapter plate SWA 071



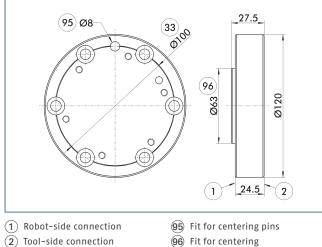
#### Adapter plate design SWM-B



Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

Description	ID	Suitable for
Adapter plates		
A-SWA-071-SWM-B 085	1523830	SWA 071
A-SWA-071-SWM-B 085-V	1523865	SWA 071
A-SWA-J16-SWM-B 085	1523836	all SWA with J screw connection diagram
A-SWA-J16-SWM-B 085-V	1523875	all SWA with J screw connection diagram

### Adapter plate ISO-A100-R

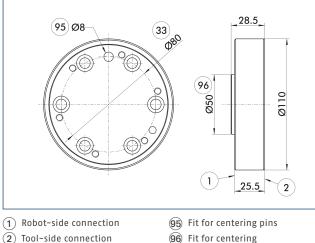


#### (33) DIN ISO-9409 bolt circle

Robot side adapter pla	te					
Description	ID					
Robot side						
A-SWK-071-IS0-A100	0321555					

① Adapter plate for quick change master without piston stroke control

#### Adapter plate ISO-A80-R



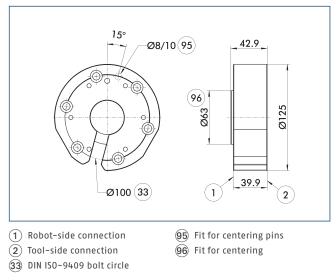
- (2) Tool-side connection
- (33) DIN ISO-9409 bolt circle

Robot side adapter plate

Description	ID
Robot side	
A-SWK-071-IS0-A80	0321554

() Adapter plate for quick change master without piston stroke control

#### Adapter plate ISO-A100-SIP-R

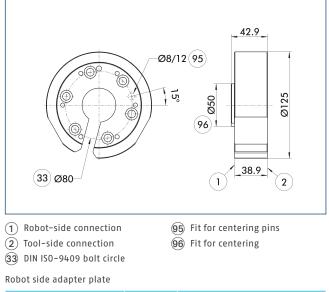


Robot side adapter plate

Description	ID	
Robot side		
A-SWK-071-IS0-A100-SIP	0302238	

① Adapter plate for quick change master with piston stroke control

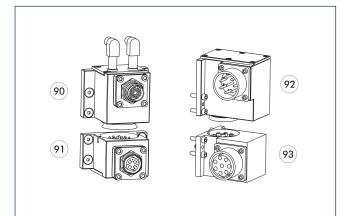
#### Adapter plate ISO-A80-SIP-R



Description	ID	
Robot side		
A-SWK-071-ISO-A80-SIP	0302239	

() Adapter plate for quick change master with piston stroke control

### Electric feed-through module



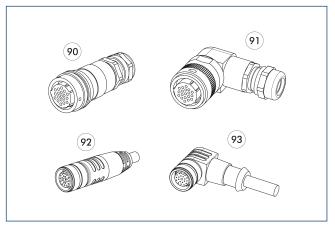
- (90) Electric module with metric thread, robot-side
- (91) Electric module with metric thread, tool-side
- (92) Electric module with MIL-Spec thread, robot-side
   (1) Specific and the second second
- (93) Electric module with MIL-Spec thread, tool-side

Modules for transmission of electrical signals.

Description	ID	No. Pins
Feed-through module	e for communi	ication on the robot side
SWO-RE5-K	9957444	
Feed-through module	e for communi	ication on the tool side
SWO-RE5-A	9957445	
Feed-through module	e for power or	n the robot side
SWO-MT8-K	9937157	
Feed-through module	e for power or	n the tool side
SW0-MT8-A	9937158	
Feed-through module	e for signal on	the robot side
SW0-G19-K	9940649	19
SWO-R19-K	9935815	19
SWO-R19W-K	9942041	15
SWO-R26-K	9935819	26
SWO-RF19-K	9948654	19
Feed-through module	e for signal on	the tool side
SWO-G19-A	9940650	19
SWO-R19-A	9935816	19
SWO-R26-A	9935820	26
SWO-RF19-A	9948657	19

For more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.

# Cable plug/cable extension



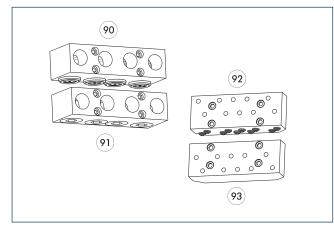
- 90 Plug/socket straight91 Connector/angled socket
- (92) Connector/straight socket with extension cable
- (93) Connector/angled socket with extension cable

Other cable lengths on request.

Description	ID	Length			
		[m]			
Angled cable connect	or, robot-side				
KAS-19B-K-90-C	0301294				
KAS-19F-K-90	1316879				
KAS-26B-K-90-C	0301296				
Angled cable connect	or, tool-side				
KAS-19B-A-90-C	0301295				
KAS-19F-A-90	1316873				
KAS-26B-A-90-C	0301297				
Angled cable connect	or with cable,	robot-side			
KV-5-SWK-19B-90	0302190	5			
KV-5-SWK-19F-90	0302172	5			
Angled cable connect	or with cable,	tool-side			
KV-3-SWA-19B-90	0302191	3			
KV-3-SWA-19F-90	0302175	3			
Straight cable connec	tor, robot-sid	e			
KAS-08G-K-0	0301268				
KAS-19B-K-O-C	0301283				
KAS-19F-K-0	1351134				
KAS-26B-K-0-C	0301290				
Straight cable connec	tor, tool-side				
KAS-08G-A-0	0301269				
KAS-19B-A-0-C	0301284				
KAS-19F-A-0	1351135				
KAS-26B-A-0-C	0301291				
Straight cable connector with cable, robot-side					
KV-5-SWK-19B-0	0302177	5			
KV-5-SWK-19F-0	0302170	5			
Straight cable connec	Straight cable connector with cable, tool-side				
KV-3-SWA-19B-0	0302178	3			
KV-3-SWA-19F-0	0302174	3			

Detailed information and further cable connectors can be found at schunk.com

# Pneumatic/ fludic feed-through modules



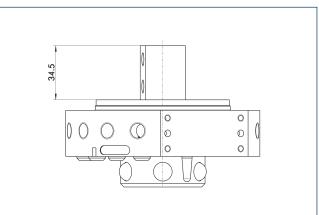
- 90 Self-sealing fluid module, robot-side
- (92) Pneumatic module, robot-side
- 93 Pneumatic module, tool-side
- (91) Self-sealing fluid module, tool-side

Modules for transferring fluids (air, vacuum or fluid).

Description	ID	No. of fluid feed-throughs			
Feed-through modul	Feed-through module for liquids on the robot side				
SWO-FG2-K	9936817	2			
Feed-through modul	Feed-through module for liquids on the tool side				
SWO-FG2-A	9936818	2			
Feed-through module for pneumatics on the robot side					
SWO-P8M5-K	9872067	8			
Feed-through module for pneumatics on the tool side					
SWO-P8M5-A	9872068	8			

 $\ensuremath{\textcircled{}}$  For other pneumatic and fluid modules, see catalog chapter "Options" or visit our website.

#### **Piston stroke control**



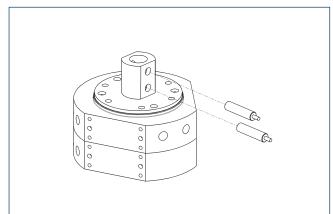
The drawing shows the minimal height of the adapter plate for installing a piston stroke control.

Description	ID
Piston stroke co	ontrol
SWK-071-SIP	0302375



Quick change system

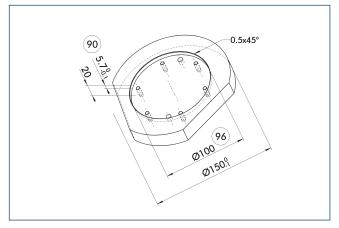
# Piston stroke control



Description	ID	Often combined
Inductive proximity switch		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	
INK 80-S	0301550	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
Clip for connector/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M12	0301776	•
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

# Adapter plate design



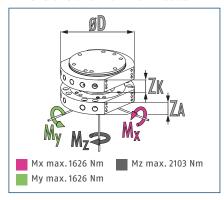
(90) Recommended adapter plate (96) Fit for centering depth

Recommendation for the design of the adapter plate.









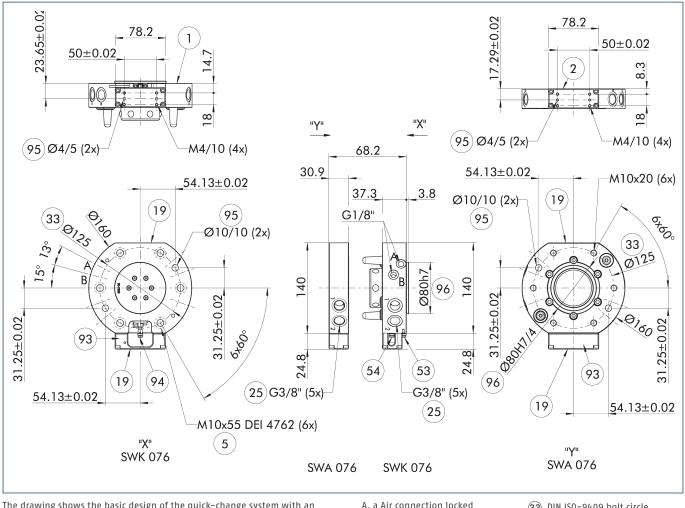
This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

Description		SWK-076-000-000-SG	SWA-076-000-000
		Quick-change master	Quick-change adapter
ID		0302392	0302391
Recommended handling weight	[kg]	100	100
Piston stroke monitoring		integrated	
Locking force	[N]	12000	12000
Repeat accuracy	[mm]	0.015	0.015
Weight	[kg]	2.25	1.43
Max. distance when locking	[mm]	2	2
Air connection thread pneumatic feed-through		5x G3/8"	5x G3/8"
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±1	±1
Max. permissible angular offset	[°]	±1	±1
Robot-side connection		ISO 9409-1-125-6-M10	ISO 9409-1-125-6-M10
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	160 x 37.3	160 x 30.9
Screw connection diagram		2 x J	2 x J

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

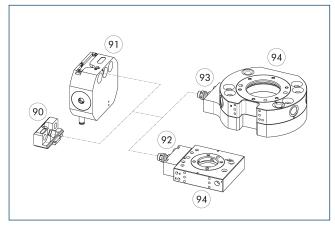
#### Main view



The drawing shows the basic design of the quick-change system with an integrated electric feed-through without dimensional consideration of the options described below.

- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- 2 Tool-side connection
- Through hole for connection (5) with screws
- (19) Mounting surface for options
- (25) Pneumatic feed-throughs
- (33) DIN ISO-9409 bolt circle
- (53) Monitoring Position unlocked
- (54) Monitoring Position locked
- (93) Optional distance adapter included in the scope of
- delivery
  - (94) Optional proximity switch
  - (95) Fit for centering pins
  - (96) Fit for centering

#### Storage system SWM-B



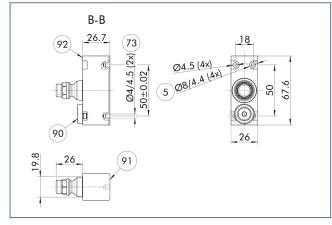
90 SWM-B 085

- 93 Intermediate plate
- (91) SWM-B 085-V
- (92) Side plate
- 94 Quick-change adapter SWA

Storage system with (-V) and without locking for safe tool storage. Detailed information and further accessories can be found in the catalog chapter "SWM-B" and "SWM.".

Description	ID	
Storage system		
SWM-B 085	1459339	
SWM-B 085-V	1442590	

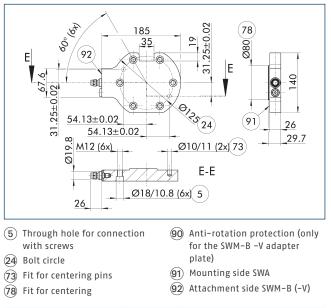
#### Adapter plate J screw connection diagram



- (5) Through hole for connection with screws
- **73** Fit for centering pins
- Anti-rotation protection (only for the SWM-B -V adapter plate)
- (91) Mounting side SWA
- (92) Attachment side SWM-B (-V)

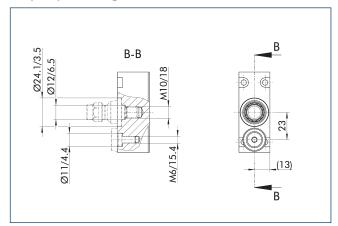
Description	ID	Suitable for
Adapter plates		
A-SWA-J16-SWM-B 085	1523836	all SWA with J screw connection diagram
A-SWA-J16-SWM-B 085-V	1523875	all SWA with J screw connection diagram

#### Adapter plate SWA 076



Description	ID	Suitable for
Adapter plates		
A-SWA-076-SWM-B 085	1523831	SWA 076
A-SWA-076-SWM-B 085-V	1523869	SWA 076

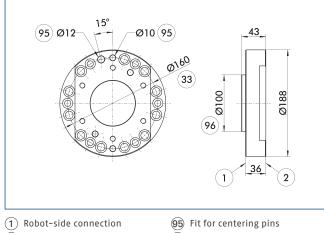
#### Adapter plate design SWM-B



Instead of using a standard adapter plate, the storage pin and anti-twist protection can also be attached to a customized adapter plate. For error-free function, all dimensions according to the drawing must be taken into account, in particular the distances between the anti-twist protections to the storage pin. The drawing is also valid for all the standard plates listed below.

Description	ID	Suitable for
Adapter plates		
A-SWA-076-SWM-B 085	1523831	SWA 076
A-SWA-076-SWM-B 085-V	1523869	SWA 076
A-SWA-J16-SWM-B 085	1523836	all SWA with J screw connection diagram
A-SWA-J16-SWM-B 085-V	1523875	all SWA with J screw connection diagram

### Adapter plate ISO-A160-M10/M12-R

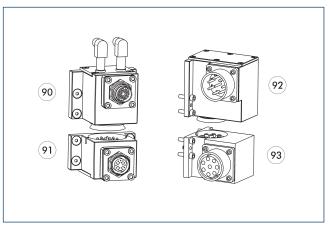


- 2 Tool-side connection
- 96 Fit for centering
- 3 DIN ISO-9409 bolt circle

# Robot side adapter plate

() Adapter plate for robots with M10 or M12 mounting patterns

### Electric feed-through module



(90) Electric module with metric thread, robot-side (91) Electric module with metric

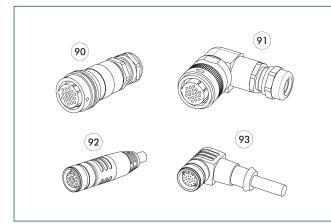
thread, tool-side

- (92) Electric module with MIL-Spec thread, robot-side (93) Electric module with MIL-Spec thread, tool-side
- Modules for transmission of electrical signals.

Description	ID	No. Pins
Feed-through module	e for communi	ication on the robot side
SWO-RE5-K	9957444	
SWO-TP-K	9871166	
Feed-through module	e for communi	ication on the tool side
SWO-RE5-A	9957445	
SWO-TP-A	9871165	
Feed-through module	e for power on	the robot side
SWO-MT8-K	9937157	
Feed-through module	e for power on	the tool side
SW0-MT8-A	9937158	
Feed-through module	e for signal on	the robot side
SWO-R19-K	9935815	19
SWO-R19R-K	9942391	15
SWO-R26-K	9935819	26
SWO-RF19-K	9948654	19
Feed-through module	e for signal on	the tool side
SWO-R19-A	9935816	19
SWO-R26-A	9935820	26
SWO-RF19-A	9948657	19

① For more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.

# Cable plug/cable extension



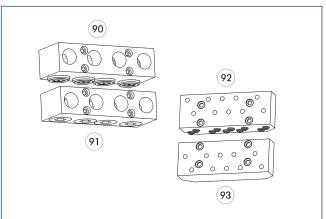
- 90 Plug/socket straight
- (91) Connector/angled socket
- (2) Connector/straight socket with extension cable
   (93) Connector/angled socket with
- extension cable

#### Other cable lengths on request.

Description	ID	Length
		[m]
Angled cable connect	or, robot-side	
KAS-19B-K-90-C	0301294	
KAS-19F-K-90	1316879	
KAS-26B-K-90-C	0301296	
Angled cable connect	or, tool-side	
KAS-19B-A-90-C	0301295	
KAS-19F-A-90	1316873	
KAS-26B-A-90-C	0301297	
Angled cable connect	or with cable,	robot-side
KV-5-SWK-19F-90	0302172	5
Angled cable connect	or with cable,	tool-side
KV-3-SWA-19B-90	0302191	3
KV-3-SWA-19F-90	0302175	3
Straight cable connec	tor, robot-sid	e
KAS-08G-K-0	0301268	
KAS-19B-K-O-C	0301283	
KAS-19F-K-0	1351134	
KAS-26B-K-0-C	0301290	
Straight cable connec	tor, tool-side	
KAS-08G-A-0	0301269	
KAS-19B-A-O-C	0301284	
KAS-19F-A-0	1351135	
KAS-26B-A-O-C	0301291	
Straight cable connec	tor with cable	e, robot-side
KV-5-SWK-19F-0	0302170	5
Straight cable connec	tor with cable	e, tool-side
KV-3-SWA-19B-0	0302178	3
KV-3-SWA-19F-0	0302174	3

 $\ensuremath{\textcircled{}}$  Detailed information and further cable connectors can be found at schunk.com

# Pneumatic/ fludic feed-through modules



Self-sealing fluid module, robot-side (92) Pneumatic module, robot-side(93) Pneumatic module, tool-side

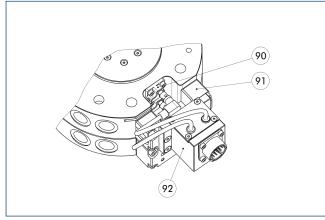
(91) Self-sealing fluid module, tool-side

Modules for transferring fluids (air, vacuum or fluid).

Description	ID	No. of fluid feed-throughs
Feed-through module	e for liquids o	n the robot side
SWO-FG4-K	9937333	4
Feed-through module	e for liquids o	n the tool side
SWO-FG4-A	9937334	4
Feed-through module	e for pneumat	ics on the robot side
SW0-P186-K	9939024	6
Feed-through module	e for pneumat	ics on the tool side
SW0-P186-A	9939025	6
Feed-through module SWO-P186-K Feed-through module	e for pneumat 9939024 e for pneumat	ics on the robot side 6 ics on the tool side

 For other pneumatic and fluid modules, see catalog chapter "Options" or visit our website.

### Assembly situation of the locking monitoring



90 AS-SWK 07691 Spacer

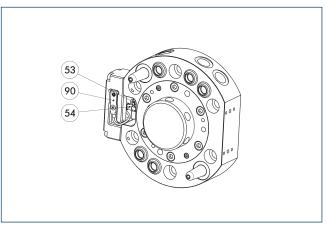
(92) Optional electrical module ...R-master with integrated sensor connection

When using the integrated piston stroke monitoring, a spacer is required between the electric optional module and the SWK. The spacer is included in the scope of delivery of the SWK (and the SWA). If the piston stroke monitoring is not used, the spacer is not required.

Description	ID	
Attachment kit for proximity switch		
AS-SWK-40Q/076 attachment kit including sensor	9955216	

The -SG/-SM/-SQ/-IN variants of the SWK include the piston stroke monitoring option. An additional order of the mounting kit is not necessary. The scope of delivery of a mounting kit contains one preset sensor with holder each, meaning that two mounting kits are required per SWK.

#### Installation situation presence monitoring



(53) Monitoring Position unlocked(54) Monitoring Position locked

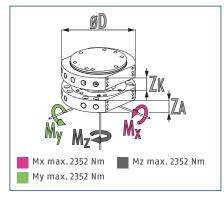
90 Sensor for presence control

Description	ID
Inductive proximity s	witch
INK 8-SL	0302456

① For each SWK, a proximity switch is required for presence monitoring.



#### Dimensions and maximum loads



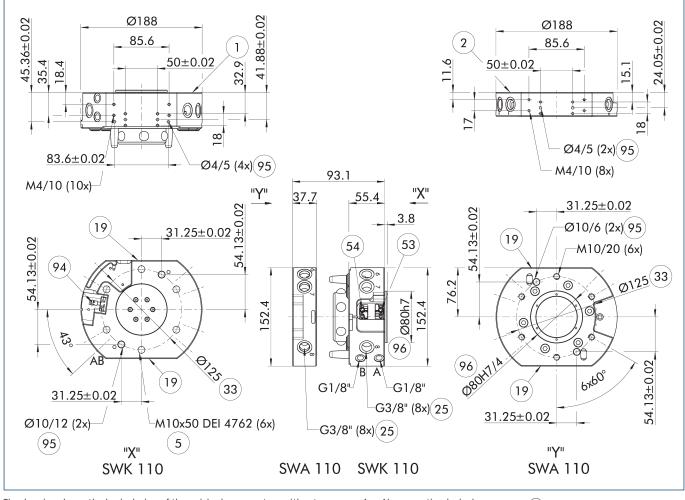
This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# **Technical data**

Description		SWK-110-000-000-SM	SWA-110-000-000
		Quick-change master	Quick-change adapter
ID		0302412	0302411
Recommended handling weight	[kg]	150	150
Piston stroke monitoring		integrated	
Locking force	[N]	12000	12000
Repeat accuracy	[mm]	0.015	0.015
Weight	[kg]	4	2.2
Max. distance when locking	[mm]	3	3
Air connection thread pneumatic feed-through		8x G3/8"	8x G3/8"
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset	[°]	±1	±1
Robot-side connection		IS0 9409-1-125-6-M10	ISO 9409-1-125-6-M10
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	188 x 55.5	188 x 37.6
Screw connection diagram		2 x J	2 x J

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

#### Main view

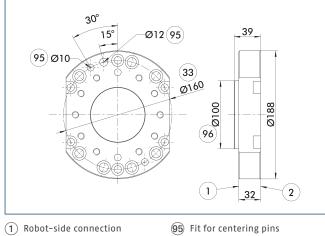


The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- (25) Pneumatic feed-throughs
- 3 DIN ISO-9409 bolt circle
- 53 Monitoring Position unlocked
- 54 Monitoring Position locked
- (94) Optional proximity switch
- (95) Fit for centering pins
- 96 Fit for centering

97

# Adapter plate ISO-A160-M10/M12-R



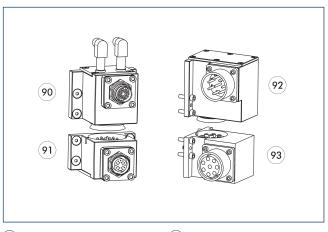
- 2 Tool-side connection
- 96 Fit for centering
- 3 DIN ISO-9409 bolt circle

#### Robot side adapter plate

Description ID	
Robot side	
A-SWK-110/210-ISO-A160-M10/M12 0302225	

() Adapter plate for robots with M10 or M12 mounting patterns

#### Electric feed-through module



(90) Electric module with metric thread, robot-side (91) Electric module with metric

thread, tool-side

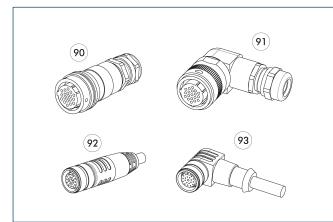
(92) Electric module with MIL-Spec thread, robot-side (93) Electric module with MIL-Spec thread, tool-side

Modules for transmission of electrical signals.

Description	ID	No. Pins		
Feed-through module for communication on the robot side				
SWO-RE5-K	9957444			
SWO-TP-K	9871166			
Feed-through module	e for communi	ication on the tool side		
SWO-RE5-A	9957445			
SWO-TP-A	9871165			
Feed-through module	e for power on	the robot side		
SWO-MT8-K	9937157			
Feed-through module	e for power on	the tool side		
SWO-MT8-A	9937158			
Feed-through module for signal on the robot side				
SWO-R19-K	9935815	19		
SWO-R19R-K	9942391	15		
SWO-R26-K	9935819	26		
SWO-RF19-K	9948654	19		
Feed-through module for signal on the tool side				
SWO-R19-A	9935816	19		
SWO-R26-A	9935820	26		
SWO-RF19-A	9948657	19		

① For more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.

# Cable plug/cable extension



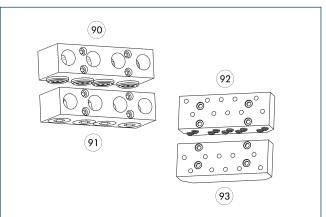
- 90 Plug/socket straight
- (91) Connector/angled socket
- (2) Connector/straight socket with extension cable
   (93) Connector/angled socket with
- extension cable

#### Other cable lengths on request.

Description	ID	Length		
		[m]		
Angled cable connector, robot-side				
KAS-19B-K-90-C	0301294			
KAS-19F-K-90	1316879			
KAS-26B-K-90-C	0301296			
Angled cable connect	or, tool-side			
KAS-19B-A-90-C	0301295			
KAS-19F-A-90	1316873			
KAS-26B-A-90-C	0301297			
Angled cable connect	or with cable,	robot-side		
KV-5-SWK-19B-90	0302190	5		
KV-5-SWK-19F-90	0302172	5		
Angled cable connect	or with cable,	tool-side		
KV-3-SWA-19B-90	0302191	3		
KV-3-SWA-19F-90	0302175	3		
Straight cable connec	tor, robot-sid	e		
KAS-08G-K-0	0301268			
KAS-19B-K-O-C	0301283			
KAS-19F-K-0	1351134			
KAS-26B-K-0-C	0301290			
Straight cable connec	tor, tool-side			
KAS-08G-A-0	0301269			
KAS-19B-A-0-C	0301284			
KAS-19F-A-0	1351135			
KAS-26B-A-0-C	0301291			
Straight cable connector with cable, robot-side				
KV-5-SWK-19B-0	0302177	5		
KV-5-SWK-19F-0	0302170	5		
Straight cable connec	tor with cable	, tool-side		
KV-3-SWA-19B-0	0302178	3		
KV-3-SWA-19F-0	0302174	3		

 $\ensuremath{\textcircled{}}$  Detailed information and further cable connectors can be found at schunk.com

# Pneumatic/ fludic feed-through modules



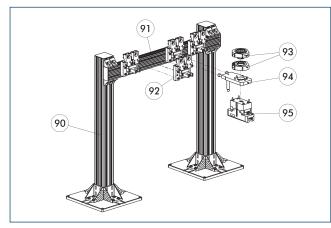
- Self-sealing fluid module, robot-side
- (92) Pneumatic module, robot-side(93) Pneumatic module, tool-side
- Self-sealing fluid module, tool-side

Modules for transferring fluids (air, vacuum or fluid).

ID	No. of fluid feed-throughs			
Feed-through module for liquids on the robot side				
9937333	4			
Feed-through module for liquids on the tool side				
9937334	4			
Feed-through module for pneumatics on the robot side				
9939024	6			
Feed-through module for pneumatics on the tool side				
9939025	6			
	e for liquids o 9937333 e for liquids o 9937334 e for pneumat 9939024 e for pneumat			

Tor other pneumatic and fluid modules, see catalog chapter "Options" or visit our website.

#### SWM-M modular storage rack



- (90) Base plate with upright profile
- (91) Horizontal profile (94) In

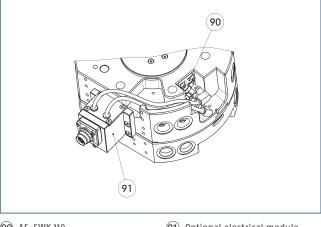
(92) Storage module

(93) Quick-change system SWS
(94) Intermediate plate
(95) Parallel gripper

The modular storage rack is designed for the specific size. The system's modular design allows you to compile your individual storage rack. This provides you with a storage rack that meets your individual requirements, taking into account the number of tools, deposition positions, and tool size. For further information please refer to the chapter "SWM storage rack"

Description	ID
Storage module	
SWM-TSM-MM-4018	0303214
Cross profile	
SWM-TSM-HM-3317	0303228
SWM-TSM-HM 3323	0303229
Sensor	
IN-B180-S-M12	0303244
Sensor bracket	
SWM-TSM-SM-4205	0303245
Vertical profile	
SWM-TSM-PM-3318	0303226
SWM-TSM-PM-3322	0303227
Intermediate plate	
SWM-TSM-TP-4059	0303220

### Assembly situation of the locking monitoring



90 AS-SWK 110

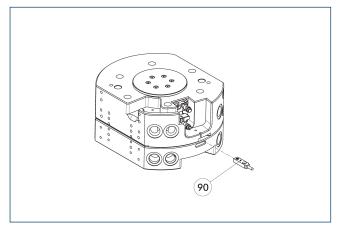
Optional electrical module ...R-master with integrated sensor connection

The drawing shows the quick-change system with integrated piston stroke monitoring and built-in proximity switch; this is directly connected to the electric modules.

Description	ID	
Attachment kit for proximity switch		
AS-SWK-110/160 attachment kit including sensor	9957835	

The -SG/-SM/-SQ/-IN variants of the SWK include the piston stroke monitoring option. An additional order of the mounting kit is not necessary. The scope of delivery of a mounting kit contains one preset sensor with holder each, meaning that two mounting kits are required per SWK.

# Installation situation presence monitoring



(90) Sensor for presence control

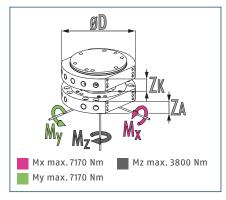
Description	ID	
Inductive proximity switch		
INK 8-SL	0302456	

 $\ensuremath{\textcircled{}}$  For each SWK, a proximity switch is required for presence monitoring.

101



#### Dimensions and maximum loads



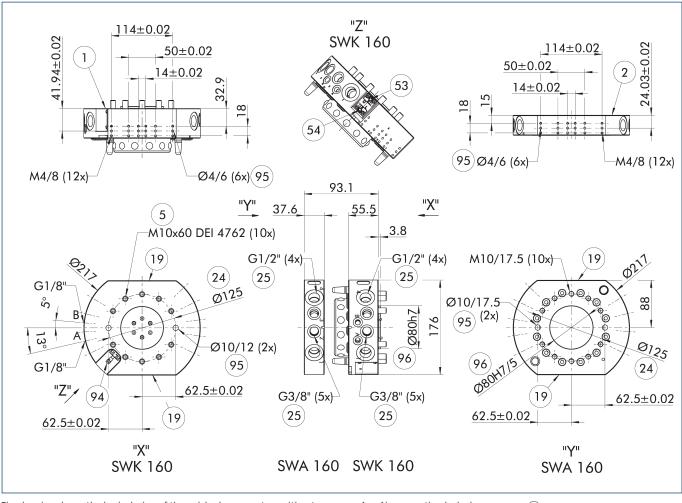
This is the max. sum of all forces and moments which are permitted to act on the change system for ensuring proper functioning.

# Technical data

Description		SWK-160-000-000-SM	SWA-160-000-000
		Quick-change master	Quick-change adapter
ID		0302440	0302441
Recommended handling weight	[kg]	300	300
Piston stroke monitoring		integrated	
Locking force	[N]	31000	31000
Repeat accuracy	[mm]	0.015	0.015
Weight	[kg]	6.44	2.86
Max. distance when locking	[mm]	2	2
Air connection thread pneumatic feed-through		5x G3/8"	5x G3/8"
Air connection thread pneumatic feed-through		4x G1/2"	4x G1/2"
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset	[°]	±1	±1
Robot-side connection		ISO 9409-1-125-10-M10	ISO 9409-1-125-10-M10
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/6.9	4.5/6.9
Dimensions Ø D x Z*	[mm]	217 x 55.5	217 x 37.6
Screw connection diagram		2 x J	2 x J

\* Please note that the heights of the change master (ZK) and change adapter (ZA) differ. The sum represents the total height of a coupled change system.

#### Main view



The drawing shows the basic design of the quick-change system without dimensional consideration of the options described below.

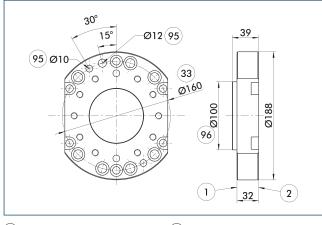
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options

24) Bolt circle

- 25 Pneumatic feed-throughs
- 53 Monitoring Position unlocked
- (54) Monitoring Position locked
- (94) Optional proximity switch
- (95) Fit for centering pins

96 Fit for centering

### Adapter plate ISO-A160-R

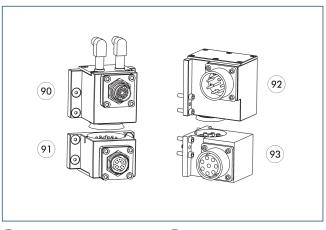


- 1 Robot-side connection
- (95) Fit for centering pins
- (2) Tool-side connection(33) DIN ISO-9409 bolt circle
- 96 Fit for centering

### Robot side adapter plate

Description	ID
Robot side	
A-SWK-160-IS0-A160	0302248

### Electric feed-through module



(90) Electric module with metric thread, robot-side
 (91) Electric module with metric

thread, tool-side

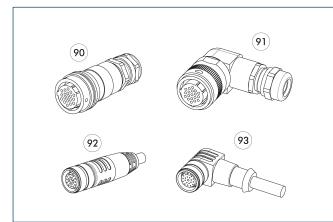
(92) Electric module with MIL-Spec thread, robot-side
(93) Electric module with MIL-Spec thread, tool-side

Modules for transmission of electrical signals.

Description	ID	No. Pins		
Feed-through module for communication on the robot side				
SWO-RE5-K	9957444			
SWO-TP-K	9871166			
Feed-through module	e for communi	cation on the tool side		
SWO-RE5-A	9957445			
SWO-TP-A	9871165			
Feed-through module	e for power on	the robot side		
SWO-MT8-K	9937157			
Feed-through module	e for power on	the tool side		
SWO-MT8-A	9937158			
Feed-through module	e for signal on	the robot side		
SWO-R19-K	9935815	19		
SWO-R19W-K	9942041	15		
SWO-R26-K	9935819	26		
SWO-RF19-K	9948654	19		
Feed-through module for signal on the tool side				
SWO-R19-A	9935816	19		
SWO-R26-A	9935820	26		
SWO-RF19-A	9948657	19		

For more detailed information and further modules and matching cable connectors, see catalog chapter "SWO" or visit our website.

# Cable plug/cable extension



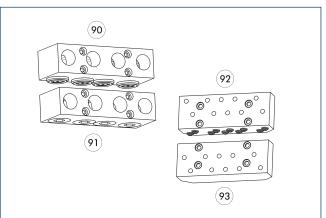
- 90 Plug/socket straight
- (91) Connector/angled socket
- (92) Connector/straight socket with extension cable
- (93) Connector/angled socket with extension cable

#### Other cable lengths on request.

Description	ID	Length		
		[m]		
Angled cable connector, robot-side				
KAS-19B-K-90-C	0301294			
KAS-19F-K-90	1316879			
KAS-26B-K-90-C	0301296			
Angled cable connect	or, tool-side			
KAS-19B-A-90-C	0301295			
KAS-19F-A-90	1316873			
KAS-26B-A-90-C	0301297			
Angled cable connect	or with cable,	robot-side		
KV-5-SWK-19B-90	0302190	5		
KV-5-SWK-19F-90	0302172	5		
Angled cable connect	or with cable,	tool-side		
KV-3-SWA-19B-90	0302191	3		
KV-3-SWA-19F-90	0302175	3		
Straight cable connec	tor, robot-sid	e		
KAS-08G-K-0	0301268			
KAS-19B-K-O-C	0301283			
KAS-19F-K-0	1351134			
KAS-26B-K-0-C	0301290			
Straight cable connec	tor, tool-side			
KAS-08G-A-0	0301269			
KAS-19B-A-0-C	0301284			
KAS-19F-A-0	1351135			
KAS-26B-A-0-C	0301291			
Straight cable connector with cable, robot-side				
KV-5-SWK-19B-0	0302177	5		
KV-5-SWK-19F-0		5		
Straight cable connec	tor with cable	e, tool-side		
KV-3-SWA-19B-0	0302178	3		
KV-3-SWA-19F-0	0302174	3		

 $\ensuremath{\textcircled{}}$  Detailed information and further cable connectors can be found at schunk.com

# Pneumatic/ fludic feed-through modules



- Self-sealing fluid module, robot-side
- (92) Pneumatic module, robot-side(93) Pneumatic module, tool-side
- Self-sealing fluid module, tool-side

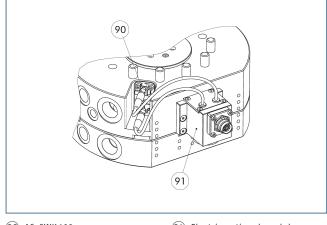
Modules for transferring fluids (air, vacuum or fluid).

ID	No. of fluid feed-throughs			
Feed-through module for liquids on the robot side				
9937333	4			
Feed-through module for liquids on the tool side				
9937334	4			
Feed-through module for pneumatics on the robot side				
9939024	6			
Feed-through module for pneumatics on the tool side				
9939025	6			
	e for liquids of 9937333 e for liquids of 9937334 e for pneumat 9939024 e for pneumat			

Tor other pneumatic and fluid modules, see catalog chapter "Options" or visit our website.



# Assembly situation of the locking monitoring



90 AS-SWK 160

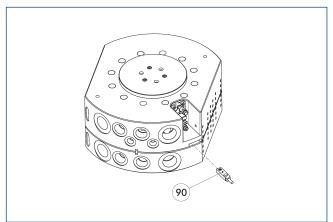
(91) Electric optional module ...W-master with integrated sensor connection

The drawing shows the quick-change system with integrated piston stroke monitoring and built-in proximity switch; this is directly connected to the electric modules.

Description	ID	
Attachment kit for proximity switch		
AS-SWK-110/160 attachment kit including sensor	9957835	

The -SG/-SM/-SQ/-IN variants of the SWK include the piston stroke monitoring option. An additional order of the mounting kit is not necessary. The scope of delivery of a mounting kit contains one preset sensor with holder each, meaning that two mounting kits are required per SWK.

#### Installation situation presence monitoring



(90) Sensor for presence control

Description	ID
Inductive proxin	nity switch
INK 8-SL	0302456

① For each SWK, a proximity switch is required for presence monitoring.





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